





IFT

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DISSERTAÇÃO DE MESTRADO

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OK

Sobre Métodos de Solução de Modelos de Toda não Abelianos

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Resumo

Nesta dissertação reconstruímos um modelo de Toda não abeliano baseado na álgebra afim $B_2(SO(5))$ a partir de sua representação de curvatura nula (ou das equações de Leznov-Saveliev) de forma a obtermos soluções. Desenvolvemos dois métodos sistemáticos: transformações de "gauge" fornecendo equações de primeira ordem (transformações de Backlund) e "dressing".

Palavras Chaves: Solitons, modelos integráveis, modelos de Toda não abelianos, álgebras afins.

Áreas do conhecimento: Física das partículas elementares e Campos; métodos matemáticos em Física; fenômenos não lineares.

Abstract

A non abelian Toda model based on the affine $B_2(SO(5))$ álgebra is reconstructed in terms of its zero curvature representation (or its Leznov-Saveliev equations). Its solutions are obtained from two sistematic methods, namely, gauge transformations leading to first order differential equations (Backlund transformations) and "dressing".

1 Capítulo 1

1.1 Introdução

Modelos integráveis a duas dimensões fornecem um laboratório para testar novos métodos de construção de soluções exatas.

Recentemente alguns modelos, fornecendo uma generalização do modelo de Sine-Gordon complexo foram construídos [1] [2] com soluções solitônicas obtidas pelo método de "dressing" [3]

Estes modelos baseiam-se em grupos "simply laced" do tipo $SL(r+1)$.

Em analogia a êsses foram construídos modelos associados a álgebras "não simply laced" baseados por exemplo em grupos do tipo B_n Ref. [4]

A finalidade da Tese presente é a de discutir mais explicitamente o caso de B_2 cujo modelo já foi construído em J.F. Gomes et.al. [4]

Reconstruímos êste modelo utilizando B_2 à partir da álgebra A_3 equipada com um automorfismo que descreve uma simetria do diagrama de Dynkin. Esta simetria permite a construção dos geradores de B_2 em termos dos geradores de A_3 .

As soluções do modelo são estudadas primeiramente em termos de transformações de "gauge" (Sotkov) relacionando duas soluções distintas (transformações de Backlund). Este método caracteriza-se por reduzir equações diferenciais não lineares de segunda ordem a equações diferenciais de primeira ordem.

Utilizando êste formalismo obtivemos uma solução particular do problema.

Um segundo formalismo também baseado em transformações de "gauge" foi estudado. Este método denominado "dressing" envolve a teoria da representação das álgebras de Kac-Moody, e fornece a solução explícita em termos de elementos de matriz (funções tau) de certos operadores (funções de vértice) que caracterizam o modelo. A dependência espaço-temporal das funções tau é escrita em termos de uma série finita de exponenciais cuja ordem depende da álgebra em questão.

Os modelos baseados em $SL(r+1)$ e descritos por J.F. Gomes et.al. tem por característica um truncamento da expansão das funções de vértice em primeira ordem. No caso de B_2 o truncamento ocorre em ordem superior (o que é verificado no caso mais simples em que se considera soluções de um vértice em cujo caso o truncamento ocorre em segunda ordem). Por exemplo no caso de soluções de duas funções de vértice, o truncamento pode ocorrer em ordem superior como discutiremos nas conclusões.

Esta dissertação está organizada da seguinte maneira.

Primeiramente introduzimos as transformações de Backlund para o modelo de Sine Gordon. Como ilustração elas são discutidas no formalismo das transformações canônicas bem como no formalismo algébrico. Em seguida a álgebra de Lie A_3 ($=SL(4)$) e suas simetrias são discutidas. Em particular, define-se a álgebra B_2 em termos dos geradores de A_3 . A construção do modelo integrável em questão é discutida e as equações de movimento são derivadas, através da condição de curvatura nula e das equações de Leznov-Saveliev.

A construção de uma transformação de Backlund é então abordada e uma solução particular é obtida. Em seguida apresenta-se o método de "dressing", após a construção dos operadores de vértice e soluções particulares são discutidas.

Nos apêndices A,B,C,D,E e F são dados detalhes e verificação de certas passagens matemáticas discutidas no texto principal.

Nas conclusões apresentamos uma maneira alternativa de se resolver as equações para as funções tau. Desse modo conseguimos certas soluções interessantes para as equações (3.69) e mencionamos os problemas em aberto.

3.69

$$\tau'' + \frac{1}{\tau} \tau'^2 + \frac{1}{\tau} \tau'' = 0 \quad (3.69)$$

3.70

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3.71

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3.73

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3.74

$$\tau'' + \frac{1}{\tau} \tau'^2 + \frac{1}{\tau} \tau'' = 0 \quad (3.74)$$

3.75

2 Capítulo 2

2.1 Equação de SINE-GORDON. Transformações de Backlund

A equação de Sine -Gordon é definida pela densidade Langrangeana :

$$\mathcal{L} = \frac{1}{2}\phi_t^2 - \frac{1}{2}\phi_x^2 + (\cos \phi - 1) \quad (2.1)$$

A equação de Euler-Langrange dá como equação de movimento

$$\phi_{tt} - \phi_{xx} - \sin \phi = 0 \quad (2.2)$$

que é a equação de Sine-Gordon.

O momento canonicamente conjugado é

$$\pi = \frac{\delta \mathcal{L}}{\delta \phi_t} = \phi_t \quad (2.3)$$

O tensor de energia momento é dado por

$$t^{uv} = \partial^u \phi \left(\frac{\partial \mathcal{L}}{\partial (\partial_v \phi)} \right) - g^{uv} \mathcal{L} \quad (2.4)$$

fornecendo como densidade Hamiltoniana

$$h = t^{00} = \partial^t \phi \left(\frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} \right) - g^{tt} \mathcal{L} = \partial^t \phi \partial_t \phi - g^{tt} \mathcal{L}$$

óu:

$$h = \frac{1}{2}\pi^2 + \frac{1}{2}\phi_x^2 + (1 - \cos \phi) \quad (2.5)$$

Já para a densidade de momento temos

$$p = t^{01} = \pi \phi_x \quad (2.6)$$

Queremos relacionar duas soluções distintas ϕ e ϕ' da equação de Sine Gordon (2.2). As hamiltonianas totais e momentos totais devem ter a mesma forma para ambas as soluções ϕ

e ϕ' e portanto as suas densidades de hamiltoniana e de momento devem diferir por derivadas totais em relação á coordenada x .

Kodama e Wadati [5] propuseram que as duas soluções ϕ e ϕ' , de (2.2) fossem obtidas uma da outra por uma transformação canônica.

Introduziram a seguinte função geratriz

$$W[\phi, \phi'] = \int_{-\infty}^{+\infty} \left\{ \phi \phi'_x - 2a \cos \frac{1}{2} (\phi + \phi') + \frac{2}{a} \cos \frac{1}{2} (\phi - \phi') \right\} dx \quad (2.7)$$

onde a é uma constante arbitrária. Neste caso temos para o momento canonicamente conjugado a ϕ [6]

$$\pi(x, t) = \frac{\delta W}{\delta \phi} = \phi'_x + a \sin \frac{1}{2} (\phi + \phi') - \frac{1}{a} \sin \frac{1}{2} (\phi - \phi') \quad (2.8a)$$

Analogamente:

$$\pi'(x, t) = -\frac{\delta W}{\delta \phi'} = \phi_x - a \sin \frac{1}{2} (\phi + \phi') - \frac{1}{a} \sin \frac{1}{2} (\phi - \phi') \quad (2.8b)$$

Os momentos totais do nosso sistema são dados respectivamente por

$$P = \int_{-\infty}^{+\infty} \pi \phi_x dx$$

$$P = \int_{-\infty}^{+\infty} \left\{ \phi'_x \phi_x + a \phi_x \sin \frac{1}{2} (\phi + \phi') - \frac{1}{a} \phi_x \sin \frac{1}{2} (\phi - \phi') \right\} dx \quad (2.9a)$$

$$P' = \int_{-\infty}^{+\infty} \pi' \phi'_x dx$$

$$P' = \int_{-\infty}^{+\infty} \left\{ \phi_x \phi'_x - \phi'_x a \sin \frac{1}{2} (\phi + \phi') - \frac{1}{a} \phi'_x \sin \frac{1}{2} (\phi - \phi') \right\} dx \quad (2.9b)$$

A sua diferença dá

$$P' - P = \int_{-\infty}^{+\infty} (\pi' \phi'_x - \pi \phi_x) dx$$

$$P' - P = \int_{-\infty}^{+\infty} -(\phi_x + \phi'_x) a \sin \frac{1}{2} (\phi + \phi') + \frac{1}{a} (\phi_x - \phi'_x) \sin \frac{1}{2} (\phi - \phi') dx$$

ou

$$P' - P = \int_{-\infty}^{+\infty} \frac{d}{dx} \left(a \cos \frac{1}{2} (\phi + \phi') - \frac{1}{a} \cos \frac{1}{2} (\phi - \phi') \right) dx \quad (2.10)$$

Um cálculo análogo para as Hamiltonianas dá

$$H' - H = \frac{1}{2} \int_{-\infty}^{+\infty} [\pi'^2 + \phi_x'^2 + 2(1 - \cos \phi')] dx - \frac{1}{2} \int_{-\infty}^{+\infty} [\pi^2 + \phi_x^2 + 2(1 - \cos \phi)] dx$$

o resultado sendo

$$2H' - 2H = \int_{-\infty}^{+\infty} \left[-2a(\phi_x + \phi_x') \sin \frac{1}{2}(\phi + \phi') - \frac{2}{a}(\phi_x - \phi_x') \sin \frac{1}{2}(\phi - \phi') \right. \\ \left. + 4 \sin \frac{1}{2}(\phi + \phi') \sin \frac{1}{2}(\phi - \phi') - 2(\cos \phi' - \cos \phi) \right] dx$$

Usando o fato $\cos \phi' - \cos \phi = -2 \sin \frac{1}{2}(\phi + \phi') \sin \frac{1}{2}(\phi' - \phi)$ segue-se:

$$H' - H = \int_{-\infty}^{+\infty} \frac{d}{dx} \left(2a \cos \frac{(\phi + \phi')}{2} + \frac{2}{a} \cos \frac{(\phi - \phi')}{2} \right) dx \quad (2.11)$$

Utilizando (2.3) as expressões (2.8a) e (2.8b) são reescritas como

$$\phi_t = \phi_x' + a \sin \frac{1}{2}(\phi + \phi') - \frac{1}{a} \sin \frac{1}{2}(\phi - \phi') \quad (2.12a)$$

$$\phi_t' = \phi_x - a \sin \frac{1}{2}(\phi + \phi') - \frac{1}{a} \sin \frac{1}{2}(\phi - \phi') \quad (2.12b)$$

Subtraindo (2.12a) e (2.12b), obtemos

$$\phi_t - \phi_t' = \phi_x' - \phi_x + 2a \sin \frac{1}{2}(\phi + \phi')$$

ou:

$$\frac{1}{2}(\partial_t + \partial_x)(\phi - \phi') = a \sin \frac{1}{2}(\phi + \phi') \quad (2.13a)$$

Da mesma maneira, somando (2.12a) e (2.12b) segue-se

$$-\frac{1}{2}(\partial_t - \partial_x)(\phi + \phi') = \frac{1}{a} \sin \frac{1}{2}(\phi - \phi') \quad (2.13b)$$

É fácil de se verificar que aplicando o operador $(\partial_t - \partial_x)$ em (2.13a) e utilizando (2.13b) de que é satisfeita a equação de Sine-Gordon (2.2). As equações (2.13a) e (2.13b) constituem as transformações de Backlund.

Reescrevamos as equações (2.13a) e (2.13b) nas coordenadas do cone de luz:

$$z = t + x \quad \bar{z} = t - x$$

ou

$$t = \frac{z + \bar{z}}{2} \quad x = \frac{z - \bar{z}}{2} \quad (2.14a)$$

por tanto

$$\partial = \frac{1}{2}(\partial_t + \partial_x)$$

$$\bar{\partial} = \frac{1}{2}(\partial_t - \partial_x) \quad (2.14b)$$

$$\partial(\phi - \phi') = a \sin \frac{1}{2}(\phi + \phi') \quad (2.13a')$$

$$\bar{\partial}(\phi + \phi') = -\frac{1}{a} \sin \frac{1}{2}(\phi - \phi') \quad (2.13b')$$

Evidentemente $\phi' = 0$ é uma solução da equação (2.2). Procuremos uma outra solução desta equação utilizando as transformações de Backlund (2.13a') e (2.13b'). Neste caso temos

$$2 \partial \left(\frac{1}{2} \phi \right) = a \sin \frac{1}{2} \phi \quad (2.15a)$$

$$2 \bar{\partial} \left(\frac{1}{2} \phi \right) = -\frac{1}{a} \sin \frac{1}{2} \phi \quad (2.15b)$$

Podemos rescrever (2.15a) e (2.15b) na forma

$$\frac{\partial \left(\frac{1}{2} \phi \right)}{\sin \frac{1}{2} \phi} = \frac{a}{2} \quad (2.16a)$$

$$\frac{\bar{\partial} \left(\frac{1}{2} \phi \right)}{\sin \frac{1}{2} \phi} = -\frac{1}{2a} \quad (2.16b)$$

A integração das equações (2.16a) e (2.16b) dá

$$\ln \tan \left(\frac{\phi}{2} \right) = \frac{a}{2} z + f_1(\bar{z})$$

$$\ln \tan \left(\frac{\phi}{2} \right) = -\frac{1}{2a} \bar{z} + f_2(z)$$

Subtraindo segue-se

$$\frac{a}{2} z - f_2(z) = f_1(\bar{z}) + \frac{1}{2a} \bar{z} = \text{constante} = \delta$$

ou

$$\frac{a}{2} z - \frac{1}{2a} \bar{z} = f_1(\bar{z}) + f_2(z)$$

Somando segue

$$2 \ln \tan \left(\frac{\phi}{2} \right) = \frac{a}{2} z + f_1(\bar{z}) - \frac{1}{2a} \bar{z} + f_2(z)$$

Por tanto:

$$\frac{\phi}{2} = \arctan e^{\frac{a}{2}z - \frac{1}{2a}\bar{z}} \quad (2.17)$$

ou utilizando (2.14a)

$$\phi = 2 \arctan \left[e^{\frac{1}{2}(a+\frac{1}{a})\left(x + \frac{(a-\frac{1}{a})}{(a+\frac{1}{a})}t\right)} \right] \quad (2.17')$$

Temos como solução de uma perturbação que viaja com velocidade

$$v = \frac{(a - \frac{1}{a})}{(a + \frac{1}{a})} \quad (2.17'')$$

Constitue a solução de 1 sóliton.

3 Capítulo 3

3.1 Equações de Lax, Condição de Curvatura Nula, e Equações de Leznov-Saveliev

Considere as equações de Lax para as conexões A e \bar{A}

$$(\partial + A)\psi = 0 \quad (3.1)$$

$$(\bar{\partial} + \bar{A})\psi = 0 \quad (3.2)$$

Aplicando o operador $\bar{\partial}$ em (3.1) e ∂ em (3.2) e utilizando a condição de integrabilidade : $\bar{\partial}\partial = \partial\bar{\partial}$, a compatibilidade das equações dá a condição de curvatura nula:

$$[\partial + A, \bar{\partial} + \bar{A}] = \partial\bar{A} - \bar{\partial}A + [A, \bar{A}] = 0 \quad (3.3)$$

Fazendo a " transformação de gauge ", (" com a função de gauge" θ)

$$A^g = \theta A \theta^{-1} - \partial\theta\theta^{-1}$$

$$\bar{A}^g = \theta \bar{A} \theta^{-1} - \bar{\partial}\theta\theta^{-1} \quad (3.4)$$

é facil verificar que a condição de curvatura nula (3.3) continua válida para A^g e \bar{A}^g , isto é

$$\partial\bar{A}^g - \bar{\partial}A^g + [A^g, \bar{A}^g] = 0 \quad (3.5)$$

Considere as equações de Lax

$$(\partial + A^g)\psi_g = 0 \quad (\bar{\partial} + \bar{A}^g)\psi_g = 0 \quad (3.6)$$

$$(\partial + A^f)\psi_f = 0 \quad (\bar{\partial} + \bar{A}^f)\psi_f = 0 \quad (3.7)$$

e considere

$$\psi_g = \theta\psi_f \quad (3.8)$$

Neste caso é facil verificar que A^g e A^f , \bar{A}^g e \bar{A}^f estão relacionadas por uma 'transformação de gauge' do tipo (3.4) onde θ é a função de "gauge" correspondente.

As soluções de condição de curvatura nula são do tipo

$$A = -(\partial T)T^{-1} \quad \bar{A} = -(\bar{\partial} T)T^{-1} \quad (3.9)$$

Considere agora os "potenciais de gauge"

$$A = -B\varepsilon_+B^{-1} \quad \bar{A} = -\bar{\partial}BB^{-1} + \varepsilon_- \quad (3.10)$$

com ε_+ e ε_- operadores constantes em relação a z e \bar{z}

$$\begin{aligned} \text{Temos } [A, \bar{A}] &= (-B\varepsilon_+B^{-1}) (-\bar{\partial}BB^{-1} + \varepsilon_-) - (-\bar{\partial}BB^{-1} + \varepsilon_-) (-B\varepsilon_+B^{-1}) \\ &= B\varepsilon_+B^{-1}\bar{\partial}BB^{-1} - B\varepsilon_+B^{-1}\varepsilon_- - \bar{\partial}B\varepsilon_+B^{-1} + \varepsilon_-B\varepsilon_+B^{-1} \end{aligned}$$

$$\partial\bar{A} - \bar{\partial}A = -\partial(\bar{\partial}BB^{-1}) + (\bar{\partial}B)\varepsilon_+B^{-1} - B\varepsilon_+B^{-1}(\bar{\partial}B)B^{-1}$$

onde usamos $\partial\varepsilon_- = \bar{\partial}\varepsilon_+ = 0$

Utilizando a condição de curvatura nula (3.3) segue :

$$\partial[\bar{\partial}BB^{-1}] = [\varepsilon_-, B\varepsilon_+B^{-1}] \quad (3.11)$$

Podemos reescrever:

$$\begin{aligned} \partial\bar{\partial}B B^{-1} + (\bar{\partial}B)(\partial B^{-1}) &= \partial\bar{\partial}B B^{-1} - (\bar{\partial}B) B^{-1}(\partial B) B^{-1} \\ &= \varepsilon_-B\varepsilon_+B^{-1} - B\varepsilon_+B^{-1} \end{aligned}$$

Multipliquemos á esquerda por B^{-1} e á direita por B

$$B^{-1}\partial\bar{\partial}B - B^{-1}(\bar{\partial}B) B^{-1}(\partial B) = B^{-1}\varepsilon_- B \varepsilon_+ - \varepsilon_+B^{-1}\varepsilon_- B$$

ou:

$$B^{-1}(\partial\bar{\partial}B) + (\bar{\partial}B^{-1})(\partial B) = [B^{-1}\varepsilon_- B, \varepsilon_+]$$

ou:

$$\bar{\partial}(B^{-1}\partial B) = -[\varepsilon_+, B^{-1}\varepsilon_- B] \quad (3.12)$$

Em resumo, no caso das conexões A e \bar{A} serem dadas por (3.10) com ε_+ e ε_- operadores constantes, então a condição de curvatura nula pode-se reescrever na forma das equações (3.11) e (3.12). Estas equações foram propostas primeiramente por Leznov e Saveliev [7]

Obtenção da Transformação de Backlund á partir de Transformações de Gauge

Vamos dar agora uma formulação sugerida por G.Sotkov.

Considere as eqs. de Lax (3.6 e 3.7) com os potenciais de gauge da forma (3.10)

$$\begin{aligned} (\partial + A^g)\psi_g &= 0 & (\partial + A^f)\psi_f &= 0 \\ (\bar{\partial} + \bar{A}^g)\psi_g &= 0 & (\bar{\partial} + \bar{A}^f)\psi_f &= 0 \end{aligned} \quad (3.13)$$

com

$$A^g = -g\varepsilon_+g^{-1} \quad \bar{A}^g = -(\bar{\partial}g)g^{-1} + \varepsilon_- \quad (3.14)$$

$$A^f = -f\varepsilon_+f^{-1} \quad \bar{A}^f = -(\bar{\partial}f)f^{-1} + \varepsilon_- \quad (3.15)$$

e considere a transformação de "gauge"

$$\psi_g = \theta\psi_f \quad (3.16)$$

Introduzindo na primeira equação (3.14) segue-se:

$$(\bar{\partial} + \bar{A}^g)\theta\psi_f = (\bar{\partial} - (\bar{\partial}g)g^{-1} + \varepsilon_-)\theta\psi_f = 0$$

e aplicando á esquerda o operador θ^{-1} obtemos

$$[\theta^{-1}\bar{\partial}\theta - \theta^{-1}(\bar{\partial}g)g^{-1}\theta + \theta^{-1}\varepsilon_-]\psi_f = 0$$

Comparando com a segunda equação de (3.14) segue

$$-(\bar{\partial}f)f^{-1} + \varepsilon_- = \theta^{-1}\bar{\partial}\theta - \theta^{-1}(\bar{\partial}g)g^{-1}\theta + \theta^{-1}\varepsilon_- \quad (3.17)$$

Da mesma maneira substituindo na equação (3.13) e comparando com a equação para ψ_f segue

$$-\theta^{-1}f\varepsilon_+f^{-1}\theta = \theta^{-1}\partial\theta - \theta^{-1}g\varepsilon_+g^{-1}\theta \quad (3.18)$$

Aplicando em (3.17) o operador θ , segue-se

$$-\theta(\bar{\partial}f)f^{-1} + [\theta, \varepsilon_-] = \bar{\partial}\theta - (\bar{\partial}g)g^{-1}\theta \quad (3.19)$$

ou a sua equivalente

$$\theta f(\bar{\partial}f^{-1}) + [\theta, \varepsilon_-] = \bar{\partial}\theta - (\bar{\partial}g)g^{-1}\theta \quad (3.20)$$

Consideremos o "anzats"

$$\theta = x + gyf^{-1} \quad (3.21)$$

com x e y, são matrizes constantes. Introduzindo (3.21) em (3.20) segue-se

$$xf\bar{\partial}f^{-1} + [\theta, \varepsilon_-] = g\bar{\partial}g^{-1}x$$

ou

$$xf\bar{\partial}f^{-1} + [x + gyf^{-1}, \varepsilon_-] = g\bar{\partial}g^{-1}x \quad (3.22)$$

Da mesma maneira, considerando as equações (3.13) e a transformação de "gauge" (3.16) segue-se:

$$\partial\theta - g\varepsilon_+g^{-1}\theta = -\theta f\varepsilon_+f^{-1} \quad (3.23)$$

Introduzindo (3.18) em (3.23) vale

$$g^{-1}\partial gy + y\partial f^{-1}f - [\varepsilon_+, y] - [\varepsilon_+, g^{-1}xf] = 0 \quad (3.24)$$

Aplicando em (3.22) o operador ∂ , e lembrando que x e y são constantes, segue utilizando para g e f as equações (3.11), (3.12):

$$x\partial(f\bar{\partial}f^{-1}) + [\partial(gyf^{-1}), \varepsilon_-] = \partial(g\bar{\partial}g^{-1})x$$

ou

$$-x\partial(\bar{\partial}f f^{-1}) + [\partial(gyf^{-1}), \varepsilon_-] = -\partial(\bar{\partial}g g^{-1})x$$

ou

$$-x[\varepsilon_-, f\varepsilon_+f^{-1}] + [\partial(gyf^{-1}), \varepsilon_-] = -[\varepsilon_-, f\varepsilon_+f^{-1}]x$$

ou

$$-x[\varepsilon_-, f\varepsilon_+f^{-1}] + [\partial g y f^{-1} + g y \partial f^{-1}, \varepsilon_-] = -[\varepsilon_-, f\varepsilon_+f^{-1}]x \quad (3.25)$$

Já a equação (3.24) reescreve-se como:

$$\partial gy + gy\partial f^{-1}f - g[\varepsilon_+, y] - g[\varepsilon_+, g^{-1}xf] = 0 \quad (3.26)$$

Substituindo em (3.25) segue:

$$-x[\varepsilon_-, f\varepsilon_+f^{-1}] + [-gy\partial f^{-1} + g[\varepsilon_+, y]f^{-1} + g[\varepsilon_+, g^{-1}xf]f^{-1} + gy\partial f^{-1}, \varepsilon_-] = -[\varepsilon_-, g\varepsilon_+g^{-1}]x \quad (3.27)$$

Agora:

$$g[\varepsilon_+, g^{-1}xf]f^{-1} = g\varepsilon_+g^{-1}x f f^{-1} - g g^{-1}x f \varepsilon_+ f^{-1} = g\varepsilon_+g^{-1}x - x f \varepsilon_+ f^{-1}$$

que introduzida em (3.27) dá:

$$x[\varepsilon_-, f\varepsilon_+f^{-1}] + -gy\partial f^{-1} + [g[\varepsilon_+, y]f^{-1}, \varepsilon_-] + [g\varepsilon_+g^{-1}x, \varepsilon_-] - [x f \varepsilon_+ f^{-1}, \varepsilon_-] = -[\varepsilon_-, g\varepsilon_+g^{-1}]x$$

ou:

$$x[\varepsilon_-, f\varepsilon_+f^{-1}] + [g[\varepsilon_+, y]f^{-1}, \varepsilon_-] + [g\varepsilon_+g^{-1}, \varepsilon_-]x +$$

$$+g\varepsilon_+g^{-1}[x, \varepsilon_-] - x[f\varepsilon_+f^{-1}, \varepsilon_-] - [x, \varepsilon_-]f\varepsilon_+f^{-1}$$

$$= -[\varepsilon_-, g\varepsilon_+g^{-1}]x \quad (3.28)$$

Esta é a condição para x e y de modo que g e f satisfaçam as equações (3.11) e (3.12).

As equações (3.22) e (3.24) com a condição (3.28) dão as transformações de Backlund. Em muitos casos, uma solução simples de (3.28) é dada por

$$[x, \varepsilon_-] = [y, \varepsilon_+] = 0 \quad (3.29)$$

3.1.1 Aplicação á Equação de Sine Gordon

Nas Variáveis de cone de luz (2.14a),(2.14b), a equação de Sine-Gordon (2.2) pode-se reescrever:

$$\partial\bar{\partial}\phi - \frac{1}{2} \sin \phi = 0 \quad (3.30)$$

Tomemos

$$\varepsilon_+ = E_\alpha^0 + E_{-\alpha}^1, \quad \varepsilon_- = E_{-\alpha}^0 + E_\alpha^{-1} \quad (3.31)$$

$$\text{onde } E_\alpha^0 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad E_{-\alpha}^1 = \lambda \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad E_{-\alpha}^0 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad E_\alpha^{-1} = \frac{1}{\lambda} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$h^0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (3.32)$$

com λ parâmetro espectral. Utilizando (3.10) obtemos

$$A = -e^{2\varphi} E_\alpha^0 - e^{-2\varphi} E_{-\alpha}^1$$

$$\bar{A} = -h^0 \bar{\partial}\varphi + E_{-\alpha}^0 + E_\alpha^{-1} \quad (3.33)$$

Dai segue:

$$[A, \bar{A}] = -2e^{2\varphi} \bar{\partial}\varphi E_\alpha^0 + 2e^{-2\varphi} \bar{\partial}\varphi E_{-\alpha}^1 + (-e^{-2\varphi} + e^{2\varphi}) h^0 \quad (3.34)$$

$$\partial\bar{A} - \bar{\partial}A = -h^0 \partial\bar{\partial}\varphi + 2\bar{\partial}\varphi e^{2\varphi} E_\alpha^0 - 2\bar{\partial}\varphi e^{-2\varphi} E_{-\alpha}^1 \quad (3.35)$$

Por tanto a condição de curvatura nula escreve-se:

$$\partial\bar{A} - \bar{\partial}A + [A, \bar{A}] = (\partial\bar{\partial}\varphi - 2 \sinh(2\varphi)) h^0 \quad (3.36)$$

dando a equação de Sine Gordon (3.20) com a correspondencia $2\varphi \leftrightarrow \phi$

Estudemos agora as transformações de Backlund para este problema do ponto de vista de transformações de gauge.

Considere a solução simples de (3.29)

$$x = a\varepsilon_- + b \qquad y = c\varepsilon_+ + d$$

Escrevamos

$$f = e^{h\varphi} = \begin{pmatrix} e^\varphi & 0 \\ 0 & e^{-\varphi} \end{pmatrix} \qquad g = e^{h\varphi'} = \begin{pmatrix} e^{\varphi'} & 0 \\ 0 & e^{-\varphi'} \end{pmatrix}$$

Neste caso a eq. (3.22) dá

$$\begin{aligned} -\frac{1}{2}\bar{\partial}(\varphi' - \varphi)b &= c \sinh(\varphi + \varphi') \\ \frac{1}{2}\bar{\partial}(\varphi' + \varphi)a &= d \sinh(\varphi - \varphi') \end{aligned} \qquad (3.37)$$

enquanto que a equação (3.24) dá

$$\begin{aligned} \frac{d}{2}\partial(\varphi - \varphi') &= -a \sinh(\varphi + \varphi') \\ -\frac{c}{2}\bar{\partial}(\varphi' - \varphi) &= b \sinh(\varphi + \varphi') \end{aligned} \qquad (3.38)$$

Temos a possibilidade de $b=c=0$ e então obtemos as transformações de Backlund:

$$\begin{aligned} \bar{\partial}(\varphi' + \varphi) &= \frac{2d}{a} \sinh(\varphi - \varphi') \\ \partial(\varphi - \varphi') &= -2\frac{a}{d} \sinh(\varphi + \varphi') \end{aligned} \qquad (3.39)$$

ou a possibilidade $a=d=0$ e temos então as transformações de Backlund na forma:

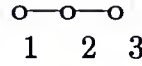
$$\begin{aligned} \bar{\partial}(\varphi' - \varphi) &= -\frac{2c}{b} \sinh(\varphi + \varphi') \\ \partial(\varphi' + \varphi) &= -\frac{2b}{c} \sinh(\varphi - \varphi') \end{aligned} \qquad (3.40)$$

3.2 A álgebra A_3 dobrada

A algebra $A_3 (=SL(4))$, tem por geradores satisfazendo ás relações de comutação:

$$\begin{aligned}
 [E_{\alpha_1}, E_{\alpha_2}] &= E_{\alpha_1+\alpha_2}, [E_{\alpha_2}, E_{\alpha_3}] = E_{\alpha_2+\alpha_3}, \\
 [E_{\alpha_1}, E_{-\alpha_1}] &= h_1, [E_{\alpha_2}, E_{-\alpha_2}] = h_2, \\
 [E_{\alpha_3}, E_{-\alpha_3}] &= h_3, [h_1, E_{\alpha_1}] = 2E_{\alpha_1}, \\
 [h_1, E_{\alpha_2}] &= -E_{\alpha_2}, [h_2, E_{\alpha_1}] = -E_{\alpha_1}, \\
 [h_2, E_{\alpha_2}] &= 2E_{\alpha_2}, [h_2, E_{\alpha_3}] = -E_{\alpha_3}, \\
 [h_3, E_{\alpha_2}] &= 2E_{\alpha_2}, [h_3, E_{\alpha_3}] = 2E_{\alpha_3}, \\
 [E_{\alpha_1}, E_{\alpha_2+\alpha_3}] &= E_{\alpha_1+\alpha_2+\alpha_3}, [E_{-\alpha_1-\alpha_2}, E_{\alpha_1}] = E_{\alpha_2}, \\
 [E_{-\alpha_1-\alpha_2}, E_{\alpha_2}] &= -E_{-\alpha_1}, [E_{-\alpha_2-\alpha_3}, E_{\alpha_2}] = E_{-\alpha_3}, \\
 [E_{\alpha_1+\alpha_2}, E_{\alpha_3}] &= E_{\alpha_1+\alpha_2+\alpha_3}, [E_{-\alpha_2-\alpha_3}, E_{\alpha_3}] = -E_{-\alpha_2} \\
 [E_{-\alpha_1-\alpha_2}, E_{\alpha_1+\alpha_2+\alpha_3}] &= E_{\alpha_3}, [E_{-\alpha_2-\alpha_3}, E_{\alpha_1+\alpha_2+\alpha_3}] = -E_{\alpha_1} \\
 [E_{-\alpha_2-\alpha_3}, E_{-\alpha_1}] &= E_{-\alpha_1-\alpha_2-\alpha_3}, [E_{\alpha_1+\alpha_2}, E_{-\alpha_1}] = -E_{\alpha_2} \\
 [E_{-\alpha_1-\alpha_2}, E_{-\alpha_3}] &= -E_{-\alpha_1-\alpha_2-\alpha_3}, [E_{\alpha_2+\alpha_3}, E_{-\alpha_3}] = E_{\alpha_2} \\
 [E_{\alpha_2+\alpha_3}, E_{-\alpha_1-\alpha_2-\alpha_3}] &= E_{-\alpha_1}, [E_{\alpha_1+\alpha_2}, E_{-\alpha_1-\alpha_2-\alpha_3}] = -E_{\alpha_3} \\
 [E_{\alpha_1}, E_{-\alpha_1-\alpha_2-\alpha_3}] &= -E_{-\alpha_2-\alpha_3}, [E_{\alpha_3}, E_{-\alpha_1-\alpha_2-\alpha_3}] = -E_{-\alpha_1-\alpha_2} \\
 [h_1, h_2] &= 0, [h_1, h_3] = 0, [h_2, h_3] = 0
 \end{aligned}
 \tag{3.41}$$

O diagrama de Dynkin de A_3 é dado por



Ele possui a simetria $1 \longleftrightarrow 3$ e $2 \longleftrightarrow 2$ o qual induz o automorfismo σ :

$$\sigma(E_{\alpha_1}) = E_{\alpha_3}, \quad \sigma(E_{\alpha_3}) = E_{\alpha_1}, \quad \sigma^2 = 1, \quad \sigma(E_{\alpha_2}) = E_{\alpha_2}
 \tag{3.42}$$

A fim de vermos como o automorfismo σ atua em $E_{\alpha_1+\alpha_2}$ notemos que

$$\sigma(E_{\alpha_1+\alpha_2}) = \sigma([E_{\alpha_1}, E_{\alpha_2}]) = [E_{\alpha_3}, E_{\alpha_2}] = -E_{\alpha_2+\alpha_3}
 \tag{3.43}$$

e portanto

$$\sigma(E_{\alpha_1+\alpha_2}) = -E_{\alpha_2+\alpha_3}
 \tag{3.44}$$

Como veremos adiante, a álgebra A_3 munida do automorfismo σ é idêntica a $B_2 = SO(5)$. Consideramos A_3 dobrada (folded) neste caso.

3.3 Relação entre a algebra A_3 dobrada e a algebra B_2

A fim de estudarmos a relação entre o A_3 dobrado e B_2 façamos a associação:

$$E_{\beta_1} = E_{\alpha_2}$$

$$E_{\beta_2} = E_{\alpha_1} + E_{\alpha_3} \quad (3.45)$$

Do ponto de vista do diagrama de Dynkin temos:

$$\begin{array}{c} \circ = < = \circ \\ 1,3 \quad 2 \end{array}$$

Agora:

$$[E_{\beta_1}, E_{\beta_2}] = [E_{\alpha_2}, E_{\alpha_1} + E_{\alpha_3}] = -E_{\alpha_1+\alpha_2} + E_{\alpha_2+\alpha_3} = E_{\beta_1+\beta_2} \quad (3.46)$$

Ainda:

$$[E_{\beta_1+\beta_2}, E_{\beta_2}] = [-E_{\alpha_1+\alpha_2} + E_{\alpha_2+\alpha_3}, E_{\alpha_1} + E_{\alpha_3}] = -2E_{\alpha_1+\alpha_2+\alpha_3} = -2E_{\beta_1+2\beta_2} \quad (3.47)$$

e por tanto

$$E_{\beta_1+2\beta_2} = E_{\alpha_1+\alpha_2+\alpha_3} \quad (3.48)$$

Quanto aos elementos de Cartan temos

$$[E_{\beta_1}, E_{-\beta_1}] = \tilde{h}_1 = [E_{\alpha_2}, E_{-\alpha_2}] = \frac{2\alpha_2 \cdot h}{\alpha_2^2} = h_2 \quad (3.49)$$

$$[E_{\beta_2}, E_{-\beta_2}] = \left(\frac{2\alpha_1 \cdot h}{\alpha_1^2} + \frac{2\alpha_3 \cdot h}{\alpha_3^2} \right) = (h_1 + h_3) = \tilde{h}_2 \quad (3.50)$$

onde \tilde{h}_1 e \tilde{h}_2 são os elementos de Cartan para $B_2 = SO(5)$

Pode-se verificar que valem as relações de comutação da álgebra B_2 : [8]

$$[E_{\beta_1}, E_{-\beta_1}] = \tilde{h}_1, [E_{\beta_2}, E_{-\beta_2}] = \tilde{h}_2, [E_{\beta_1+\beta_2}, E_{-\beta_1-\beta_2}] = 2\tilde{h}_1 + \tilde{h}_2$$

$$[E_{\beta_1+2\beta_2}, E_{-\beta_1-2\beta_2}] = \tilde{h}_1 + \tilde{h}_2$$

$$E_{\pm\beta_1} = \pm \frac{1}{2} [\tilde{h}_1, E_{\pm\beta_1}] = \pm \frac{1}{2} [E_{\pm\beta_1}, \tilde{h}_2] = \pm \frac{1}{2} [E_{\pm(\beta_1+\beta_2)}, E_{\mp\beta_2}]$$

$$E_{\pm\beta_2} = \pm [E_{\pm\beta_2}, \tilde{h}_1] = \pm \frac{1}{2} [\tilde{h}_2, E_{\pm\beta_2}] = \pm \frac{1}{2} [E_{\mp\beta_1}, E_{\pm(\beta_1+\beta_2)}] = \pm [E_{\pm(\beta_1+2\beta_2)}, E_{\pm(\beta_1+\beta_2)}]$$

$$E_{\pm(\beta_1+\beta_2)} = \pm [\tilde{h}_1, E_{\pm(\beta_1+\beta_2)}] = \pm [E_{\pm\beta_1}, E_{\pm\beta_2}] = \pm [E_{\mp\beta_2}, E_{\pm(\beta_1+2\beta_2)}]$$

$$E_{\pm(\beta_1+2\beta_2)} = \pm \frac{1}{2} [\tilde{h}_2, E_{\pm(\beta_1+2\beta_2)}] = \pm \frac{1}{2} [E_{\pm\beta_2}, E_{\pm(\beta_1+\beta_2)}] \quad (3.51)$$

3.4 Algebra de Kac Moody

Seja uma álgebra de Lie definida pelos comutadores

$$[E_\alpha, E_\beta] = \varepsilon(\alpha, \beta) E_{\alpha+\beta} \quad [h_\gamma, E_\beta] = 2 \frac{\alpha_\gamma \cdot \beta}{\alpha_\gamma^2} E_\beta$$

$$[E_\alpha, E_{-\alpha}] = h_\alpha \quad [h_\gamma, h_b] = 0 \quad (3.52)$$

α, β são raízes, $\varepsilon(\alpha, \beta)$ é determinado por (3.41), $h_\gamma = \alpha_\gamma \cdot H$ e tomamos a notação α_γ como uma raiz referida com nome γ .

Introduzimos a Loop Algebra

$$[E_\alpha^m, E_\beta^n] = \varepsilon(\alpha, \beta) E_{\alpha+\beta}^{m+n} \quad [h_\alpha^m, E_\beta^n] = 2 \frac{\alpha_\alpha \cdot \beta}{\alpha_\alpha^2} E_\beta^{m+n}$$

$$[E_\alpha^m, E_{-\alpha}^n] = h_\alpha^{m+n} \quad [h_\alpha^m, h_\beta^n] = 0 \quad (3.53)$$

com $E_\alpha^m = \lambda^m E_\alpha$, $h_\beta^m = \lambda^m h_\beta$ e λ é um número complexo arbitrário.

Ela pode-se generalizar a uma Algebra de Kac Moody mudando os comutadores entre os elementos de Cartan e os comutadores entre os geradores conjugados na seguinte forma

$$[E_\alpha^m, E_{-\alpha}^n] = h_\alpha^{m+n} + cm\delta_{m,-n} \quad [h_\alpha^m, h_\beta^n] = cm\delta_{m,-n} tr(h_\alpha h_\beta) \quad (3.54)$$

onde c é um operador chamado de 'termo central' que comuta com todos os geradores. Em resumo, temos que a Algebra de Kac Moody é definida pelos comutadores.

$$\begin{aligned} [E_\alpha^m, E_\beta^n] &= \varepsilon(\alpha, \beta) E_{\alpha+\beta}^{m+n} & [h_\alpha^m, E_\beta^n] &= 2 \frac{\alpha_\alpha \cdot \beta}{\alpha_\alpha^2} E_\beta^{m+n} \\ [E_\alpha^m, E_{-\alpha}^n] &= h_\alpha^{m+n} + cm\delta_{m,-n} & [h_\alpha^m, h_\beta^n] &= cm\delta_{m,-n} tr(h_\alpha h_\beta) \end{aligned} \quad (3.55)$$

Utilizaremos a graduação

$$Q = 2d + \frac{2 \lambda_2 \cdot h}{\alpha_2^2} \quad (3.56)$$

com $[d, \Lambda^m] = m\Lambda^m$, onde Λ^m é um gerador qualquer da álgebra de Kac-Moody e

$$\frac{2\lambda_2 \cdot \alpha_i}{\alpha_2^2} = \delta_{i,2} \quad (3.57)$$

O operador Q vai dar conta do grau de qualquer expressão que seja dada em função de geradores da Algebra de Kac Moody.

3.5 Construção de Modelo

Consideraremos os seguintes elementos constantes de grau ± 1 ,

$$\begin{aligned}\varepsilon_+ &= (E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0) + (E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1) \\ \varepsilon_- &= (E_{-\alpha_1-\alpha_2}^0 - E_{-\alpha_2-\alpha_3}^0) + (E_{\alpha_1+\alpha_2}^{-1} - E_{\alpha_2+\alpha_3}^{-1})\end{aligned}\quad (3.58)$$

e o elemento de grupo construído a partir de geradores de grau zero

$$B = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{\varphi(h)} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad (3.59)$$

com

$$\varphi(h) = \varphi(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3) + R(h_1 + h_3) + \nu c + \eta d \quad (3.60)$$

póde-se verificar que ε_+ , ε_- e B são invariantes pelo automorfismo σ .
Introduzimos as conexões A e \bar{A} por meio de:

$$A = -B\varepsilon_+B^{-1}$$

$$\bar{A} = -\partial_- B B^{-1} + \varepsilon_- \quad (3.61)$$

Fazendo o calculo para $B^{-1} \partial B$ e substituindo $\tilde{\psi}e^R \rightarrow \psi$, $\tilde{\chi} e^R \rightarrow \chi$, (ver apêndice A)

$$\begin{aligned}B^{-1} \partial B |_{vinc} &= \\ &= \partial \psi e^{-R(E_{\alpha_1}^0 + E_{\alpha_3}^0)} + \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial \varphi + \partial \nu c + \partial \eta d + \frac{\partial \chi}{\Delta} e^{R(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}\end{aligned}\quad (3.62)$$

onde introduzimos o vínculo

$$\partial R = \frac{\psi \partial \chi}{1 + \chi \psi} \quad (3.63)$$

o que corresponde a tomar em $B^{-1} \partial B$ a corrente na direção de $(h_1 + h_3)$ de igual a zero. Esta é a chamada condição de "Black Hole", e pode-se provar que ela decorre do fato de $(h_1 + h_3)$ comutar com ε_+ e ε_- .

Analogamente consideramos a corrente $\bar{\partial} B B^{-1}$ (ver apêndice B), a condição de "Black Hole"

$$\bar{\partial} R = \frac{\chi \bar{\partial} \psi}{1 + \chi \psi} \quad (3.64)$$

dá

$$\bar{\partial}BB^{-1}|_{vinc} = \bar{\partial}\chi e^{-R}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0) + \bar{\partial}\varphi \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) + \frac{\bar{\partial}\psi}{\Delta} e^R(E_{\alpha_1}^0 + E_{\alpha_3}^0) + \bar{\partial}\nu c + \bar{\partial}\eta d \quad (3.65)$$

As equações de movimento para os campos χ, ψ, φ, R são obtidas á partir da equação de curvatura nula

$$\partial\bar{A} - \bar{\partial}A + [A, \bar{A}] = 0 \quad (3.66)$$

onde substituímos (3.59) em (3.61).

$$\begin{aligned} \bar{A} = & -e^{-\varphi}(1 + 2\chi\psi)(E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0) - 2\psi e^{-\varphi-R}(1 + \chi\psi)E_{\alpha_1+\alpha_2+\alpha_3}^0 \\ & - e^{\varphi}(1 + 2\chi\psi) \left(E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1 \right) - 2\psi e^{-\varphi-R-\eta}(1 + \chi\psi)E_{-\alpha_2}^1 \\ & + 2\chi e^{-\varphi+R}E_{\alpha_2}^0 + 2\chi e^{\varphi+R-\eta}E_{-\alpha_1-\alpha_2-\alpha_3}^1 \end{aligned} \quad (3.67)$$

$$\begin{aligned} A = & E_{-\alpha_1-\alpha_2}^0 - E_{-\alpha_2-\alpha_3}^0 + E_{\alpha_1+\alpha_2}^{-1} - E_{\alpha_2+\alpha_3}^{-1} + \partial\psi e^{-R}(E_{\alpha_1}^0 + E_{\alpha_3}^0) + \\ & + \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial\varphi + \frac{\partial\psi}{\Delta} e^R(E_{-\alpha_1}^0 + E_{-\alpha_3}^0) + \partial\nu c + \partial\eta d \end{aligned} \quad (3.68)$$

no caso de Kac Moody. Introduzindo (3.67) e (3.68) em (3.66), obtemos:

$$\partial\bar{\partial}\varphi - 2(1 + 2\psi\chi)e^{-\varphi} + 2(1 + 2\psi\chi)e^{\varphi-\eta} = 0$$

$$\partial\bar{\partial}\nu - 2e^{\varphi-\eta}(1 + 2\psi\chi) = 0$$

$$\partial\bar{\partial}\chi(1 + \psi\chi) - \psi\partial\chi\bar{\partial}\chi + 4\chi(1 + \psi\chi)^2 \left(\frac{e^{\varphi-\eta} + e^{-\varphi}}{2} \right) = 0$$

$$\partial\bar{\partial}\psi(1 + \psi\chi) - \chi\partial\psi\bar{\partial}\psi + 4\psi(1 + \psi\chi)^2 \left(\frac{e^{-\varphi-\eta} + e^{-\varphi}}{2} \right) = 0 \quad (3.69)$$

pode-se verificar facilmente que estas equações são deriváveis da Langrangiana

$$\mathcal{L} = 2 \frac{\partial\chi\bar{\partial}\psi}{(1 + \psi\chi)} + \frac{1}{2}\partial\varphi\bar{\partial}\varphi - 4(1 + \chi\psi) \left(\frac{e^{-\varphi-\eta} + e^{\varphi}}{2} \right) + \bar{\partial}\eta\partial\nu \quad (3.70)$$

Pode-se verificar que as equações (3.69) seguem também das equações de Leznov-Saveliev (Veja Apêndice E)

3.6 Solução as Equações (3.69) na aproximação de "Loop Algebra"

Tentemos resolver as equações (3.69) na aproximação de "Loop Algebra", (não consideramos ν e nem η). Neste caso temos

$$B^{-1}\partial B|_{vinc} = \partial\psi e^{-R}(E_{\alpha_1}^0 + E_{\alpha_3}^0) + \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3\right) \partial\varphi + \frac{\partial\chi}{\Delta} e^R(E_{-\alpha_1}^0 + E_{-\alpha_3}^0) \quad (3.71)$$

$$\bar{\partial}BB^{-1}|_{vinc} = \bar{\partial}\chi e^{-R}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0) + \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3\right) \bar{\partial}\varphi + \frac{\bar{\partial}\psi}{\Delta} e^R(E_{\alpha_1}^0 + E_{\alpha_3}^0) \quad (3.72)$$

De agora em diante suprimimos a notação $|_{vinc}$, subentendendo $B^{-1}\partial B$ e $\bar{\partial}B B^{-1}$ vinculados.

Podemos reescrever ε_+ e ε_- na forma matricial

$$\varepsilon_+ = (E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0) + (E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1) = \begin{pmatrix} 0 & \sigma_3 \\ \lambda\sigma_3 & 0 \end{pmatrix} \quad (3.73)$$

$$\varepsilon_- = (E_{-\alpha_1-\alpha_2}^0 - E_{-\alpha_2-\alpha_3}^0) + (E_{\alpha_1+\alpha_2}^{-1} - E_{\alpha_2+\alpha_3}^{-1}) = \begin{pmatrix} 0 & \lambda^{-1}\sigma_3 \\ \sigma_3 & 0 \end{pmatrix} \quad (3.74)$$

onde $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ é a matriz de Pauli e λ é o parâmetro de "Loop".

Utilizemos o método sugerido por G.Sotkov para formular a transformação de Backlund para o sistema.

Tomemos o "ansatz"

$$x = \alpha 1 + \beta(h_1 + h_3) + \gamma\varepsilon_-$$

$$y = \bar{\alpha}1 + \bar{\beta}(h_1 + h_3) + \bar{\gamma}\varepsilon_+$$

tais que $[x, \varepsilon_-] = [y, \varepsilon_+] = 0$

Explícitamente

$$x = \begin{pmatrix} \alpha.1 + \beta\sigma_3 & \lambda^{-1}\gamma\sigma_3 \\ \gamma\sigma_3 & \alpha.1 + \beta\sigma_3 \end{pmatrix} \quad (3.75)$$

$$y = \begin{pmatrix} \bar{\alpha}.1 + \bar{\beta}\sigma_3 & \bar{\gamma}\sigma_3 \\ \bar{\gamma}\sigma_3 & \bar{\alpha}.1 + \bar{\beta}\sigma_3 \end{pmatrix} \quad (3.76)$$

$$\varphi(h) = \varphi\left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3\right) + R(h_1 + h_3) = \begin{pmatrix} e^{\frac{1}{2}\varphi+R} & 0 & 0 & 0 \\ 0 & e^{\frac{1}{2}\varphi-R} & 0 & 0 \\ 0 & 0 & e^{-\frac{1}{2}\varphi+R} & 0 \\ 0 & 0 & 0 & e^{-\frac{1}{2}\varphi-R} \end{pmatrix} \quad (3.77)$$

e escrevemos as equações de primeira ordem

$$B^{-1}\partial B x = B^{-1}y\varepsilon_- - \varepsilon_-B^{-1}y \quad (3.78)$$

$$-\bar{\partial}BB^{-1}y = -Bx\varepsilon_+ + \varepsilon_+Bx \quad (3.79)$$

$$B^{-1}\partial B = \begin{pmatrix} \frac{1}{2}\partial\varphi & \partial\psi e^{-R} & 0 & 0 \\ \frac{\partial\chi}{\Delta} e^R & \frac{1}{2}\partial\varphi & 0 & 0 \\ 0 & 0 & \frac{-1}{2}\partial\varphi & \partial\psi e^{-R} \\ 0 & 0 & \frac{\partial\chi}{\Delta} e^R & \frac{-1}{2}\partial\varphi \end{pmatrix} \quad (3.80)$$

$$\bar{\partial}BB^{-1} = \begin{pmatrix} \frac{1}{2}\bar{\partial}\varphi & \bar{\partial}\psi e^R & 0 & 0 \\ \frac{\bar{\partial}\chi}{\Delta} e^{-R} & \frac{1}{2}\bar{\partial}\varphi & 0 & 0 \\ 0 & 0 & \frac{-1}{2}\bar{\partial}\varphi & \frac{\bar{\partial}\psi}{\Delta} e^R \\ 0 & 0 & \frac{\bar{\partial}\chi}{\Delta} e^{-R} & \frac{-1}{2}\bar{\partial}\varphi \end{pmatrix} \quad (3.81)$$

onde

$$\Delta = (1 + \psi\chi) \quad (3.82)$$

As equações (3.77) e (3.78) reescrevem-se

$$\frac{1}{2}(\alpha + \beta)\partial\varphi = \bar{\gamma}e^{-\tilde{R}}(1 + \chi\psi)^{1/2}(e^{-\varphi/2} - e^{\varphi/2})$$

$$\frac{1}{2}(\alpha - \beta)\partial\varphi = \bar{\gamma}e^{-\tilde{R}}(1 + \chi\psi)^{1/2}(e^{-\varphi/2} - e^{\varphi/2})$$

$$(\alpha - \beta)\frac{\partial\psi}{(1 + \psi\chi)^{1/2}}e^{-\tilde{R}} = -\bar{\gamma}\psi(e^{-\varphi/2} + e^{\varphi/2})$$

$$(\alpha + \beta)\frac{\bar{\partial}\chi}{(1 + \psi\chi)^{1/2}}e^{\tilde{R}} = -\bar{\gamma}\chi(e^{-\varphi/2} + e^{\varphi/2}) \quad (3.83)$$

$$\frac{1}{2}(\bar{\alpha} + \bar{\beta})\bar{\partial}\varphi = \gamma e^{\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2})$$

$$\frac{1}{2}(\bar{\alpha} - \bar{\beta})\bar{\partial}\varphi = \gamma e^{-\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2}) \quad (3.84)$$

$$(\bar{\alpha} - \bar{\beta})\frac{\bar{\partial}\psi}{(1 + \psi\chi)^{1/2}}e^{\tilde{R}} = \gamma\psi(e^{\varphi/2} + e^{-\varphi/2})$$

$$(\bar{\alpha} + \bar{\beta}) \frac{\bar{\partial}\chi}{(1 + \psi\chi)^{1/2}} e^{-\tilde{R}} = \gamma\psi(e^{-\varphi/2} + e^{\varphi/2})$$

com

$$\tilde{R} = R - \frac{1}{2} \ln(1 + \chi\psi) \quad (3.85)$$

$$-\frac{1}{2}\gamma\partial\varphi = (\bar{\alpha} + \bar{\beta})e^{-\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2})$$

$$\frac{1}{2}\gamma\partial\varphi = -(\bar{\alpha} - \bar{\beta})e^{\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2})$$

$$-\gamma \frac{\partial\psi}{(1 + \chi\psi)^{1/2}} e^{-\tilde{R}} = (\bar{\alpha} - \bar{\beta})\psi(e^{\varphi/2} + e^{-\varphi/2})$$

$$\gamma \frac{\partial\chi}{(1 + \chi\psi)^{1/2}} e^{\tilde{R}} = (\bar{\alpha} + \bar{\beta})\chi(e^{\varphi/2} + e^{-\varphi/2}) \quad (3.86)$$

$$\frac{1}{2}\bar{\gamma}\bar{\partial}\varphi = (\alpha + \beta)e^{\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2})$$

$$-\frac{1}{2}\bar{\gamma}\bar{\partial}\varphi = -(\alpha - \beta)e^{-\tilde{R}}(1 + \chi\psi)^{1/2}(e^{\varphi/2} - e^{-\varphi/2})$$

$$\bar{\gamma} \frac{\bar{\partial}\psi}{(1 + \chi\psi)^{1/2}} e^{\tilde{R}} = (\alpha - \beta)\psi(e^{\varphi/2} + e^{-\varphi/2})$$

$$\bar{\gamma} \frac{\bar{\partial}\chi}{(1 + \chi\psi)^{1/2}} e^{-\tilde{R}} = (\alpha + \beta)\chi(e^{\varphi/2} + e^{-\varphi/2}) \quad (3.87)$$

As duas primeiras equações de (3.83), (3.86),(3.82b), (3.87) dão

$$\tilde{R} = \text{constante}$$

Das duas primeiras equações de (3.83) e (3.86) obtemos

$$(\partial + \sigma\bar{\partial})\varphi = 0 \quad \text{onde } \sigma = \frac{\bar{\gamma}(\bar{\alpha} - \bar{\beta})}{\gamma(\alpha + \beta)} \quad (3.88)$$

Análogamente as outras expressões dão:

$$(\partial + \sigma\bar{\partial})\psi = (\partial + \sigma\bar{\partial})\chi = 0 \quad (3.89)$$

Então os campos são funções de $z - \frac{1}{\sigma}\bar{z}$

Aplicamos o operador $\bar{\partial}$ na 1ª equação (3.83). Utilizando o fato que $\tilde{R} = \text{constante}$, não é difícil mostrar que

$$\frac{1}{2}(\alpha + \beta)\bar{\partial}\partial\varphi = \frac{-\gamma\bar{\gamma}}{(\bar{\alpha} - \beta)}(e^{-\varphi} - e^{\varphi}) \quad (3.90)$$

Isto é, φ satisfaz a equação de Sinh-Gordon. Comparando com a primeira equação (3.69) segue-se que $\chi\psi = \text{constante}$

As duas primeiras equações (3.83) dão:

$$e^{2\tilde{R}} = \frac{(\alpha - \beta)}{(\alpha + \beta)} \quad (3.91)$$

Multiplico a 3ª equação de (3.83) por χ e a 4ª equação por ψ e divido uma pela outra obtendo:

$$\frac{(\alpha - \beta)\chi\partial\psi}{(\alpha + \beta)\psi\partial\chi}e^{-2\tilde{R}} = 1 = \frac{\chi\partial\psi}{\psi\partial\chi} \quad (3.92)$$

onde utilizamos (3.91). De $\psi\chi = \text{constante}$ segue :

$$\psi\partial\chi + \chi\partial\psi = 0$$

enquanto (3.92) da

$$\psi\partial\chi - \chi\partial\psi = 0.$$

Estas 2 últimas equações dão $\psi\partial\chi = \chi\partial\psi = 0$. Da mesma forma temos $\psi\bar{\partial}\chi = \chi\bar{\partial}\psi = 0$. e por tanto ψ e χ são constantes, As duas últimas equações (3.83) dizem que $\psi = \chi = 0$.

Em outras palavras, temos a solução para φ satisfazendo a eq. de Sinh-Gordon e $\chi = \psi = 0$, $R=0$.

3.7 Estudo dos Autoestados e Autovalores dos operadores $\varepsilon_+, \varepsilon_-$.

Vamos agora estudar os autoestados e autovalores correspondentes aos operadores $\varepsilon_+, \varepsilon_-$, eles são dados por (ver apêndice B):

$$\begin{aligned}
 F_1^+ &= \sum_n E_{\alpha_1}^n \lambda^{-2n} + \sum_n E_{\alpha_3}^n \lambda^{-2n} + \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n \lambda^{-2n-1} + \sum_n E_{-\alpha_2}^n \lambda^{-2n+1} \\
 F_1^- &= \sum_n E_{\alpha_1}^n \lambda^{-2n} + \sum_n E_{\alpha_3}^n \lambda^{-2n} - \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n \lambda^{-2n-1} - \sum_n E_{-\alpha_2}^n \lambda^{-2n+1} \\
 F_2^+ &= \sum_n E_{\alpha_2}^n \lambda^{-2n} + \sum_n E_{-\alpha_3}^n \lambda^{-2n} + \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^n \lambda^{-2n-1} + \sum_n E_{-\alpha_1}^n \lambda^{-2n+1} \\
 F_2^- &= \sum_n E_{\alpha_2}^n \lambda^{-2n-1} + \sum_n E_{-\alpha_3}^n \lambda^{-2n} + \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^n \lambda^{-2n+1} + \sum_n E_{-\alpha_1}^n \lambda^{-2n} \\
 F_4^+ &= \sum_n h_1^n \lambda^{-2n} + 2 \sum_n h_2^n \lambda^{-2n} + \sum_n h_3^n \lambda^{-2n} - \sum_n E_{\alpha_1+\alpha_2}^n \lambda^{-2n-1} + \\
 &+ \sum_n E_{\alpha_2+\alpha_3}^n \lambda^{-2n-1} + \sum_n E_{-\alpha_1-\alpha_2}^n \lambda^{-2n+1} - \sum_n E_{-\alpha_2-\alpha_3}^n \lambda^{-2n+1} - c \\
 F_4^- &= \sum_n h_1^n \lambda^{-2n} + 2 \sum_n h_2^n \lambda^{-2n} + \sum_n h_3^n \lambda^{-2n} + \sum_n E_{\alpha_1+\alpha_2}^n \lambda^{-2n-1} + \\
 &- \sum_n E_{\alpha_2+\alpha_3}^n \lambda^{-2n-1} - \sum_n E_{-\alpha_1-\alpha_2}^n \lambda^{-2n+1} + \sum_n E_{-\alpha_2-\alpha_3}^n \lambda^{-2n+1} - c \\
 F_6^+ &= \sum_n E_{\alpha_2}^n \lambda^{-2n} - \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^n \lambda^{-2n-1} \\
 F_6^- &= \sum_n E_{-\alpha_2}^n \lambda^{2n} - \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n \lambda^{2n-1}
 \end{aligned} \tag{3.93}$$

e satisfazem á condição de serem invariantes pelo automorfismo σ .

Valem as relações

$$\begin{aligned}
 [\varepsilon^m, F_1^\pm] &= \pm 2\lambda^{2m+1} F_1^\pm & [\varepsilon, F_2^\pm] &= \pm 2\lambda^{2m+1} F_2^\pm \\
 [\varepsilon^m, F_4^\pm] &= \pm 2\lambda^{2m+1} F_4^\pm & [\varepsilon^m, F_6^\pm] &= 0
 \end{aligned} \tag{3.94}$$

onde definimos

$$\varepsilon^m = \left(E_{\alpha_1+\alpha_2}^m - E_{\alpha_2+\alpha_3}^m \right) + \left(E_{-\alpha_1-\alpha_2}^{m+1} - E_{-\alpha_2-\alpha_3}^{m+1} \right) \tag{3.95}$$

Para $m=0$, ε^m se reduz a ε_+ enquanto que para $m=-1$, ε^{-1} se reduz a ε_- .

Vamos reecriver as expressões (3.93), (3.94), e (3.95) em termos dos geradores (3.45), (3.46), (3.47), (3.48)

$$\varepsilon^m = -E_{\beta_1+\beta_2}^m - E_{-(\beta_1+\beta_2)}^m$$

$$F_1^\pm = \sum_n E_{\beta_2}^n \lambda^{-2n} \pm \sum_n E_{\beta_1+2\beta_2}^n \lambda^{-2n-1} \pm \sum_n E_{-\beta_1}^n \lambda^{-2n+1}$$

$$F_2^\pm = \sum_n E_{\beta_1}^n \lambda^{-2n-1} \mp \sum_n E_{-\beta_2}^n \lambda^{-2n} + \sum_n E_{-\beta_1-2\beta_2}^n \lambda^{-2n+1}$$

$$F_4^\pm = \sum_n \tilde{h}_2^n \lambda^{-2n} + 2 \sum_n \tilde{h}_1^n \lambda^{-2n} - \sum_n E_{\beta_1+\beta_2}^n \lambda^{-2n-1} \mp \sum_n E_{-\beta_1-\beta_2}^n \lambda^{-2n+1} - c$$

$$F_6^\pm = \sum_n E_{\pm\beta_1}^n \lambda^{-2n} - \sum_n E_{\pm(\beta_1+2\beta_2)}^n \lambda^{-2n+1} \quad (3.96)$$

3.8 Metodo de "dressing"

Um método para determinar as soluções solitónicas consiste em vestir (to dress) o vácuo para uma solução não trivial por meio de transformação de "gauge".

A condição de curvatura nula implica que as conexões A e \bar{A} são puro "gauge".

As soluções de "vácuo" satisfazem

$$A_{vac} = \varepsilon_- + \partial \nu_0 c = \varepsilon_- + 2\bar{z}c$$

$$A_{vac} = -\varepsilon_+ \quad (3.97)$$

com $[\varepsilon_+, \varepsilon_-] = 2c$

Então

$$\begin{aligned} T_0 &= e^{\varepsilon_- z} e^{-\varepsilon_+ \bar{z}} & T_0^{-1} &= e^{\varepsilon_+ \bar{z}} e^{-\varepsilon_- z} \\ T_0^{-1} \partial T_0 &= e^{\varepsilon_+ \bar{z}} e^{-\varepsilon_- z} \partial (e^{\varepsilon_- z}) e^{-\varepsilon_+ \bar{z}} = e^{\varepsilon_+ \bar{z}} \varepsilon_- e^{-\varepsilon_+ \bar{z}} \\ &= \varepsilon_- + \bar{z} [\varepsilon_+, \varepsilon_-] = \varepsilon_- + 2c \bar{z} = A_{vac} = -(\partial T_0^{-1}) T_0 \end{aligned}$$

Também

$$-\bar{\partial} T_0^{-1} T_0 = T_0^{-1} \bar{\partial} T_0 = e^{\varepsilon_+ \bar{z}} e^{-\varepsilon_- z} \bar{\partial} (e^{\varepsilon_- z}) e^{-\varepsilon_+ \bar{z}} = -\varepsilon_+ = \bar{A}_{vac}$$

Póde-se escrever

$$(\partial + A_{vac}) T_0^{-1} = 0$$

$$(\bar{\partial} + \bar{A}_{vac}) T_0^{-1} = 0$$

Escrevamos A e \bar{A} na forma

$$A = (T_o \theta)^{-1} \partial (T_o \theta) = \theta^{-1} T_o^{-1} (\partial T_o) \theta + \theta^{-1} \partial \theta$$

ou:

$$A = \theta^{-1} A_{vac} \theta + \theta^{-1} \partial \theta$$

Da mesma maneira

$$\bar{A} = \theta^{-1} \bar{A}_{vac} \theta + \theta^{-1} \bar{\partial} \theta = (T_o \theta)^{-1} \bar{\partial} (T_o \theta)$$

O método de "dressing" baseia-se na hipótese da existência de duas transformações de gauge geradas por θ^\pm mapeando o vácuo numa configuração não trivial:

$$A = (\theta^\pm)^{-1} A_{vac} (\theta^\pm) + (\theta^\pm)^{-1} \partial \theta^\pm = B^{-1} \partial B + \varepsilon_-$$

$$\bar{A} = (\theta^\pm)^{-1} \bar{A}_{vac} (\theta^\pm) + (\theta^\pm)^{-1} \bar{\partial} (\theta^\pm) = -B^{-1} \varepsilon_+ B \quad (3.98)$$

com θ^+ contendo graus positivos e nulo:

$$\theta^+ = \theta_o \theta_> \text{ com } \theta_> = e^{t^{(1)}+t^{(2)}+\dots}$$

onde $t^{(i)}$ é construído com o auxílio de geradores de grau $i > 0$.

$$\text{Então: } A = \theta_>^{-1} \theta_o^{-1} A_{vac} \theta_o \theta_> + \theta_>^{-1} (\theta_o^{-1} \partial \theta_o) \theta_> + \theta_>^{-1} \partial \theta_>$$

ou

$$\partial B B^{-1} + \varepsilon_- = \theta_>^{-1} \theta_o^{-1} (\varepsilon_- + 2 \bar{z}) \theta_o \theta_> + \theta_>^{-1} \theta_o^{-1} \partial \theta_o \theta_> + \theta_>^{-1} \partial \theta_>$$

Comparemos os 2 lados pelos diferentes graus.

$$\text{grau -1} \quad \varepsilon_- = \theta_o^{-1} \varepsilon_- \theta \rightarrow \text{permite a escolha } \theta_o = 1$$

$$\text{grau 0} \quad B^{-1} \partial B = [\varepsilon_-, t^1] + 2 \bar{z}$$

(3.99)

Temos também:

$$\bar{A} = \theta_>^{-1} \theta_o^{-1} (-\varepsilon_+) \theta_o \theta_> + \theta_>^{-1} \theta_o^{-1} \bar{\partial} \theta_o \theta_> + \theta_>^{-1} \bar{\partial} \theta_> = -B^{-1} \varepsilon_+ B$$

analisando o grau 0 temos $0 = 0$

$$\text{enquanto o grau 1 dá} \quad -\varepsilon_+ + \bar{\partial} t_1 = -B^{-1} \varepsilon_+ B$$

(3.100)

Verifiquemos que (3.99) e (3.100) satisfazem à equação do movimento correta

$$\begin{aligned} \bar{\partial} (B^{-1} \partial B) &\stackrel{(1)}{=} [\varepsilon_-, \bar{\partial} t_1] + 2 \stackrel{(2)}{=} [\varepsilon_-, -B^{-1} \varepsilon_+ B + \varepsilon_+] + 2 \\ &= -[\varepsilon_-, B^{-1} \varepsilon_+ B] + [\varepsilon_-, \varepsilon_+] + 2 \\ &= -[\varepsilon_-, B^{-1} \varepsilon_+ B] \text{ pois } [\varepsilon_-, \varepsilon_+] = -2 \end{aligned}$$

Temos também :

$$A = \theta_-^{-1} A_{vac} \theta_- = \theta_-^{-1} (\partial \theta_-) = \varepsilon_- + B^{-1} \partial B$$

$$\bar{A} = \theta_-^{-1} \bar{A}_{vac} \theta_- + \theta_-^{-1} (\bar{\partial} \theta_-) = -B^{-1} \varepsilon_+ B$$

com

$$\theta_- = \tilde{\theta}_o \theta_< \quad \text{e} \quad \theta_< = e^{t^{(-1)}+t^{(-2)}}$$

onde $t^{(-i)}$ é construído com geradores de graus negativos $(-i)$, $(i > 0)$

Reescrevemos

$$\begin{aligned} A &= \theta_<^{-1} \tilde{\theta}_o^{-1} (\varepsilon_- + 2 \bar{z}) \tilde{\theta}_o \theta_< + \theta_<^{-1} \tilde{\theta}_o^{-1} \partial \tilde{\theta}_o \theta_< + \theta_<^{-1} \partial \theta_< \\ &= \varepsilon_- + B^{-1} \partial B \end{aligned}$$

Comparando os dois membros de grau zero obtemos:

$$2 \bar{z} + \tilde{\theta}_o^{-1} \partial \tilde{\theta}_o = B^{-1} \partial B$$

$$\text{ou} \quad \tilde{\theta}_o = B e^{-2z\bar{z}}$$

Comparando os dois membros de grau -1 temos

$$\varepsilon_- + [B^{-1}\partial B - 2\bar{z} c, t^{-1}] + \partial t^{-1} = \varepsilon_-$$

ou

$$[B^{-1}\partial B, t^{-1}] + \partial t^{-1} = 0$$

De maneira análoga temos

$$\bar{A} = \theta_{<}^{-1} \tilde{\theta}_0^{-1} (-\varepsilon_+) \tilde{\theta}_0 \theta_{<} + \theta_{<}^{-1} (\tilde{\theta}_0^{-1} \bar{\partial} \tilde{\theta}_0) + \theta_{<}^{-1} \bar{\partial} \theta_{<} = -B^{-1} \varepsilon_+ B$$

Comparando os dois membros de grau zero, temos:

$$[-B^{-1} \varepsilon_+ B, t^{-1}] + B^{-1} \bar{\partial} B - 2z = 0$$

Comparando os dois membros de grau 1

$$-B^{-1} \varepsilon_+ B = -B^{-1} \varepsilon_+ B$$

Escrevemos agora

$$(\partial + A_{vac}) \theta T = 0 \quad (\bar{\partial} + \bar{A}_{vac}) \theta T = 0$$

com T a determinar. Multipliquemos à esquerda por θ^{-1}

$$\theta^{-1}(\partial \theta T + \theta \partial T + A_{vac} \theta T) = 0$$

ou

$$(\theta^{-1} \partial \theta + \theta^{-1} A_{vac} \theta) T + \partial T = (\partial + A) T = 0$$

Considerando no lugar de θ as funções θ_+ e θ_- , temos:

$$\theta_+^{-1} (\partial + A_{vac}) \theta_+ T = 0 \rightarrow \theta_+ T = T_o^{-1}$$

$$\theta_-^{-1} (\partial + A_{vac}) \theta_- T g^{-1} = 0 \rightarrow \theta_- T g^{-1} = T_o^{-1}$$

onde g é um elemento de grupo constante. Daí segue

$$T = \theta_+^{-1} T_o^{-1}$$

$$T = \theta_-^{-1} T_o^{-1} g$$

e portanto

$$\theta_- \theta_+^{-1} = T_o^{-1} g T_o$$

$$(\tilde{\theta}_o \theta_{<}^{-1}) (\theta_o \theta_{>}^{-1}) = T_o^{-1} g T_o$$

ou

$$\theta_{<}^{-1} B e^{-2z\bar{z}} \theta_{>}^{-1} = T_o^{-1} g T_o$$

com $\theta_o = 1$ e T_o^{-1} solução do vácuo, isto é

$$(\partial + A_{vac}) T_o^{-1} = 0 \quad (\bar{\partial} + \bar{A}_{vac}) T_o^{-1} = 0$$

Temos para o estado de peso mais alto $|\lambda_i\rangle$

$$\theta_{>} |\lambda_i\rangle = 0$$

e portanto

$$\theta_{<}^{-1} B e^{-2z\bar{z}} |\lambda_i\rangle = T_o^{-1} g T_o |\lambda_i\rangle .$$

1^o) Projeção em $|0\rangle$:

$$\langle 0 | e^{-2z\bar{z} + \nu \hat{c}} | 0 \rangle = \langle 0 | T_o^{-1} g T_o | 0 \rangle = e^{-2z\bar{z} + \nu}$$

2^o) Projeção em $|\lambda_i\rangle$ com $i = 1, 3$

$$= \langle \lambda_i | e^{\chi(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{\lambda_2 H \varphi + (h_1 + h_3) R + \nu c} e^{\psi(E_{\alpha_1}^0 + E_{\alpha_3}^0)} | \lambda_i \rangle = e^{\lambda_2 \lambda_i \varphi + R - 2z\bar{z} + \nu}$$

$$= \langle \lambda_i | T_o^{-1} g T_o | \lambda_i \rangle \quad i=1,3$$

$$\begin{aligned}
3) & \langle \lambda_i | e^{\chi(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{\lambda_2 H \varphi + \nu c + (h_1 + h_3)R - 2z\bar{z}} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_i \rangle \\
& = e^{\lambda_i \lambda_2 \varphi + \nu + R - 2z\bar{z}} \langle \lambda_i | (1 + \psi (E_{\alpha_1}^0 + E_{\alpha_3}^0)) (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_i \rangle \\
& = \psi e^{\lambda_i \lambda_2 \varphi + \nu + R - 2z\bar{z}} \langle \lambda_i | h_1 + h_3 | \lambda_i \rangle = \psi e^{\lambda_i \lambda_2 \varphi + \nu - 2z\bar{z} + R}
\end{aligned}$$

para $i = 1$ ou 3

Por sua vez esta expressão é igual a:

$$\langle \lambda_i | T_o^{-1} g T_o (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_i \rangle \quad i=1,3$$

$$\begin{aligned}
4) & \langle \lambda_i | (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) e^{\chi(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{\lambda_2 H \varphi + (h_1 + h_3)R - 2z\bar{z} + \nu c} | \lambda_i \rangle \\
& = e^{\lambda_i \lambda_2 \varphi + \nu + R - 2z\bar{z}} \langle \lambda_i | (E_{\alpha_1}^0 + E_{\alpha_3}^0) (1 + \chi (E_{-\alpha_1}^0 + E_{-\alpha_3}^0)) | \lambda_i \rangle \\
& = \chi e^{\lambda_i \lambda_2 \varphi + \nu + R - 2z\bar{z}} \langle \lambda_i | h_1 + h_3 | \lambda_i \rangle \\
& = \langle \lambda_i | (E_{\alpha_1}^0 + E_{\alpha_3}^0) T_o^{-1} g T_o | \lambda_i \rangle \quad \text{para } i=1,3
\end{aligned}$$

Tomemos a autofunção F de ε_{\pm} :

$$[\varepsilon_{\pm}, F] = w_{\pm} F$$

Então considerando $g = e^{aF}$ (a constante), $T_o^{-1} g T_o = e^{aF e^{w_+ \bar{z} - w_- z}}$

Resumindo podemos escrever

$$\tau_0 = e^{\nu - 2z\bar{z}} = \langle 0 | T^{-1} g T | 0 \rangle$$

$$\tau_1 = e^{\lambda_1 \lambda_2 \varphi + \nu - 2z\bar{z} + R} = \langle \lambda_1 | T^{-1} g T | \lambda_1 \rangle$$

$$\tau_2 = e^{\lambda_2^2 \varphi + \nu - 2z\bar{z}} = \langle \lambda_2 | T^{-1} g T | \lambda_2 \rangle$$

$$\tau_{\psi} = \psi \tau_1 = \psi e^{\lambda_1 \lambda_2 \varphi + \nu - 2z\bar{z} + R} = \langle \lambda_1 | T^{-1} g T (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_1 \rangle$$

$$\tau_{\chi} = \chi \tau_1 = \chi e^{\lambda_1 \lambda_2 \varphi + \nu - 2z\bar{z} + R} = \langle \lambda_1 | (E_{\alpha_1}^0 + E_{\alpha_3}^0) T^{-1} g T | \lambda_1 \rangle \quad (3.101)$$

As equações de movimento em termos das funções tau escrevem-se

$$\tau_1^2 \tau_0^2 \tau_2 \partial \bar{\partial} \tau_2 - \tau_1^2 \tau_0 \tau_2^2 \partial \bar{\partial} \tau_0 + \tau_1^2 \partial \tau_0 \tau_2^2 \bar{\partial} \tau_0 - \tau_1^2 \partial \tau_2 \tau_0^2 \bar{\partial} \tau_2 - 2\tau_0^3 \tau_2 \tau_1^2 - 4\tau_0^3 \tau_2 \tau_{\chi} \tau_{\psi} + 2\tau_2^3 \tau_0 \tau_1^2 + 4\tau_2^3 \tau_0 \tau_{\chi} \tau_{\psi} = 0$$

$$2\tau_1^2 \tau_0^2 + \tau_1^2 \tau_0 \partial \bar{\partial} \tau_0 - \tau_1^2 \partial \tau_0 \bar{\partial} \tau_0 - 2\tau_1^2 \tau_0 \tau_2 - 4\tau_0 \tau_2 \tau_{\chi} \tau_{\psi} = 0$$

$$\begin{aligned}
& \tau_1^4 \tau_2 \tau_0 \partial \bar{\partial} \tau_{\chi} - \tau_1^3 \tau_2 \tau_0 \bar{\partial} \tau_{\chi} \partial \tau_1 - \tau_1^3 \tau_2 \tau_0 \partial \tau_{\chi} \bar{\partial} \tau_1 - \tau_1^3 \tau_2 \tau_0 \tau_{\chi} \partial \bar{\partial} \tau_1 + 2\tau_1^2 \tau_2 \tau_0 \partial \tau_1 \tau_{\chi} \bar{\partial} \tau_1 + \\
& + \tau_1 \tau_2 \tau_0 \tau_{\chi}^2 \tau_{\psi} \bar{\partial} \partial \tau_1 + \tau_1^2 \tau_2 \tau_0 \tau_{\chi} \tau_{\psi} \partial \bar{\partial} \tau_{\chi} + \tau_2 \tau_0 \tau_{\chi}^2 \tau_{\psi} \partial \tau_1 \bar{\partial} \tau_1 - \tau_1^2 \tau_2 \tau_0 \tau_{\psi} \partial \tau_{\chi} \bar{\partial} \tau_{\chi} + \\
& + 2\tau_1^4 \tau_2^2 \tau_{\chi} + 2\tau_1^4 \tau_0^2 \tau_{\chi} + 4\tau_1^2 \tau_2^2 \tau_{\chi}^2 \tau_{\psi} + 4\tau_1^2 \tau_0^2 \tau_{\chi}^2 \tau_{\psi} + 2\tau_2^2 \tau_{\chi}^3 \tau_{\psi}^2 + 2\tau_0^2 \tau_{\chi}^3 \tau_{\psi}^2 = 0
\end{aligned}$$

$$\begin{aligned}
& \tau_1^4 \tau_2 \tau_0 \partial \bar{\partial} \tau_{\psi} - \tau_1^3 \tau_2 \tau_0 \bar{\partial} \tau_{\psi} \partial \tau_1 - \tau_1^3 \tau_2 \tau_0 \partial \tau_{\psi} \bar{\partial} \tau_1 - \tau_1^3 \tau_2 \tau_0 \tau_{\psi} \partial \bar{\partial} \tau_1 + 2\tau_1^2 \tau_2 \tau_0 \partial \tau_1 \tau_{\psi} \bar{\partial} \tau_1 + \\
& + \tau_1 \tau_2 \tau_0 \tau_{\chi}^2 \tau_{\psi}^2 \bar{\partial} \partial \tau_1 + \tau_1^2 \tau_2 \tau_0 \tau_{\chi} \tau_{\psi} \partial \bar{\partial} \tau_{\psi} + \tau_2 \tau_0 \tau_{\chi}^2 \tau_{\psi}^2 \partial \tau_1 \bar{\partial} \tau_1 - \tau_1^2 \tau_2 \tau_0 \tau_{\chi} \partial \tau_{\psi} \bar{\partial} \tau_{\psi} +
\end{aligned}$$

$$+2\tau_1^4\tau_2^2\tau_\psi + 2\tau_1^4\tau_0^2\tau_\psi + 4\tau_1^2\tau_2^2\tau_\psi^2\tau_\chi + 4\tau_1^2\tau_0^2\tau_\psi^2\tau_\chi + 2\tau_2^2\tau_\psi^3\tau_\chi^2 + 2\tau_0^2\tau_\psi^3\tau_\chi^2 = 0$$

$$\partial\tau_1\tau_2\tau_0\tau_1^2 + 2\partial\tau_1\tau_2\tau_0\tau_\chi\tau_\psi - \frac{1}{2}\tau_1^3\partial\tau_2\tau_0 - \frac{1}{2}\tau_1\partial\tau_2\tau_0\tau_\chi\tau_\psi +$$

$$-\frac{1}{2}\tau_1^3\tau_2\partial\tau_0 - \frac{1}{2}\tau_1\tau_2\partial\tau_0\tau_\chi\tau_\psi - \tau_\psi\tau_2\tau_0\partial\tau_\chi\tau_1 = 0$$

(3.102)

3.9 Solução de um Vértice

Considere $g=e^{aF_4^+(\gamma)}$ com $F_4^+(\gamma)$ dado na expressão (3.93).

Então: $T_o^{-1}gT_o=e^{a\rho F_4^+(\gamma)}$ com $\rho=e^{2\gamma\bar{z}-\frac{2}{\gamma}z}$

Façamos a expansão até a 2ª ordem:

$$e^{a\rho F_4^+(\gamma)}=1+a\rho F_4^+(\gamma)+\frac{a^2\rho^2}{2!}\left(F_4^+(\gamma)\right)^2$$

Temos

$$\langle \lambda_i | e^{a\rho F_4^+(\gamma)} | \lambda_i \rangle = 1 + a\rho \langle \lambda_i | F_4^+(\gamma) | \lambda_i \rangle + \frac{a^2\rho^2}{2!} \langle \lambda_i | \left(F_4^+(\gamma)\right)^2 | \lambda_i \rangle \quad (3.103)$$

com $i=0,1,2$. Utilizando $F_4^+(\gamma)$ da expressão (3.93) temos:

$$\langle \lambda_i | \left(F_4^+(\gamma)\right)^2 | \lambda_i \rangle = \langle \lambda_i | \left\{ \sum_{n \geq 0, m \leq 0} [I_{m,n}] \gamma^{-2(m+n)} + 1 \right\} | \lambda_i \rangle \quad (3.104)$$

$$\text{onde } I_{m,n} = h_1^n h_1^m + h_3^n h_3^m + 4h_2^n h_2^m + 4h_1^n h_2^m + 4h_2^n h_3^m - E_{\alpha_1+\alpha_2}^n E_{-\alpha_1-\alpha_2}^m + \\ - E_{-\alpha_1-\alpha_2}^n E_{\alpha_1+\alpha_2}^m - E_{\alpha_2+\alpha_3}^n E_{-\alpha_2-\alpha_3}^m - E_{-\alpha_2-\alpha_3}^n E_{\alpha_2+\alpha_3}^m - 2h_1 - 4h_2 - 2h_3$$

Podemos substituir os diferentes produtos de operadores pelos seus comutadores e usar

$$[h_1^n, h_1^m] = [h_3^n, h_3^m] = [h_2^n, h_2^m] = 2n \delta_{n+m,0}$$

$$[h_1^n, h_2^m] = [h_2^n, h_3^m] = -n \delta_{n+m,0}$$

$$\left[E_{\alpha_1+\alpha_2}^n, E_{-\alpha_1-\alpha_2}^m \right] = h_1^{n+m} + h_2^{n+m} + n \delta_{n+m,0}$$

$$\left[E_{\alpha_2+\alpha_3}^n, E_{-\alpha_2-\alpha_3}^m \right] = h_2^{n+m} + h_3^{n+m} + n \delta_{n+m,0}$$

Neste caso a equação (3.104) reduz-se a:

$$\langle \lambda_0 | \left(F_4^+(\gamma)\right)^2 | \lambda_0 \rangle = \langle \lambda_0 | \left\{ \sum_{n>0} (2n + 2n + 8n - 4n - 4n - 4n) + 1 \right\} | \lambda_0 \rangle$$

$$\langle \lambda_1 | \left(F_4^+(\gamma)\right)^2 | \lambda_1 \rangle = 0$$

$$\langle \lambda_2 | \left(F_4^+(\gamma)\right)^2 | \lambda_2 \rangle = 1$$

$$\langle \lambda_0 | F_4^+(\gamma) | \lambda_0 \rangle = -1$$

$$\langle \lambda_1 | F_4^+(\gamma) | \lambda_1 \rangle = 0$$

$$\langle \lambda_2 | F_4^+(\gamma) | \lambda_2 \rangle = 1$$

Daí segue

$$\tau_0 = \langle \lambda_0 | T_o^{-1}gT_o | \lambda_0 \rangle = e^{\nu-2z\bar{z}} = 1 - a\rho(\gamma) + \frac{a^2}{2!}\rho^2(\gamma)$$

$$\tau_1 = \langle \lambda_1 | T_o^{-1}gT_o | \lambda_1 \rangle = 1 = e^{\frac{1}{2}\varphi + R-2z\bar{z}+\nu}$$

$$\tau_2 = \langle \lambda_2 | T_o^{-1}gT_o | \lambda_2 \rangle = 1 + a\rho(\gamma) + \frac{a^2}{2!}\rho^2(\gamma) = e^{\varphi+\nu-2z\bar{z}}$$

$$\chi = \psi = 0 \rightarrow R = \text{constante}$$

De $\tau_1 = 1$ segue : $\varphi = -2(\nu - 2z\bar{z}) - 2R$, que introduzida em τ_2 dá

$$e^{-2(\nu-2z\bar{z})-2R} = 1 + a\rho(\gamma) + \frac{a^2}{2!}\rho^2(\gamma)$$

ou:

$$e^{-2R} = \left(1 + a\rho(\gamma) + \frac{a^2}{2!}\rho^2(\gamma)\right) \left(1 - a\rho(\gamma) + \frac{a^2}{2!}\rho^2(\gamma)\right)$$

dando R não constante que é uma contradição.

A fim de evitarnos este problema escrevamos:

$$\begin{aligned}
\langle \lambda_i | (F_4^+(\gamma))^2 | \lambda_i \rangle &= \lim_{\gamma_1 \rightarrow \gamma_2 = \gamma} \langle \lambda_i | F_4^+(\gamma_1) F_4^+(\gamma_2) | \lambda_i \rangle = \\
&= \langle \lambda_i | \sum_{n \geq 0, m \leq 0} [h_1^n h_1^m + h_3^n h_3^m + 4h_2^n h_2^m + 4h_1^n h_2^m + 4h_2^n h_3^m] \gamma_1^{-2n} \gamma_2^{-2m} + \\
&\quad - \left[E_{\alpha_1 + \alpha_2}^n E_{-\alpha_1 - \alpha_2}^m + E_{\alpha_2 + \alpha_3}^n E_{-\alpha_2 - \alpha_3}^m \right] \gamma_1^{-(2n+1)} \gamma_2^{-(2m-1)} + \\
&\quad - \left[E_{-\alpha_1 - \alpha_2}^n E_{\alpha_1 + \alpha_2}^m + E_{-\alpha_2 - \alpha_3}^n E_{\alpha_2 + \alpha_3}^m \right] \gamma_1^{-(2n-1)} \gamma_2^{-(2m+1)} + 1 | \lambda_i \rangle
\end{aligned}$$

Substituindo os diferentes produtos de operadores pelos seus comutadores segue

$$\begin{aligned}
&\lim_{\gamma_1 \rightarrow \gamma_2 = \gamma} \langle \lambda_0 | F_4^+(\gamma_1) F_4^+(\gamma_2) | \lambda_0 \rangle = \\
&= \lim_{\gamma_1 \rightarrow \gamma_2} \sum_{n > 0} 4n \left(\frac{\gamma_2}{\gamma_1} \right)^{2n} - \sum_{n > 0} 2 \left(\frac{\gamma_2}{\gamma_1} + \frac{\gamma_1}{\gamma_2} \right) \left(\frac{\gamma_2}{\gamma_1} \right)^{2n} n \\
&= \lim_{\gamma_1 \rightarrow \gamma_2} \sum_{n > 0} \left(4 - 2 \frac{\gamma_2}{\gamma_1} - 2 \frac{\gamma_1}{\gamma_2} \right) \left(\frac{\gamma_2}{\gamma_1} \right)^{2n} n = \lim_{\gamma_1 \rightarrow \gamma_2} 2 \left(2 - \frac{\gamma_2}{\gamma_1} - \frac{\gamma_1}{\gamma_2} \right) \frac{\left(\frac{\gamma_2}{\gamma_1} \right)^2}{\left[1 - \left(\frac{\gamma_2}{\gamma_1} \right)^2 \right]^2} \\
&= \lim_{\gamma_1 \rightarrow \gamma_2} \frac{2}{\gamma_1 \gamma_2} \frac{(2\gamma_1 \gamma_2 - \gamma_2^2 - \gamma_1^2) \left(\frac{\gamma_2}{\gamma_1} \right)^2}{\left[1 - \left(\frac{\gamma_2}{\gamma_1} \right)^2 \right]^2} = \lim_{\gamma_1 \rightarrow \gamma_2} - \frac{2}{\gamma_1 \gamma_2} \frac{(\gamma_1 - \gamma_2)^2 \left(\frac{\gamma_2}{\gamma_1} \right)^2}{\left[1 - \frac{\gamma_2}{\gamma_1} \right]^2 \left[1 + \frac{\gamma_2}{\gamma_1} \right]^2} = \\
&\lim_{\gamma_1 \rightarrow \gamma_2} - \frac{2}{\left(\frac{\gamma_2}{\gamma_1} \right) \left[1 + \frac{\gamma_2}{\gamma_1} \right]^2} = - \frac{1}{2}
\end{aligned}$$

Daí segue

$$\begin{aligned}
\langle \lambda_0 | (F_4^+(\gamma))^2 | \lambda_0 \rangle &= \frac{1}{2} \\
\langle \lambda_1 | (F_4^+(\gamma))^2 | \lambda_1 \rangle &= -\frac{1}{2} \\
\langle \lambda_2 | (F_4^+(\gamma))^2 | \lambda_2 \rangle &= \frac{1}{2}
\end{aligned}$$

e portanto

$$\begin{aligned}
e^{\nu - 2z\bar{z}} &= 1 - a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma) \\
e^{\frac{1}{2}\varphi + R - 2z\bar{z} + \nu} &= 1 - \frac{a^2}{4}\rho^2(\gamma) \\
e^{\varphi - z\bar{z} + \nu} &= 1 + a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)
\end{aligned} \tag{3.105}$$

Daí segue

$$e^\varphi = \frac{1 + a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)}{1 - a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)} \tag{3.106}$$

Também

$$\begin{aligned}
e^R &= \frac{\left(1 - \frac{a^2}{4}\rho^2(\gamma) \right) \sqrt{1 - a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)}}{\left(1 - a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma) \right) \sqrt{1 + a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)}} = \frac{\left(1 - \frac{a^2}{4}\rho^2(\gamma) \right)}{\sqrt{1 - a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)} \sqrt{1 + a\rho(\gamma) + \frac{a^2}{4}\rho^2(\gamma)}} \\
e^R &= \frac{\left(1 - \frac{a^2}{4}\rho^2(\gamma) \right)}{\sqrt{(1 + a\rho(\gamma))^2 - a^2\rho^2(\gamma)}} = 1
\end{aligned}$$

e portanto $R=0$ e consistente com $\chi = \psi = 0$

3.10 Solução com 2 vértices

Tomemos $g = e^{a_1 F_1^+(\gamma_1)} e^{a_2 F_2^-(\gamma_2)}$, Então:

$$T^{-1}gT = e^{a_1 \rho_1^+ F_1^+(\gamma_1)} e^{a_2 \rho_2^- F_2^-(\gamma_2)}$$

$$\text{com } \rho_1^+ = e^{2\gamma_1 \bar{z} - \frac{2}{\gamma_1} z} \quad \rho_2^- = e^{-2\gamma_2 \bar{z} + \frac{2}{\gamma_2} z}$$

Calculemos τ , expandindo $e^{a_1 \rho_1^+ F_1^+(\gamma_1)}$ e $e^{a_2 \rho_2^- F_2^-(\gamma_2)}$ até 1ª ordem cada um deles.

Segue então utilizando as expressões

$$\begin{aligned} & \langle \lambda_i | F_1^+(\gamma_1) F_2^-(\gamma_2) | \lambda_i \rangle = \\ & \langle \lambda_i | \sum_{n \geq 0, m \leq 0} (h_1^{m+n} + n \delta_{m+n,0}) \gamma_1^{-2n} \gamma_2^{-2m} \\ & \quad + \sum_{n \geq 0, m \leq 0} (h_1^{m+n} + h_2^{m+n} + h_3^{m+n} + n \delta_{m+n,0}) \gamma_1^{-(2n+1)} \gamma_2^{-(2m-1)} \\ & \quad + \sum_{n > 0, m < 0} (-h_2^{m+n} + n \delta_{m+n,0}) \gamma_1^{-(2n-1)} \gamma_2^{-(2m+1)} \\ & \quad + \sum_{n \geq 0, m \leq 0} (h_3^{m+n} + n \delta_{m+n,0}) \gamma_1^{-2n} \gamma_2^{-2m} | \lambda_i \rangle \end{aligned}$$

onde $|\lambda_i\rangle$ pode ser $|\lambda_0\rangle, |\lambda_1\rangle, |\lambda_2\rangle, |\lambda_3\rangle, \text{ etc.}$

Por tanto

$$\begin{aligned} & \langle \lambda_0 | F_1^+(\gamma_1) F_2^-(\gamma_2) | \lambda_0 \rangle \\ & = \sum_{n=0}^{\infty} n \left(\frac{\gamma_2}{\gamma_1}\right)^{2n} + \sum_{n=0}^{\infty} n \frac{\gamma_2}{\gamma_1} \left(\frac{\gamma_2}{\gamma_1}\right)^{2n} + \sum_{n=1}^{\infty} n \frac{\gamma_1}{\gamma_2} \left(\frac{\gamma_2}{\gamma_1}\right)^{2n} + \sum_{n=0}^{\infty} n \left(\frac{\gamma_2}{\gamma_1}\right)^{2n} \\ & = \left(2 + \frac{\gamma_2}{\gamma_1} + \frac{\gamma_1}{\gamma_2}\right) \sum_{n=0}^{\infty} n \left(\frac{\gamma_2}{\gamma_1}\right)^{2n} \end{aligned}$$

$$\text{Utilizando } x^n = \sum_{n=0}^{\infty} \frac{1}{1-x}, \quad x \frac{\partial}{\partial x} \sum_{n=0}^{\infty} x^n = \sum_{n=0}^{\infty} n x^n = \frac{x}{(1-x)^2}$$

$$\text{Segue-se } \sum_{n=0}^{\infty} n \left(\frac{\gamma_2}{\gamma_1}\right)^n = \frac{\gamma_1^2 \gamma_2^2}{(\gamma_1 - \gamma_2)^2}$$

e portanto:

$$\langle \lambda_0 | F_1^+(\gamma_1) F_2^-(\gamma_2) | \lambda_0 \rangle = \frac{\gamma_1 \gamma_2}{(\gamma_1 - \gamma_2)^2}$$

Da mesma maneira segue-se

$$\begin{aligned} \langle \lambda_1 | F_1^+(\gamma_1) F_2^-(\gamma_2) | \lambda_1 \rangle & = \frac{\gamma_1^2}{(\gamma_1 - \gamma_2)^2} \\ \langle \lambda_2 | F_1^+(\gamma_1) F_2^-(\gamma_2) | \lambda_2 \rangle & = \frac{\gamma_1 \gamma_2}{(\gamma_1 - \gamma_2)^2} \end{aligned}$$

Portanto segue

$$e^{\nu - 2z\bar{z}} = \langle \lambda_0 | T_o^{-1} g T_o | \lambda_0 \rangle = 1 + a_1 a_2 \rho_1^+ \rho_2^- \frac{\gamma_1 \gamma_2}{(\gamma_1 - \gamma_2)^2} \quad (3.107)$$

$$e^{\varphi - 2z\bar{z} + \nu} = e^{\nu - 2z\bar{z}} \quad (3.108)$$

e portanto $\varphi = 0$

Também segue:

$$e^{\frac{1}{2}\varphi + R - z\bar{z} + \nu} = 1 + a_1 a_2 \rho_1^+ \rho_2^- \frac{\gamma_1^2}{(\gamma_1 - \gamma_2)^2} \quad (3.109)$$

Temos tambem

$$\begin{aligned}
& \langle \lambda_1 | T_o^{-1} g T_o (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_1 \rangle \\
&= a_1 \langle \lambda_1 | F_1^+ (\gamma_1) \rho_1^+ (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) | \lambda_1 \rangle \\
&= a_1 \rho_1^+ \langle \lambda_1 | \sum_{n=0}^{\infty} E_{\alpha_1}^n \gamma_1^{-2n} E_{-\alpha_1}^0 + \sum_{n=0}^{\infty} E_{\alpha_3}^n \gamma_1^{-2n} E_{-\alpha_3}^0 | \lambda_1 \rangle \\
&= a_1 \rho_1^+ \langle \lambda_1 | \sum_{n=0}^{\infty} (h_1^n \gamma_1^{-2n} + h_3^n \gamma_1^{-2n}) | \lambda_1 \rangle = a_1 \rho_1^+
\end{aligned}$$

Portanto

$$\psi = \frac{a_1 \rho_1^+}{1 + a_1 a_2 \rho_1^+ \rho_2^- \frac{\gamma_1^2}{(\gamma_1 - \gamma_2)^2}} \quad (3.110)$$

Da mesma maneira considerando:

$$\begin{aligned}
& \langle \lambda_1 | (E_{\alpha_1}^0 + E_{\alpha_3}^0) T_o^{-1} g T_o | \lambda_1 \rangle = \\
& a_2 \rho_2^- \langle \lambda_1 | E_{\alpha_1}^0 \sum_{n=0}^{\infty} E_{-\alpha_1}^n \gamma_2^{-2n} | \lambda_1 \rangle = a_2 \rho_2^-
\end{aligned}$$

Portanto

$$\chi = \frac{a_2 \rho_2^-}{1 + a_1 a_2 \rho_1^+ \rho_2^- \frac{\gamma_1^2}{(\gamma_1 - \gamma_2)^2}} \quad (3.111)$$

Pode-se mostrar que (3.107)-(3.111) são soluções das equações (3.102) até a segunda ordem em ρ .

Entretanto não são soluções em ordem superior.

4 Capítulo 4

4.1 Conclusões

4.2

De acordo com sugestão do professor L.A.Ferreira, podemos utilizar o método de Hirota para expandir as funções tau em series de potencias de exponenciais que dão o comportamento espaço temporal dos elementos de matriz

$$\langle \lambda_i | T_o^{-1} g T_o | \lambda_i \rangle$$

Introduzindo nas equações (3.102) podemos resolve-las utilizando o programa de " Matemática ".

No caso das soluções de um vértice obtivemos como resultado as expressões (3.105), já obtidas analiticamente. Além disso obtivemos também soluções com $\chi = 0, \psi \neq 0, \varphi \neq 0$, ou $\chi \neq 0, \psi = 0, \varphi \neq 0$.

No caso de soluções com dois vértices, τ_0, τ_1 e τ_2 são expandidas até segunda ordem nas exponenciais enquanto que τ_χ e τ_ψ são expandidas até primeira ordem. Entretanto eles não são soluções de (3.102) em ordem superior.

Ao tomarmos expansões nas exponenciais em ordem superior para as funções tau, mais explicitamente, até quarta ordem, chegamos por cálculo computacional, à conclusão que τ_0, τ_1 e τ_2 truncam até segunda ordem enquanto que τ_χ e τ_ψ não. Por exemplo obtivemos :

$$\tau_0 = 1 + a_1 a_2 \frac{e^{2\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 2\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_1 \gamma_2}{(\gamma_1 - \gamma_2)^2} \quad (4.1)$$

$$\tau_2 = \tau_0 \quad (4.2)$$

$$\tau_1 = 1 + a_1 a_2 \frac{e^{2\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 2\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_2^2}{(\gamma_1 - \gamma_2)^2} \quad (4.3)$$

$$\begin{aligned} \tau_\chi = a_2 e^{-2\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} - a_1 a_2^2 \frac{e^{2\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 4\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_2}{(\gamma_1 - \gamma_2)} + \\ + a_1^2 a_2^3 \frac{e^{4\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 6\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_1 \gamma_2^2}{(\gamma_1 - \gamma_2)^3} \end{aligned} \quad (4.4)$$

$$\begin{aligned} \tau_\psi = a_1 e^{-2\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right)} - a_1^2 a_2 \frac{e^{4\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 2\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_2}{(\gamma_1 - \gamma_2)} + \\ + a_1^3 a_2^2 \frac{e^{6\left(-\frac{\bar{x}}{\gamma_1} + z \gamma_1\right) - 4\left(-\frac{\bar{x}}{\gamma_2} + z \gamma_2\right)} \gamma_1 \gamma_2^2}{(\gamma_1 - \gamma_2)^3} \end{aligned} \quad (4.5)$$

Entretanto estas não são soluções das equações (3.102).

Indo para ordens superiores verificamos que τ_0, τ_1 e τ_2 permanecem inalteradas e que τ_χ e τ_ψ recebem contribuições adicionais. Constatamos uma regularidade: cada termo da série que comparece em τ_χ e τ_ψ é obtido do anterior pela multiplicação do fator:

$$-a_1 a_2 \frac{(\gamma_1 \gamma_2) e^{-2\left(-\frac{z}{\gamma_2} + z \gamma_2\right)} e^{2\left(-\frac{z}{\gamma_1} + z \gamma_1\right)}}{(\gamma_1 - \gamma_2)^3} \quad (4.6)$$

Dessa maneira τ_χ e τ_ψ não são truncados e são expressos por meio de séries infinitas. Podemos soma-las obtendo:

$$\tau_\chi = \frac{a_2 e^{-2\left(-\frac{z}{\gamma_2} + z \gamma_2\right)} (\gamma_1 - \gamma_2 + \gamma_2 \tau_0)}{\gamma_1 \tau_0} \quad (4.7)$$

$$\tau_\psi = \frac{a_1 e^{-2\left(-\frac{z}{\gamma_1} + z \gamma_1\right)} (\gamma_1 - \gamma_2 + \gamma_2 \tau_0)}{\gamma_1 \tau_0} \quad (4.8)$$

Mostra-se que (4.1), (4.2), (4.3), (4.4), (4.5) verificam as equações (3.102) e portanto dão $\psi \neq 0, \chi \neq 0$ e $\varphi = 0$.

O passo seguinte é o de construir as soluções de tres e mais vértices.

5 Apêndice A.

5.1 Cálculo de $B^{-1}(\partial B)$.

Indiquemos $h = h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3$, $h' = h_1 + h_3$

$$B = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad (\text{A.1})$$

Seja

$$n = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}, \quad a = e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d}, \quad m = e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)}$$

isto é $B = nam$ ou $B^{-1} = m^{-1}a^{-1}n^{-1}$

Seja $I = B^{-1}(\partial B)$

$$I = m^{-1}a^{-1}n^{-1}(\partial n)am + m^{-1}a^{-1}(\partial a)m + m^{-1}(\partial m)$$

$$m^{-1}(\partial m) = (\partial \tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0)$$

$$n^{-1}(\partial n) = (\partial \tilde{\chi})(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)$$

$$a^{-1}(\partial a) = \left[\left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial \varphi + (h_1 + h_3) \partial R + (\partial \nu) c + (\partial \eta) d \right]$$

Usando estas tres ultimas expresiones

$$\begin{aligned} I &= (\partial \tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0) + \\ &\left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial \varphi + \\ &(\partial R) e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} (h_1 + h_3) e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} + (\partial \nu) c + (\partial \eta) d + \\ &(\partial \tilde{\chi}) e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} e^{-(h_1 + h_3)R} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) e^{(h_1 + h_3)R} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \end{aligned}$$

Seja

$$M = e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} (h_1 + h_3) e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad e \quad N = e^{-(h_1 + h_3)R} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) e^{(h_1 + h_3)R}$$

$$I = (\partial \tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0) + \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial \varphi +$$

$$(\partial R) M + (\partial \nu) c + (\partial \eta) d + (\partial \tilde{\chi}) e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} N e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)}$$

(A.3)

pode-se verificar que

$$M = e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} (h_1 + h_3) e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} = h' + 2\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0) \quad (\text{A.4})$$

$$N = e^{-(h_1 + h_3)R} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) e^{(h_1 + h_3)R} = e^{2R} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) \quad (\text{A.5})$$

substituindo (A.4) e (A.5) em (A.3)

$$\begin{aligned}
 I &= (\partial\tilde{\psi}) (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \\
 & \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial\varphi + (\partial R) (h' + 2\tilde{\psi} (E_{\alpha 1}^0 + E_{\alpha 3}^0)) + (\partial\nu) c + (\partial\eta) d + \\
 & (\partial\tilde{\chi}) e^{-\tilde{\psi}(E_{\alpha 1}^0 + E_{\alpha 3}^0)} e^{2R} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) e^{\tilde{\psi}(E_{\alpha 1}^0 + E_{\alpha 3}^0)}
 \end{aligned} \tag{A.6}$$

pode-se verificar que

$$\begin{aligned}
 e^{-\tilde{\psi}(E_{\alpha 1}^0 + E_{\alpha 3}^0)} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) e^{\tilde{\psi}(E_{\alpha 1}^0 + E_{\alpha 3}^0)} &= E_{-\alpha 1}^0 + E_{-\alpha 3}^0 - \tilde{\psi}h' - \tilde{\psi}^2 (E_{\alpha 1}^0 + E_{\alpha 3}^0) \\
 I &= (\partial\tilde{\psi}) (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \\
 & \left[\left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial\varphi + (\partial R) (h' + 2\tilde{\psi} (E_{\alpha 1}^0 + E_{\alpha 3}^0)) + (\partial\nu) c + (\partial\eta) d \right] + \\
 & (\partial\tilde{\chi}) e^{2R} \left[E_{-\alpha 1}^0 + E_{-\alpha 3}^0 - \tilde{\psi}h' - \tilde{\psi}^2 (E_{\alpha 1}^0 + E_{\alpha 3}^0) \right]
 \end{aligned} \tag{A.7}$$

$$I = \left[(\partial\tilde{\psi}) + 2\tilde{\psi} (\partial R) - \tilde{\psi}^2 (\partial\tilde{\chi}) e^{2R} \right] (E_{\alpha 1}^0 + E_{\alpha 3}^0) + (\partial\tilde{\chi}) e^{2R} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0)$$

$$+ \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \partial\varphi + (\partial R) (h') + (\partial\nu) c + (\partial\eta) d$$

fazendo as transformações $\tilde{\psi} = \psi e^{-R}$, $\tilde{\chi} = \chi e^{-R}$ temos

$$I = B^{-1} (\partial B) =$$

$$I = \left[(\partial\psi) + \psi (\partial R) + \psi^2 (\chi (\partial R) - \partial\chi) \right] (E_{\alpha 1}^0 + E_{\alpha 3}^0) +$$

$$\left[(1 + \chi\psi) (\partial R) - \psi\partial\chi \right] (h_1 + h_3) +$$

$$(\partial\chi - \chi\partial R) e^R (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) +$$

$$+ \partial\varphi \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) + (\partial\nu) c + (\partial\eta) d$$

Considerando o coeficiente em direção $(h_1 + h_3)$ igual a zero, isto é

$$(1 + \chi\psi) (\partial R) - \psi\partial\chi = 0, \text{ isto é } \partial R = \frac{\psi\partial\chi}{(1+\chi\psi)} \quad \text{finalmente temos}$$

$$B^{-1} (\partial B) |_{vinc} =$$

$$= (\partial\psi) e^{-R} (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \frac{\partial\chi}{\Delta} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0)$$

$$+ \partial\varphi \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) + (\partial\nu) c + (\partial\eta) d$$

(A.8)

6 Apêndice B.

6.1 Cálculo de $\bar{\partial}BB^{-1}$.

$$B = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad (\text{B.1})$$

$$\text{Seja } n = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} \quad a = e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} \quad m = e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad (\text{B.2})$$

$$(\bar{\partial}B) = \bar{\partial}(nam) = (\bar{\partial}n)am + n(\bar{\partial}a)m + na(\bar{\partial}m)$$

$$(\bar{\partial}m)m^{-1} = (\bar{\partial}\tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0)$$

$$(\bar{\partial}n)n^{-1} = (\bar{\partial}\tilde{\chi})(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)$$

$$(\bar{\partial}a)a^{-1} = \left[(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\bar{\partial}\varphi + (h_1 + h_3)\bar{\partial}R + (\bar{\partial}\nu)c + (\bar{\partial}\eta)d \right]$$

$$\text{Seja } J = (\bar{\partial}B)B^{-1}$$

$$J = \left[(\bar{\partial}n)n^{-1} + n(\bar{\partial}a)a^{-1}n^{-1} + na(\bar{\partial}m)m^{-1}a^{-1}n^{-1} \right]$$

$$= J1 + J2 + J3 \text{ onde}$$

$$J1 = (\bar{\partial}n)n^{-1} = (\bar{\partial}\tilde{\chi})(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)$$

$$J2 = n(\bar{\partial}a)a^{-1}n^{-1}$$

$$= e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} \left[(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\bar{\partial}\varphi + (h_1 + h_3)\bar{\partial}R + (\bar{\partial}\nu)c + (\bar{\partial}\eta)d \right] e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

$$J3 = na(\bar{\partial}m)m^{-1}a^{-1}n^{-1}$$

$$= e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} (\bar{\partial}\tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0)$$

$$e^{-(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi - (h_1 + h_3)R - \nu c - \eta d} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

$$J2 = (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\bar{\partial}\varphi + (\bar{\partial}R) \left[e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} (h_1 + h_3) e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} \right]$$

$$+ (\bar{\partial}\nu)c + (\bar{\partial}\eta)d$$

$$\text{Seja } M = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} (h_1 + h_3) e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

$$\text{usando } e^p b e^{-p} = b + [p, b] + \frac{1}{2!} [p, [p, b]] + \frac{1}{3!} [p, [p, [p, b]]] + \dots \text{ temos}$$

$$M = (h_1 + h_3) + \tilde{\chi}[(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (h_1 + h_3)] +$$

$$+ \frac{\tilde{\chi}^2}{2!} [(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), [(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (h_1 + h_3)]] + \dots$$

usando $[(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (h_1 + h_3)] = 2(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)$ temos

$$M = (h_1 + h_3) + \tilde{\chi}[2(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)] \\ + \frac{\tilde{\chi}^2}{2!} [(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), 2(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)] + \dots$$

$$\text{ou } M = (h_1 + h_3) + 2\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)$$

$$J_2 = (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3) \bar{\partial}\varphi \\ + (\bar{\partial}R) [(h_1 + h_3) + 2\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)] \\ + (\bar{\partial}\nu) c + (\bar{\partial}\eta) d$$

agora,

$$J_3 = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} \\ (\bar{\partial}\tilde{\psi})(E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{-(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi - (h_1 + h_3)R - \nu c - \eta d} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

simplificando temos

$$J_3 = (\bar{\partial}\tilde{\psi}) e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_1 + h_3)R} (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{-(h_1 + h_3)R} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} =$$

$$\text{Seja } N = e^{(h_1 + h_3)R} (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{-(h_1 + h_3)R}$$

$$\text{usando } e^p b e^{-p} = b + [p, b] + \frac{1}{2!} [p, [p, b]] + \frac{1}{3!} [p, [p, [p, b]]] + \dots$$

$$N = (E_{\alpha_1}^0 + E_{\alpha_3}^0) + [(h_1 + h_3)R, (E_{\alpha_1}^0 + E_{\alpha_3}^0)] \\ + \frac{1}{2!} [(h_1 + h_3)R, [(h_1 + h_3)R, (E_{\alpha_1}^0 + E_{\alpha_3}^0)]] + \dots$$

ordenando

$$N = (E_{\alpha_1}^0 + E_{\alpha_3}^0) + R [(h_1 + h_3), (E_{\alpha_1}^0 + E_{\alpha_3}^0)] \\ + \frac{(R)^2}{2!} [(h_1 + h_3), [(h_1 + h_3), (E_{\alpha_1}^0 + E_{\alpha_3}^0)]] + \dots$$

agora, usando $[h_1 + h_3, (E_{\alpha_1}^0 + E_{\alpha_3}^0)] = 2(E_{\alpha_1}^0 + E_{\alpha_3}^0)$ temos

$$N = (E_{\alpha_1}^0 + E_{\alpha_3}^0) + R [2(E_{\alpha_1}^0 + E_{\alpha_3}^0)] + \frac{(R)^2}{2!} [(h_1 + h_3), [2(E_{\alpha_1}^0 + E_{\alpha_3}^0)]] + \dots$$

$$= (E_{\alpha_1}^0 + E_{\alpha_3}^0) + R[2(E_{\alpha_1}^0 + E_{\alpha_3}^0)] + \frac{(R)^2}{2!} (2) [2(E_{\alpha_1}^0 + E_{\alpha_3}^0)] + \dots$$

$$= (E_{\alpha_1}^0 + E_{\alpha_3}^0) [1 + R(2) + \frac{(R)^2}{2!} (2)2 + \dots] = (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{2R}$$

$$N = (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{2R}$$

$$J_3 = (\bar{\partial}\tilde{\psi}) e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{2R} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

$$J_3 = e^{2R} (\bar{\partial}\tilde{\psi}) e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} (E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

$$\text{seja } P = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} [(E_{\alpha_1}^0 + E_{\alpha_3}^0) e^{-2R}] e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} =$$

usando $e^p b e^{-p} = b + [p, b] + \frac{1}{2!} [p, [p, b]] + \frac{1}{3!} [p, [p, [p, b]]] + \dots$ temos

$$P = (E_{\alpha_1}^0 + E_{\alpha_3}^0) + [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (E_{\alpha_1}^0 + E_{\alpha_3}^0)]$$

$$+ \frac{1}{2!} [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (E_{\alpha_1}^0 + E_{\alpha_3}^0)]] + \dots$$

$$+ \frac{1}{3!} [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), [\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), (E_{\alpha_1}^0 + E_{\alpha_3}^0)]]] + \dots$$

usando $[(E_{\alpha_1}^0 + E_{\alpha_3}^0), (E_{-\alpha_1}^0 + E_{-\alpha_3}^0)] = h_1 + h_3$ temos

$$P = (E_{\alpha_1}^0 + E_{\alpha_3}^0) + \tilde{\chi} [-h_1 - h_3] + \frac{(\tilde{\chi})^2}{2!} [(E_{-\alpha_1}^0 + E_{-\alpha_3}^0), [-h_1 - h_3]]$$

$$+\frac{(\tilde{\chi})^3}{3!} \left[(E_{-\alpha 1}^0 + E_{-\alpha 3}^0), [(E_{-\alpha 1}^0 + E_{-\alpha 3}^0), -h_1 - h_3] \right] + \dots$$

agora, usando $[E_{-\alpha 1}^0 + E_{-\alpha 3}^0, -h'] = 2(E_{-\alpha 1}^0 + E_{-\alpha 3}^0)$ temos

$$P = (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \tilde{\chi} [-h_1 - h_3] + \frac{(\tilde{\chi})^2}{2!} [-2(E_{-\alpha 1}^0 + E_{-\alpha 3}^0)] \\ - \frac{(\tilde{\chi})^3}{3!} \left[(E_{-\alpha 1}^0 + E_{-\alpha 3}^0), -2(E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] + \dots$$

$$P = (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \tilde{\chi} [-h_1 - h_3] - \frac{(\tilde{\chi})^2}{2!} [2(E_{-\alpha 1}^0 + E_{-\alpha 3}^0)] - 0$$

$$P = (E_{\alpha 1}^0 + E_{\alpha 3}^0) - \tilde{\chi} (h_1 + h_3) - \tilde{\chi}^2 (E_{-\alpha 1}^0 + E_{-\alpha 3}^0)$$

$$J3 = e^{2R} (\bar{\partial}\tilde{\psi}) \left[(E_{\alpha 1}^0 + E_{\alpha 3}^0) - \tilde{\chi} (h_1 + h_3) - \tilde{\chi}^2 (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] \quad (\text{B.3})$$

juntando (B.1), (B.2) e (B.3) temos

$$J = \\ = (\bar{\partial}B) B^{-1} = (\bar{\partial}\tilde{\chi}) (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) + (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3) \bar{\partial}\varphi \\ + (\bar{\partial}R) \left[(h_1 + h_3) + 2\tilde{\chi} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] + (\bar{\partial}\nu) c + (\bar{\partial}\eta) d \\ + e^{2R} (\bar{\partial}\tilde{\psi}) \left[(E_{\alpha 1}^0 + E_{\alpha 3}^0) - \tilde{\chi} (h_1 + h_3) - \tilde{\chi}^2 (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] \quad (\text{B.4})$$

ou em componentes,

$$J = (\bar{\partial}B) B^{-1} \\ = (\bar{\partial}\tilde{\chi}) (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) + (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3) \bar{\partial}\varphi + \\ + (\bar{\partial}R) \left[(h_1 + h_3) + 2\tilde{\chi} (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] \\ + (\bar{\partial}\nu) c + (\bar{\partial}\eta) d + e^{2R} (\bar{\partial}\tilde{\psi}) \left[(E_{\alpha 1}^0 + E_{\alpha 3}^0) - \tilde{\chi} (h_1 + h_3) - \tilde{\chi}^2 (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) \right] \quad (\text{B.5})$$

temos

$$(\bar{\partial}B) B^{-1} = [(\bar{\partial}\tilde{\chi}) + (\bar{\partial}R) 2\tilde{\chi} - e^{2R} (\bar{\partial}\tilde{\psi}) \tilde{\chi}^2] (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) + \\ + [(\bar{\partial}R) - e^{2R} (\bar{\partial}\tilde{\psi}) \tilde{\chi}] (h_1 + h_3) + \\ + e^{2R} (\bar{\partial}\tilde{\psi}) (E_{\alpha 1}^0 + E_{\alpha 3}^0) + (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3) (\bar{\partial}\varphi) + (\bar{\partial}\nu) c + (\bar{\partial}\eta) d \\ \text{fazendo a transformac\~{a}o } \tilde{\chi} \rightarrow \chi e^{-R}, \tilde{\psi} \rightarrow \psi e^{-R}$$

tomando a componente em $E_{-\alpha 1}^0 + E_{-\alpha 3}^0$:

$$(\bar{\partial}\chi + \chi\bar{\partial}R - \chi^2\bar{\partial}\psi + \chi^2\psi\bar{\partial}R) e^{-R}$$

a componente em $h_1 + h_3$:

$$\bar{\partial}R - \chi\bar{\partial}\psi + \chi\psi\bar{\partial}R = -\chi\bar{\partial}\psi + (1 + \chi\psi)\bar{\partial}R = 0 \rightarrow \bar{\partial}R = \frac{\chi\bar{\partial}\psi}{1 + \chi\psi}$$

a componente em $E_{\alpha_1}^0 + E_{\alpha_3}^0$

$$(\bar{\partial}\psi - \psi\bar{\partial}R) e^R$$

a componente em $E_{-\alpha_1}^0 + E_{-\alpha_3}^0$:

$$\begin{aligned} & (\bar{\partial}\chi + \chi\bar{\partial}R - \chi^2\bar{\partial}\psi + \chi^2\psi\bar{\partial}R) e^{-R} = \\ & = (\bar{\partial}\chi + \chi \left(\frac{\chi\bar{\partial}\psi}{1+\chi\psi} \right) - \chi^2\bar{\partial}\psi + \chi^2\psi \left(\frac{\chi\bar{\partial}\psi}{1+\chi\psi} \right)) e^{-R} \\ & = e^{-R(x)} \bar{\partial}\chi(x) \end{aligned}$$

a componente em $E_{\alpha_1}^0 + E_{\alpha_3}^0$

$$(\bar{\partial}\psi - \psi\bar{\partial}R) e^R = \left(\bar{\partial}\psi(x) - \psi(x) \left(\frac{\chi(x)\bar{\partial}\psi(x)}{1+\chi(x)\psi(x)} \right) \right) e^{R(x)} = e^{R(x)} \frac{\bar{\partial}\psi(x)}{1+\chi(x)\psi(x)}$$

finalmente temos

$$\begin{aligned} (\bar{\partial}B) B^{-1} &= \frac{\bar{\partial}\psi}{1+\chi\psi} e^R (E_{\alpha_1}^0 + E_{\alpha_3}^0) + \bar{\partial}\chi e^{-R} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) + \\ &+ \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) (\bar{\partial}\varphi) + (\bar{\partial}\nu)c + (\bar{\partial}\eta)d \end{aligned}$$

7 Apêndice C.

7.1 Cálculo de $B^{-1} \varepsilon_+ B$.

Dados

$$B = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \quad (C.1)$$

e

$$\varepsilon_+ = E_{\alpha_1 + \alpha_2}^0 - E_{\alpha_2 + \alpha_3}^0 + E_{-\alpha_1 - \alpha_2}^1 - E_{-\alpha_2 - \alpha_3}^1 \quad (C.2)$$

temos

$$B^{-1} \varepsilon_+ B = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^\Lambda e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} \varepsilon_+ e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} e^{-\Lambda} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)}$$

onde $\Lambda = (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \nu c + \eta d$

E facil ver que $B^{-1} \varepsilon_+ B = \tilde{B}^{-1} \varepsilon_+ \tilde{B}$

(C.3)

onde $\tilde{B} = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^\Omega e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)}$ e

$$\Omega = (h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3)\varphi + (h_1 + h_3)R + \eta d$$

pois c comuta com todos os geradores.

$$\varepsilon_+ = E_{\alpha_1 + \alpha_2}^0 - E_{\alpha_2 + \alpha_3}^0 + E_{-\alpha_1 - \alpha_2}^1 - E_{-\alpha_2 - \alpha_3}^1 = \begin{pmatrix} 0 & \sigma_3 \\ \lambda \sigma_3 & 0 \end{pmatrix}$$

onde $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\tilde{B}^{-1} \varepsilon_+ \tilde{B} =$$

$$\tilde{B} = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^\Omega e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{h\varphi + h'R + \eta d} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)}$$

$$\tilde{B}^{-1} = e^{-\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} e^{-h\varphi - h'R - \eta d} e^{-\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} \quad (C.4)$$

Agora

$$h = \frac{1}{2}A \quad \text{onde } A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{e } 1 = \mathbb{I}_{2 \times 2}$$

então

$$e^{\varphi h} = e^{\varphi \frac{A}{2}} = 1 + \frac{\varphi A}{2} + \frac{1}{2!} \left(\frac{\varphi A}{2}\right)^2 + \frac{1}{3!} \left(\frac{\varphi A}{2}\right)^3 + \dots$$

$$= \left[1 + \frac{1}{2!} \left(\frac{\varphi}{2}\right)^2 + \dots\right] + \left[\frac{1}{2} + \frac{1}{3!} \left(\frac{\varphi}{2}\right)^3 + \dots\right] A$$

$$= \cosh\left(\frac{\varphi}{2}\right) + A \sinh\left(\frac{\varphi}{2}\right)$$

isto é

$$e^{\varphi h} = \begin{pmatrix} M_1 I & 0 \\ 0 & M_2 I \end{pmatrix}$$

$$\text{onde } M_1 = \left(\cosh \frac{1}{2}\varphi + \sinh \frac{1}{2}\varphi \right), M_2 = \left(\cosh \frac{1}{2}\varphi - \sinh \frac{1}{2}\varphi \right), I = I_{2 \times 2}$$

$$\text{ou } e^{\varphi h} = \begin{pmatrix} e^{\frac{\varphi}{2}} I & 0 \\ 0 & e^{-\frac{\varphi}{2}} I \end{pmatrix} \quad \text{então } e^{-\varphi h} = \begin{pmatrix} e^{-\frac{\varphi}{2}} I & 0 \\ 0 & e^{\frac{\varphi}{2}} I \end{pmatrix}$$

(C.5)

$$h' = h_1 + h_3 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} \sigma_3 & 0 \\ 0 & \sigma_3 \end{pmatrix}$$

$$\begin{aligned} (h')^2 &= 1 & (h')^3 &= h' \\ e^{h'R} &= 1 + R h' + R^2 \frac{1}{2!} + R^3 \frac{1}{3!} h' + R^4 \frac{1}{4!} + \dots \\ &= \left(1 + \frac{1}{2!} \left(\frac{R^2}{4} \right) + \frac{1}{4!} \left(\frac{R^4}{16} \right) + \dots \right) + h' \left(R + \frac{R^3}{3!} + \dots \right) \end{aligned}$$

$$e^{h'R} = \cosh R + g \sinh R = \begin{pmatrix} N & 0 \\ 0 & N \end{pmatrix}$$

$$\text{onde } N = \begin{pmatrix} \sinh R + \cosh R & 0 \\ 0 & \cosh R - \sinh R \end{pmatrix}$$

$$e^{h'R} = \begin{pmatrix} e^R & 0 & 0 & 0 \\ 0 & e^{-R} & 0 & 0 \\ 0 & 0 & e^R & 0 \\ 0 & 0 & 0 & e^{-R} \end{pmatrix} \quad e^{-h'R} = \begin{pmatrix} e^{-\frac{R}{2}} & 0 & 0 & 0 \\ 0 & e^{-\frac{R}{2}} & 0 & 0 \\ 0 & 0 & e^{\frac{R}{2}} & 0 \\ 0 & 0 & 0 & e^{\frac{R}{2}} \end{pmatrix}$$

(C.6)

reescrevendo (5)

$$\tilde{B} = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{\Omega} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} = e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} e^{h\varphi + h'R} e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} e^{\eta d} \quad (C.7)$$

$$\begin{aligned} \text{e facil mostrar que } e^{\tilde{\chi}(E_{-\alpha_1}^0 + E_{-\alpha_3}^0)} &= 1 + \tilde{\chi} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0) e \\ e^{\tilde{\psi}(E_{\alpha_1}^0 + E_{\alpha_3}^0)} &= 1 + \tilde{\psi} (E_{\alpha_1}^0 + E_{\alpha_3}^0) \end{aligned}$$

então

$$\tilde{B} = [1 + \tilde{\chi} (E_{-\alpha_1}^0 + E_{-\alpha_3}^0)] e^{h\varphi} e^{h'R} [1 + \tilde{\psi} (E_{\alpha_1}^0 + E_{\alpha_3}^0)] e^{\eta d} \quad (C.8)$$

onde

$$e^{h\varphi}e^{h'R} = \begin{pmatrix} e^{\frac{1}{2}\varphi}e^R & 0 & 0 & 0 \\ 0 & e^{\frac{1}{2}\varphi}e^{-R} & 0 & 0 \\ 0 & 0 & e^{-\frac{1}{2}\varphi}e^R & 0 \\ 0 & 0 & 0 & e^{-\frac{1}{2}\varphi}e^{-R} \end{pmatrix} \quad (\text{C.9})$$

substituindo (C.9) em (C.8)

$$\begin{aligned} \tilde{B} &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ \tilde{\chi} & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & \tilde{\chi} & 1 \end{pmatrix} \begin{pmatrix} e^{\frac{1}{2}\varphi}e^R & 0 & 0 & 0 \\ 0 & e^{\frac{1}{2}\varphi}e^{-R} & 0 & 0 \\ 0 & 0 & e^{-\frac{1}{2}\varphi}e^R & 0 \\ 0 & 0 & 0 & e^{-\frac{1}{2}\varphi}e^{-R} \end{pmatrix} \begin{pmatrix} 1 & \tilde{\psi} & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & \tilde{\psi} \\ 0 & 0 & 0 & 1 \end{pmatrix} e^{\eta d} = \\ \tilde{B} &= \begin{pmatrix} e^{\frac{1}{2}\varphi+R} & \psi e^{\frac{1}{2}\varphi+R} & 0 & 0 \\ \tilde{\chi} e^{\frac{1}{2}\varphi+R} & \tilde{\chi} \psi e^{\frac{1}{2}\varphi+R} + e^{\frac{1}{2}\varphi-R} & 0 & 0 \\ 0 & 0 & e^{-\frac{1}{2}\varphi+R} & \psi e^{-\frac{1}{2}\varphi+R} \\ 0 & 0 & \tilde{\chi} e^{-\frac{1}{2}\varphi+R} & \tilde{\chi} \psi e^{-\frac{1}{2}\varphi+R} + e^{-\frac{1}{2}\varphi-R} \end{pmatrix} e^{\eta d} \end{aligned}$$

$$\tilde{B}^{-1} = e^{-\eta d} e^{-\tilde{\psi}(E_{\alpha 1}^0 + E_{\alpha 3}^0)} e^{-h'R} e^{-h\varphi} e^{-\tilde{\chi}(E_{-\alpha 1}^0 + E_{-\alpha 3}^0)}$$

$$\begin{aligned} e^{-h'R} e^{-h\varphi} &= \begin{pmatrix} e^{-R} & 0 & 0 & 0 \\ 0 & e^R & 0 & 0 \\ 0 & 0 & e^{-R} & 0 \\ 0 & 0 & 0 & e^R \end{pmatrix} \begin{pmatrix} e^{-\frac{\varphi}{2}} & 0 & 0 & 0 \\ 0 & e^{-\frac{\varphi}{2}} & 0 & 0 \\ 0 & 0 & e^{\frac{\varphi}{2}} & 0 \\ 0 & 0 & 0 & e^{\frac{\varphi}{2}} \end{pmatrix} \\ &= \begin{pmatrix} e^{-\frac{1}{2}\varphi-R} & 0 & 0 & 0 \\ 0 & e^{-\frac{1}{2}\varphi+R} & 0 & 0 \\ 0 & 0 & e^{\frac{1}{2}\varphi-R} & 0 \\ 0 & 0 & 0 & e^{\frac{1}{2}\varphi+R} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \tilde{B}^{-1} &= e^{-\eta d} \begin{pmatrix} 1 & -\tilde{\psi} & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -\tilde{\psi} \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} e^{-\frac{1}{2}\varphi-R} & 0 & 0 & 0 \\ 0 & e^{-\frac{1}{2}\varphi+R} & 0 & 0 \\ 0 & 0 & e^{\frac{1}{2}\varphi-R} & 0 \\ 0 & 0 & 0 & e^{\frac{1}{2}\varphi+R} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ -\tilde{\chi} & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -\tilde{\chi} & 1 \end{pmatrix} \\ &= e^{-\eta d} \begin{pmatrix} e^{-\frac{1}{2}\varphi-R} + \tilde{\psi} e^{-\frac{1}{2}\varphi+R} \tilde{\chi} & -\tilde{\psi} e^{-\frac{1}{2}\varphi+R} & 0 & 0 \\ -e^{-\frac{1}{2}\varphi+R} \tilde{\chi} & e^{-\frac{1}{2}\varphi+R} & 0 & 0 \\ 0 & 0 & e^{\frac{1}{2}\varphi-R} + \tilde{\psi} e^{\frac{1}{2}\varphi+R} \tilde{\chi} & -\tilde{\psi} e^{\frac{1}{2}\varphi+R} \\ 0 & 0 & -e^{\frac{1}{2}\varphi+R} \tilde{\chi} & e^{\frac{1}{2}\varphi+R} \end{pmatrix} : \end{aligned}$$

Usando as propiedades de d,

$$\begin{aligned} e^{-\eta d} \varepsilon_+ e^{\eta d} &= e^{-\eta d} (E_{\alpha 1 + \alpha 2}^0 - E_{\alpha 2 + \alpha 3}^0 + E_{-\alpha 1 - \alpha 2}^1 - E_{-\alpha 2 - \alpha 3}^1) e^{\eta d} \\ &= e^{-\eta d} (E_{-\alpha 1 - \alpha 2}^1 - E_{-\alpha 2 - \alpha 3}^1) e^{\eta d} \end{aligned}$$

usando a identidade $e^p b e^{-p} = b + [p, b] + \frac{1}{2!} [p, [p, b]] + \frac{1}{3!} [p, [p, [p, b]]] + \dots$

temos

$$\begin{aligned} e^{-\eta d} (E_{-\alpha_1 - \alpha_2}^1) e^{\eta d} &= \\ &= E_{-\alpha_1 - \alpha_2}^1 - \eta [d, E_{-\alpha_1 - \alpha_2}^1] + \frac{(-\eta)^2}{2!} [d, [d, E_{-\alpha_1 - \alpha_2}^1]] + \dots \end{aligned}$$

sustituindo

$$\begin{aligned} [d, E_{-\alpha_1 - \alpha_2}^1] &= E_{-\alpha_1 - \alpha_2}^1 \\ [d, [d, E_{-\alpha_1 - \alpha_2}^1]] &= [d, E_{-\alpha_1 - \alpha_2}^1] = E_{-\alpha_1 - \alpha_2}^1 \end{aligned}$$

então

$$\begin{aligned} e^{-\eta d} (E_{-\alpha_1 - \alpha_2}^1) e^{\eta d} &= \\ &= E_{-\alpha_1 - \alpha_2}^1 - \eta E_{-\alpha_1 - \alpha_2}^1 + \frac{(-\eta)^2}{2!} E_{-\alpha_1 - \alpha_2}^1 + \frac{(-\eta)^3}{3!} E_{-\alpha_1 - \alpha_2}^1 + \dots = e^{-\eta} E_{-\alpha_1 - \alpha_2}^1 \\ &\quad \dots (*) \end{aligned}$$

$$e^{-\eta d} (E_{-\alpha_1 - \alpha_2}^1) e^{\eta d} = e^{-\eta} E_{-\alpha_1 - \alpha_2}^1$$

$$\text{e analogamente} \quad e^{-\eta d} (E_{-\alpha_2 - \alpha_3}^1) e^{\eta d} = e^{-\eta} E_{-\alpha_2 - \alpha_3}^1$$

então

$$\begin{aligned} e^{-\eta d} \varepsilon_+ e^{\eta d} &= e^{-\eta d} (E_{\alpha_1 + \alpha_2}^0 - E_{\alpha_2 + \alpha_3}^0 + E_{-\alpha_1 - \alpha_2}^1 - E_{-\alpha_2 - \alpha_3}^1) e^{\eta d} \\ &= E_{\alpha_1 + \alpha_2}^0 - E_{\alpha_2 + \alpha_3}^0 + (E_{-\alpha_1 - \alpha_2}^1 - E_{-\alpha_2 - \alpha_3}^1) e^{-\eta} \end{aligned}$$

$$e^{-\eta d} \varepsilon_+ e^{\eta d} = E_{\alpha_1 + \alpha_2}^0 - E_{\alpha_2 + \alpha_3}^0 + (E_{-\alpha_1 - \alpha_2}^1 - E_{-\alpha_2 - \alpha_3}^1) e^{-\eta} =$$

$$= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ \lambda e^{-\eta} & 0 & 0 & 0 \\ 0 & -\lambda e^{-\eta} & 0 & 0 \end{pmatrix}$$

$$[d, E_{-\alpha_1 - \alpha_2}^1] = E_{-\alpha_1 - \alpha_2}^1$$

$$\tilde{B}^{-1} \varepsilon_+ \tilde{B} = \begin{bmatrix} 0 & \tilde{P} \\ \tilde{Q} & 0 \end{bmatrix} \quad \text{onde}$$

$$\tilde{P} = \begin{bmatrix} e^{-\varphi} + 2 \tilde{\psi} e^{-\varphi + 2R} \tilde{\chi} & 2 (e^{-\frac{1}{2}\varphi - R} + \tilde{\psi} e^{-\frac{1}{2}\varphi + R} \tilde{\chi}) \tilde{\psi} e^{-\frac{1}{2}\varphi + R} \\ -2e^{-\varphi + 2R} \tilde{\chi} & -2 \tilde{\psi} e^{-\varphi + 2R} \tilde{\chi} - e^{-\varphi} \end{bmatrix} \quad \text{e}$$

$$\tilde{Q} = \begin{bmatrix} \lambda e^{-\eta + \varphi} + 2 \tilde{\psi} \lambda \tilde{\chi} e^{\varphi + 2R - \eta} & 2 (e^{\frac{1}{2}\varphi - R} + \tilde{\psi} e^{\frac{1}{2}\varphi + R} \tilde{\chi}) \lambda \tilde{\psi} e^{-\eta + \frac{1}{2}\varphi + R} \\ -2 \tilde{\chi} \lambda e^{\varphi + 2R - \eta} & -2 \tilde{\psi} \lambda \tilde{\chi} e^{\varphi + 2R - \eta} - \lambda e^{-\eta + \varphi} \end{bmatrix}$$

com as mudanças $\tilde{\psi} = \psi e^{-R}$, $\tilde{\chi} = \chi e^{-R}$ temos

$$\begin{aligned} B^{-1} \varepsilon_+ B &= \\ &= \begin{pmatrix} 0 & 0 & e^{-\varphi} (1 + 2\psi\chi) & 2e^{-\varphi - R} (1 + \psi\chi)\psi \\ 0 & 0 & -2\chi e^{-\varphi + R} & -e^{-\varphi} (1 + 2\psi\chi) \\ \lambda e^{-\eta + \varphi} (1 + 2\psi\chi) & 2e^{\varphi - R - \eta} (1 + \psi\chi)\lambda\psi & 0 & 0 \\ -2\chi\lambda e^{R + \varphi - \eta} & -\lambda e^{-\eta + \varphi} (1 + 2\psi\chi) & 0 & 0 \end{pmatrix} \end{aligned}$$

ou

$$B^{-1}\varepsilon_+B = \begin{bmatrix} 0 & P \\ Q & 0 \end{bmatrix}$$

$$\text{onde } P = \begin{bmatrix} e^{-\varphi}(1+2\psi\chi) & 2e^{-\varphi-R}(1+\psi\chi)\psi \\ -2\chi e^{-\varphi+R} & -e^{-\varphi}(1+2\psi\chi) \end{bmatrix}$$

$$\text{e } Q = \begin{bmatrix} \lambda e^{-\eta+\varphi}(1+2\psi\chi) & 2e^{\varphi-R-\eta}(1+\psi\chi)\lambda\psi \\ -2\chi\lambda e^{R+\varphi-\eta} & -\lambda e^{-\eta+\varphi}(1+2\psi\chi) \end{bmatrix}$$

Reescrevendo em forma de operadores,

$$B^{-1}\varepsilon_+B =$$

$$\begin{aligned} & e^{-\varphi}(1+2\psi\chi)E_{\alpha_1+\alpha_2} - e^{-\varphi}(1+2\psi\chi)E_{\alpha_2+\alpha_3} + \\ & + 2e^{-\varphi-R}(1+\psi\chi)\psi E_{\alpha_1+\alpha_2+\alpha_3} - 2\chi e^{-\varphi+R}E_{\alpha_2} + \\ & e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_1-\alpha_2}^1 - e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_2-\alpha_3}^1 + \\ & - 2\chi e^{R+\varphi-\eta}E_{-\alpha_1-\alpha_2-\alpha_3}^1 + 2e^{\varphi-R-\eta}(1+\psi\chi)\psi E_{-\alpha_2}^1 \end{aligned}$$

(C.10)

8 Apêndice D.

8.1 Contribuição do termo central em $[B^{-1}\varepsilon_+B, \varepsilon_-]$

No apêndice C, mostrou-se que $B^{-1}\varepsilon_+B = \begin{bmatrix} 0 & P \\ Q & 0 \end{bmatrix}$

onde

$$P = \begin{bmatrix} e^{-\varphi}(1+2\psi\chi) & 2e^{-\varphi-R}(1+\psi\chi)\psi \\ -2\chi e^{-\varphi+R} & -e^{-\varphi}(1+2\psi\chi) \end{bmatrix} \quad e$$

$$Q = \begin{bmatrix} \lambda e^{-\eta+\varphi}(1+2\psi\chi) & 2e^{\varphi-R-\eta}(1+\psi\chi)\lambda\psi \\ -2\chi\lambda e^{R+\varphi-\eta} & -\lambda e^{-\eta+\varphi}(1+2\psi\chi) \end{bmatrix}$$

nos sabemos que $\varepsilon_- = \begin{bmatrix} 0 & \frac{1}{\lambda}\sigma_3 \\ \sigma_3 & 0 \end{bmatrix}$

reescrevendo $B^{-1}\varepsilon_+B$ em termos de operadores

$$B^{-1}\varepsilon_+B = e^{-\varphi}(1+2\psi\chi)E_{\alpha_1+\alpha_2}^0 - e^{-\varphi}(1+2\psi\chi)E_{\alpha_2+\alpha_3}^0 - 2\chi e^{-\varphi+R}E_{\alpha_2}^0 \\ + 2e^{-\varphi-R}(1+\psi\chi)\psi E_{\alpha_1+\alpha_2+\alpha_3}^0 + \lambda e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_1-\alpha_2}^0 \\ - \lambda e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_2-\alpha_3}^0 + 2e^{\varphi-R-\eta}(1+\psi\chi)\lambda\psi E_{-\alpha_2}^0 \\ - 2\chi\lambda e^{R+\varphi-\eta}E_{-\alpha_1-\alpha_2-\alpha_3}^0$$

e em termos de geradores de Kac Moody

$$B^{-1}\varepsilon_+B = e^{-\varphi}(1+2\psi\chi)E_{\alpha_1+\alpha_2}^0 - e^{-\varphi}(1+2\psi\chi)E_{\alpha_2+\alpha_3}^0 \\ - 2\chi e^{-\varphi+R}E_{\alpha_2}^0 + 2e^{-\varphi-R}(1+\psi\chi)\psi E_{\alpha_1+\alpha_2+\alpha_3}^0 + \\ e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_1-\alpha_2}^1 - e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_2-\alpha_3}^1 \\ + 2e^{\varphi-R-\eta}(1+\psi\chi)\psi E_{-\alpha_2}^1 - 2\chi e^{R+\varphi-\eta}E_{-\alpha_1-\alpha_2-\alpha_3}^1$$

$$\varepsilon_- = E_{\alpha_1+\alpha_2}^{-1} - E_{\alpha_2+\alpha_3}^{-1} + E_{-\alpha_1-\alpha_2}^0 - E_{-\alpha_2-\alpha_3}^0$$

Definição: $[M, N]_c =$ parte de $[M, N]$ com termo central
 $[M, N]_{nc} =$ parte de $[M, N]$ sem termo central

$$[B^{-1}\varepsilon_+B, \varepsilon_-]_c \\ = [e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_1-\alpha_2}^1 - e^{-\eta+\varphi}(1+2\psi\chi)E_{-\alpha_2-\alpha_3}^1, E_{\alpha_1+\alpha_2}^{-1} - E_{\alpha_2+\alpha_3}^{-1}]_c \\ \text{usando } [E_{\alpha}^m, E_{-\alpha}^n]_c = cm\delta_{m,-n} \quad \text{temos } [E_{\alpha}^1, E_{-\alpha}^{-1}]_c = c$$

$$[B^{-1}\varepsilon_+B, \varepsilon_-]_c = e^{-\eta+\varphi}(1+2\psi\chi)[E_{-\alpha_1-\alpha_2}^1, E_{\alpha_1+\alpha_2}^{-1}]_c + e^{-\eta+\varphi}(1+2\psi\chi)[E_{-\alpha_2-\alpha_3}^1, E_{\alpha_2+\alpha_3}^{-1}]_c \\ = e^{-\eta+\varphi}(1+2\psi\chi)c + e^{-\eta+\varphi}(1+2\psi\chi)c$$

isto é $[B^{-1}\varepsilon_+B, \varepsilon_-]_c = 2e^{-\eta+\varphi}(1+2\psi\chi)c$

8.2 Apêndice E. Verificação das equações (73) utilizando as equações de Leznov-Saveliev

Considere a equação de Leznov-Saveliev

$$\bar{\partial}(B^{-1}\partial B) = [B^{-1}\varepsilon_+B, \varepsilon_-]$$

e calculemos o lado direito. Façamos primeiro os cálculos sem levar em conta o termo central.

No Apêndice C mostrou-se que

$$B^{-1}\varepsilon_+B = \begin{bmatrix} 0 & P \\ Q & 0 \end{bmatrix} \quad \text{onde}$$

$$P = \begin{bmatrix} e^{-\varphi}(1+2\psi\chi) & 2e^{-\varphi-R}(1+\psi\chi)\psi \\ -2\chi e^{-\varphi+R} & -e^{-\varphi}(1+2\psi\chi) \end{bmatrix},$$

$$Q = \begin{bmatrix} \lambda e^{-\eta+\varphi}(1+2\psi\chi) & 2e^{\varphi-R-\eta}(1+\psi\chi)\lambda\psi \\ -2\chi\lambda e^{R+\varphi-\eta} & -\lambda e^{-\eta+\varphi}(1+2\psi\chi) \end{bmatrix}$$

$$\text{enquanto que } \varepsilon_- = \begin{bmatrix} 0 & \frac{1}{\lambda} \sigma_3 \\ 1 & 0 \end{bmatrix}$$

$$\text{então } [B^{-1}\varepsilon_+B, \varepsilon_-]_{nc} = \begin{bmatrix} M & 0 \\ 0 & N \end{bmatrix} \quad \dots(\alpha)$$

onde $M =$

$$= \begin{bmatrix} -e^{-\eta+\varphi} - 2e^{-\eta+\varphi}\psi\chi + 2\psi\chi e^{-\varphi} + e^{-\varphi} & -2\psi e^{-\varphi-R} - 2\psi^2 e^{-\varphi-R}\chi - 2\psi e^{\varphi-R-\eta} - 2\psi^2 e^{\varphi-R-\eta}\chi \\ -2\chi e^{-\varphi+R} - 2\chi e^{R+\varphi-\eta} & -e^{-\eta+\varphi} - 2e^{-\eta+\varphi}\psi\chi + 2\psi\chi e^{-\varphi} + e^{-\varphi} \end{bmatrix}$$

e $N =$

$$= \begin{bmatrix} e^{-\eta+\varphi} + 2e^{-\eta+\varphi}\psi\chi - 2\psi\chi e^{-\varphi} - e^{-\varphi} & -2\psi e^{-\varphi-R} - 2\psi^2 e^{-\varphi-R}\chi - 2\psi e^{\varphi-R-\eta} - 2\psi^2 e^{\varphi-R-\eta}\chi \\ -2\chi e^{-\varphi+R} - 2\chi e^{R+\varphi-\eta} & e^{-\eta+\varphi} + 2e^{-\eta+\varphi}\psi\chi - 2\psi\chi e^{-\varphi} - e^{-\varphi} \end{bmatrix}$$

No Apêndice D mostrou-se que a contribuição da parte central ao comutador é dada por

$$[B^{-1}\varepsilon_+B, \varepsilon_-]_c = 2 e^{-\eta+\varphi}(1+2\psi\chi)c$$

$$\text{Lembrando que } h = h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 = \begin{pmatrix} \frac{1}{2}I & 0 \\ 0 & -\frac{1}{2}I \end{pmatrix} \quad \text{com } I = I_{2 \times 2}$$

reescrevemos o resultado (α) em forma de operadores:

$$[B^{-1}\varepsilon_+B, \varepsilon_-] =$$

$$\begin{aligned} & \left(-2\psi e^{-\varphi-R} - 2\psi^2 e^{-\varphi-R}\chi - 2\psi e^{\varphi-R-\eta} - 2\psi^2 e^{\varphi-R-\eta}\chi \right) (E_{\alpha 1}^0 + E_{\alpha 3}^0) \\ & + \left(-e^{-\eta+\varphi} - 2e^{-\eta+\varphi}\psi\chi + 2\psi\chi e^{-\varphi} + e^{-\varphi} \right) \left(2 \left(h_2 + \frac{1}{2}h_1 + \frac{1}{2}h_3 \right) \right) \\ & + \left(-2\chi e^{-\varphi+R} - 2\chi e^{R+\varphi-\eta} \right) (E_{-\alpha 1}^0 + E_{-\alpha 3}^0) + 2e^{-\eta+\varphi}(1+2\psi\chi)c \end{aligned}$$

(E.1)

Agora, no Apêndice A mostrou-se que

$$B^{-1}\bar{\partial}B = \left[(\bar{\partial}\psi) e^{-R} \right] (E_{\alpha 1}^0 + E_{\alpha 3}^0) + \left[\frac{\bar{\partial}\chi}{\Delta} e^R \right] (E_{-\alpha 1}^0 + E_{-\alpha 3}^0)$$

$$+\bar{\partial}\varphi\left(h_2+\frac{1}{2}h_1+\frac{1}{2}h_3\right)+\left(\bar{\partial}\nu\right)c+\left(\bar{\partial}n\right)d$$

(E.2)

então

$$\begin{aligned}\partial(B^{-1}\bar{\partial}B) &= \left(\partial\left(\bar{\partial}\psi e^{-R}\right)\right)\left(E_{\alpha 1}^0+E_{\alpha 3}^0\right)+\partial_+\left(\frac{\bar{\partial}\chi}{\Delta}\right)\left(E_{-\alpha 1}^0+E_{-\alpha 3}^0\right)+ \\ &+ \left(\partial\bar{\partial}\varphi\right)\left(h_2+\frac{1}{2}h_1+\frac{1}{2}h_3\right)+\left(\partial\bar{\partial}\nu\right)c+\left(\partial\bar{\partial}n\right)d\end{aligned}$$

nesta última expressão temos que a componente de $\left(E_{-\alpha 1}^0+E_{-\alpha 3}^0\right)$ é

$$\partial\left(\bar{\partial}\psi e^{-R}\right)=\left(\partial\bar{\partial}\psi-\left(\bar{\partial}\psi\right)\left(\partial R\right)\right)e^{-R}$$

e a componente de $\left(E_{-\alpha 1}^0+E_{-\alpha 3}^0\right)$ é

$$\partial\left(\frac{\bar{\partial}\chi}{\Delta}e^R\right)=\frac{-\psi\left(\bar{\partial}\chi\right)\left(\partial\chi\right)+\left(\partial\bar{\partial}\chi\right)+\chi\psi\left(\partial\bar{\partial}\chi\right)}{\left(1+\chi\psi\right)^2}e^R$$

Os resultados de cada lado na equação de Leznov-Saveliev são:

$$\begin{aligned}[B^{-1}\varepsilon_+B,\varepsilon_-] &= \\ &\left(-2\psi e^{-\varphi-R}-2\psi^2 e^{-\varphi-R}\chi-2\psi e^{\varphi-R-\eta}-2\psi^2 e^{\varphi-R-\eta}\chi\right)\left(E_{\alpha 1}^0+E_{\alpha 3}^0\right) \\ &+ \left(-e^{-\eta+\varphi}-2e^{-\eta+\varphi}\psi\chi+2\psi\chi e^{-\varphi}+e^{-\varphi}\right)\left(2\left(h_2+\frac{1}{2}h_1+\frac{1}{2}h_3\right)\right) \\ &+ \left(-2\chi e^{-\varphi+R}-2\chi e^{R+\varphi-\eta}\right)\left(E_{-\alpha 1}^0+E_{-\alpha 3}^0\right)+2e^{-\eta+\varphi}\left(1+2\psi\chi\right)c\end{aligned}$$

(E.3)

$$\begin{aligned}\partial(B^{-1}\bar{\partial}B) &= \\ &\left(\partial\bar{\partial}\psi-\left(\bar{\partial}\psi\right)\left(\partial R\right)\right)e^{-R}\left(E_{\alpha 1}^0+E_{\alpha 3}^0\right)+ \\ &+ \left[\frac{-\psi\left(\bar{\partial}\chi\right)\left(\partial\chi\right)+\left(\partial\bar{\partial}\chi\right)+\chi\psi\left(\partial\bar{\partial}\chi\right)}{\left(1+\chi\psi\right)^2}\right]e^R\left(E_{-\alpha 1}^0+E_{-\alpha 3}^0\right)+ \\ &+ \left(\partial\bar{\partial}\varphi\right)\left(h_2+\frac{1}{2}h_1+\frac{1}{2}h_3\right)+\left(\partial\bar{\partial}\nu\right)c+\left(\partial\bar{\partial}n\right)d\end{aligned}$$

(E.4)

por tanto, igualando as respectivas componentes, obtemos as equações

$$\begin{aligned}&\left(-2\psi e^{-\varphi-R}-2\psi^2 e^{-\varphi-R}\chi-2\psi e^{\varphi-R-\eta}-2\psi^2 e^{\varphi-R-\eta}\chi\right) \\ &= \left(\partial\bar{\partial}\psi-\left(\bar{\partial}\psi\right)\left(\partial R\right)\right)e^{-R}\end{aligned}$$

(E.5.1)

$$\left[\frac{-\psi\left(\bar{\partial}\chi\right)\left(\partial\chi\right)+\left(\partial\bar{\partial}\chi\right)+\chi\psi\left(\partial\bar{\partial}\chi\right)}{\left(1+\chi\psi\right)^2}e^R\right]=\left(-2\chi e^{-\varphi+R}-2\chi e^{R+\varphi-\eta}\right)$$

(E.5.2)

$$\left(\partial\bar{\partial}\varphi\right)=2\left(-e^{-\eta+\varphi}-2e^{-\eta+\varphi}\psi\chi+2\psi\chi e^{-\varphi}+e^{-\varphi}\right)$$

(E.5.3)

$$2e^{-\eta+\varphi}(1+2\psi\chi) = \partial \bar{\partial} \nu \quad (\text{E.5.4})$$

$$\partial \bar{\partial} \eta = 0 \quad (\text{E.5.5})$$

na aproximação de Loop Algebra consideramos $\eta = 0$, e simplificando as equações temos

$$-2\psi(e^{-\varphi} + e^{\varphi})(1 + \psi\chi) = (\partial \bar{\partial} \psi - (\bar{\partial}\psi)(\partial R)) \quad (\text{E.6.1})$$

$$\frac{-\psi(\bar{\partial}\chi)(\partial\chi) + (\partial \bar{\partial} \chi) + \chi\psi(\partial \bar{\partial} \chi)}{(1 + \chi\psi)^2} = -2\chi(e^{-\varphi} + e^{+\varphi}) \quad (\text{E.6.2})$$

$$(\partial \bar{\partial} \varphi) = 2 \left(-(1 + 2\psi\chi) \left(e^{\varphi} - \frac{1}{e^{\varphi}} \right) \right) \quad (\text{E.6.3})$$

$$2e^{\varphi}(1 + 2\psi\chi) = \partial \bar{\partial} \nu \quad (\text{E.6.4})$$

isto é

$$-2\psi(e^{-\varphi} + e^{\varphi})(1 + \psi\chi) = (\partial \bar{\partial} \psi - (\bar{\partial}\psi)(\partial R)) \quad (\text{E.7.1})$$

$$-\psi(\bar{\partial}\chi)(\partial\chi) + (1 + \chi\psi)(\partial \bar{\partial} \chi) + 2\chi(1 + \chi\psi)^2(e^{-\varphi} + e^{+\varphi}) = 0 \quad (\text{E.7.2})$$

$$(\partial \bar{\partial} \varphi) + 2((1 + 2\psi\chi)(e^{\varphi} - e^{-\varphi})) = 0 \quad \text{ou}$$

$$(\partial \bar{\partial} \varphi) + 2(1 + 2\psi\chi)e^{\varphi} - 2(1 + 2\psi\chi)e^{-\varphi} \quad (\text{E.7.3})$$

$$\partial \bar{\partial} \nu - 2e^{\varphi}(1 + 2\psi\chi) = 0 \quad (\text{E.7.4})$$

substituindo na primeira equação (E.7.1) $\partial R = \frac{\chi(\partial\psi)}{(1+\chi\psi)}$:

$$-2\psi(e^{-\varphi} + e^{\varphi})(1 + \psi\chi) = \partial \bar{\partial} \psi - \frac{\chi(\bar{\partial}\psi)(\partial\psi)}{(1+\chi\psi)} \quad \text{ou}$$

$$\begin{aligned} -2\psi(e^{-\varphi} + e^{\varphi})(1 + \psi\chi)^2 &= (1 + \chi\psi) \partial \bar{\partial} \psi - \chi(\bar{\partial}\psi)(\partial\psi) \\ (1 + \chi\psi) \partial \bar{\partial} \psi - \chi(\bar{\partial}\psi)(\partial\psi) + 2\psi(1 + \psi\chi)^2(e^{-\varphi} + e^{\varphi}) &\quad \text{ou} \\ -\chi(\bar{\partial}\psi)(\partial\psi) + (1 + \chi\psi) \partial \bar{\partial} \psi + 2\psi(1 + \psi\chi)^2(e^{-\varphi} + e^{\varphi}) &\end{aligned}$$

(E.7.1')

9 Apêndice F.

9.1 Cálculo dos autovalores dos operadores $\varepsilon_+, \varepsilon_-$.

1. Cálculo do autovalor w_+ na equação $[\varepsilon_+, F_1^+] = w_+ F_1^+$ onde

$$F_1^+ = \sum_n E_{\alpha_1}^n z^{-2n} + \sum_n E_{\alpha_3}^n z^{-2n} + \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{-2n-1} + \sum_n E_{-\alpha_2}^n z^{-2n+1}.$$

$$\varepsilon_+ = E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1$$

porém $[\varepsilon_+, F_1^+]$ não aparecem termos centrais, e podemos trabalhar nesta parte com a representação matricial:

$$\varepsilon_+ = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ \lambda & 0 & 0 & 0 \\ 0 & -\lambda & 0 & 0 \end{pmatrix}$$

$$[\varepsilon_+, F_1^+] = w_+ F_1^+$$

Os comutadores de ε_+ com os termos de F_1^+ são

$$\begin{aligned} [\varepsilon_+, E_{\alpha_1}^0] &= E_{\alpha_1+\alpha_2+\alpha_3}^0 + E_{-\alpha_2}^1 & [\varepsilon_+, E_{\alpha_3}^0] &= E_{\alpha_1+\alpha_2+\alpha_3}^0 + E_{-\alpha_2}^1 \\ [\varepsilon_+, E_{\alpha_1+\alpha_2+\alpha_3}^0] &= E_{\alpha_1}^1 + E_{\alpha_3}^1 & [\varepsilon_+, E_{-\alpha_2}^0] &= E_{\alpha_1}^0 + E_{\alpha_3}^0 \end{aligned} \quad \text{porém, substituindo}$$

em

$$[\varepsilon_+, F_1^+] = \sum_n [\varepsilon_+, E_{\alpha_1}^n] z^{-2n} + \sum_n [\varepsilon_+, E_{\alpha_3}^n] z^{-2n} \\ + \sum_n [\varepsilon_+, E_{\alpha_1+\alpha_2+\alpha_3}^n] z^{-2n-1} + \sum_n [\varepsilon_+, E_{-\alpha_2}^n] z^{-2n+1}$$

temos

$$= \sum_n (E_{\alpha_1+\alpha_2+\alpha_3}^n + E_{-\alpha_2}^{n+1}) z^{-2n} + \sum_n (E_{\alpha_1+\alpha_2+\alpha_3}^n + E_{-\alpha_2}^{n+1}) z^{-2n} +$$

$$\sum_n (E_{\alpha_1}^{n+1} + E_{\alpha_3}^{n+1}) z^{-2n-1} + \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^{-2n+1} =$$

$$= 2 \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{-2n} + E_{-\alpha_2}^{n+1} z^{-2n} +$$

$$+ \sum_n (E_{\alpha_1}^{n+1} + E_{\alpha_3}^{n+1}) z^{-2n-1} + \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^{-2n+1}$$

efetuando a mudança $m = n + 1$ nos graus $n+1$ de "loop", temos

$$= 2 \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{-2n} + E_{-\alpha_2}^m z^{-2(m-1)}$$

$$+ \sum_m (E_{\alpha_1}^m + E_{\alpha_3}^m) z^{-2(m-1)-1} + \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^{-2n+1}$$

simplificando os expoentes,

$$= 2 \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{-2n} + 2 \sum_n E_{-\alpha_2}^m z^{-2m+2}$$

$$+ \sum_m (E_{\alpha_1}^m + E_{\alpha_3}^m) z^{-2m+1} + \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^{-2n+1}$$

e fatorando $2z$, temos

$$= 2z \left\{ \sum_n E_{\alpha_1}^n z^{-2n} + \sum_n E_{\alpha_3}^n z^{-2n} + \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{-2n-1} + \sum_n E_{-\alpha_2}^n z^{-2n+1} \right\}$$

$$[\varepsilon_+, F_1^+] = 2zF_1^+$$

2. Cálculo de w_+ para $[\varepsilon_+, F_2^+] = w_+F_2^+$ onde

$$F_2^+ = \sum_n E_{\alpha_2}^n z^{-2n-1} - \sum_n E_{-\alpha_3}^n z^{-2n} + \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^n z^{-2n+1} - \sum_n E_{-\alpha_1}^n z^{-2n}$$

Também aqui não aparecem termos centrais,

$$[\varepsilon_+, F_2^+] = w_+F_2^+$$

Temos

$$\begin{aligned} [\varepsilon_+, E_{\alpha_2}^0] &= -E_{-\alpha_1}^1 - E_{-\alpha_3}^1 & [\varepsilon_+, E_{-\alpha_3}^0] &= -E_{\alpha_2}^0 - E_{-\alpha_1-\alpha_2-\alpha_3}^1 \\ [\varepsilon_+, E_{-\alpha_1-\alpha_2-\alpha_3}^0] &= -E_{-\alpha_1}^0 - E_{-\alpha_3}^0 & [\varepsilon_+, E_{-\alpha_1}^0] &= -E_{\alpha_2}^0 - E_{-\alpha_1-\alpha_2-\alpha_3}^1 \end{aligned}$$

Substituindo os comutadores no mesmo ordem,

$$\begin{aligned} [\varepsilon_+, F_2^+] &= \sum_n [\varepsilon_+, E_{\alpha_2}^n] z^{-2n-1} - \sum_n [\varepsilon_+, E_{-\alpha_3}^n] z^{-2n} \\ &\quad + \sum_n [\varepsilon_+, E_{-\alpha_1-\alpha_2-\alpha_3}^n] z^{-2n+1} - \sum_n [\varepsilon_+, E_{-\alpha_1}^n] z^{-2n} \\ [\varepsilon_+, F_2^+] &= \sum_n (-E_{-\alpha_1}^{n+1} - E_{-\alpha_3}^{n+1}) z^{-2n-1} - \sum_n (-E_{\alpha_2}^n - E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1}) z^{-2n} \\ &\quad + \sum_n (-E_{-\alpha_1}^n - E_{-\alpha_3}^n) z^{-2n+1} - \sum_n (-E_{\alpha_2}^n - E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1}) z^{-2n} = \\ &= - \sum_n (E_{-\alpha_1}^{n+1} + E_{-\alpha_3}^{n+1}) z^{-2n-1} + \sum_n (E_{\alpha_2}^n + E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1}) z^{-2n} \\ &\quad - \sum_n (E_{-\alpha_1}^n + E_{-\alpha_3}^n) z^{-2n+1} + \sum_n (E_{\alpha_2}^n + E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1}) z^{-2n} \\ &= -2 \sum_n (E_{-\alpha_1}^{n+1} + E_{-\alpha_3}^{n+1}) z^{-2n-1} + 2 \sum_n (E_{\alpha_2}^n + E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1}) z^{-2n} = \\ &\quad -2 \sum_n (E_{-\alpha_1}^{n+1} + E_{-\alpha_3}^{n+1}) z^{-2n-1} + 2 \sum_n E_{\alpha_2}^n z^{-2n} + 2 \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^{n+1} z^{-2n} \end{aligned}$$

a mudança $n=m-1$ nos graus $n+1$ de "loop", temos

$$-2 \sum_m (E_{-\alpha_1}^m + E_{-\alpha_3}^m) z^{-2m+1} + 2 \sum_n E_{\alpha_2}^n z^{-2n} + 2 \sum_m E_{-\alpha_1-\alpha_2-\alpha_3}^m z^{-2m+2}$$

fatorando $2z$

$$2z \left[\sum_n - (E_{-\alpha_1}^n + E_{-\alpha_3}^n) z^{-2n} + \sum_n E_{\alpha_2}^n z^{-2n-1} + \sum_n E_{-\alpha_1-\alpha_2-\alpha_3}^n z^{-2n+1} \right]$$

$$[\varepsilon_+, F_2^+] = 2z F_2^+$$

3. Cálculo de w_+ para $[\varepsilon_+, F_4^+] = w_+F_4^+$ onde

$$\varepsilon_+ = E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1$$

$$\begin{aligned} F_4^+ &= \sum_n h_1^n z^{-2n} + 2 \sum_n h_2^n z^{-2n} + \sum_n h_3^n z^{-2n} - \sum_n E_{\alpha_1+\alpha_2}^n z^{-2n-1} \\ &\quad + \sum_n E_{\alpha_2+\alpha_3}^n z^{-2n-1} + \sum_n E_{-\alpha_1-\alpha_2}^n z^{-2n+1} - \sum_n E_{-\alpha_2-\alpha_3}^n z^{-2n+1} - c \end{aligned}$$

Comutadores sem usar termos centrais

$$\begin{aligned} [\varepsilon_+, h_1^0] &= E_{-\alpha_1-\alpha_2}^1 + E_{-\alpha_2-\alpha_3}^1 - E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 \\ [\varepsilon_+, h_2^0] &= E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1 - E_{\alpha_1+\alpha_2}^0 + E_{\alpha_2+\alpha_3}^0 \\ [\varepsilon_+, h_3^0] &= -E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1 + E_{\alpha_1+\alpha_2}^0 + E_{\alpha_2+\alpha_3}^0 \\ [\varepsilon_+, E_{\alpha_1+\alpha_2}^0] &= -h_1^1 - h_2^1 \\ [\varepsilon_+, E_{-\alpha_1-\alpha_2}^0] &= h_1^0 + h_2^0 \\ [\varepsilon_+, E_{\alpha_2+\alpha_3}^0] &= h_2^1 + h_3^1 \\ [\varepsilon_+, E_{-\alpha_2-\alpha_3}^0] &= -h_2^0 - h_3^0 \end{aligned}$$

As contribuições da álgebra de Kac Moody ao comutador $[\varepsilon_+, F_4^+]$

$$\varepsilon_+ = E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1$$

$$[E_{-\alpha_1-\alpha_2}^1, E_{\alpha_1+\alpha_2}^n] = -[E_{\alpha_1+\alpha_2}^n, E_{-\alpha_1-\alpha_2}^1] \quad \text{usando } [E_\alpha^m, E_{-\alpha}^n] = H_\alpha^{m+n} + c m \delta_{m,-n}$$

temos $[E_{\alpha_1+\alpha_2}^n, E_{-\alpha_1-\alpha_2}^1] = (H_{\alpha_1+\alpha_2}^{n+1} + c n \delta_{n,-1})$ isto é

$$[E_{-\alpha_1-\alpha_2}^1, E_{\alpha_1+\alpha_2}^n] = -H_{\alpha_1+\alpha_2}^{n+1} - c n \delta_{n,-1} \quad \text{aparece termo central se } n = -1 \dots (\alpha)$$

$$[E_{-\alpha_2-\alpha_3}^1, E_{\alpha_2+\alpha_3}^n] = -[E_{\alpha_2+\alpha_3}^n, E_{-\alpha_2-\alpha_3}^1] = -(H_{\alpha_2+\alpha_3}^{n+1} + c n \delta_{n,-1})$$

$$[E_{-\alpha_2-\alpha_3}^1, E_{\alpha_2+\alpha_3}^n] = -H_{\alpha_2+\alpha_3}^{n+1} - c n \delta_{n,-1} \quad \text{aparece termo central se } n = -1 \dots (\beta)$$

Tabela de comutadores incluindo Kac Moody

usando α e β temos

$$\varepsilon_+ = E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1$$

$$[\varepsilon_+, E_{\alpha_1+\alpha_2}^n] = [E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1, E_{\alpha_1+\alpha_2}^n] =$$

$$= -h_1^{n+1} - h_2^{n+1} - c n \delta_{n,-1}$$

usando (α) :

$$[\varepsilon_+, E_{\alpha_2+\alpha_3}^n] = [E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0 + E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1, E_{\alpha_2+\alpha_3}^n]$$

$$= h_2^{n+1} + h_3^{n+1} + c n \delta_{n,-1}$$

usando (β) :

$$[\varepsilon_+, h_1^0] = E_{-\alpha_1-\alpha_2}^1 + E_{-\alpha_2-\alpha_3}^1 - E_{\alpha_1+\alpha_2}^0 - E_{\alpha_2+\alpha_3}^0$$

$$[\varepsilon_+, h_2^0] = E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1 - E_{\alpha_1+\alpha_2}^0 + E_{\alpha_2+\alpha_3}^0$$

$$[\varepsilon_+, h_3^0] = -E_{-\alpha_1-\alpha_2}^1 - E_{-\alpha_2-\alpha_3}^1 + E_{\alpha_1+\alpha_2}^0 + E_{\alpha_2+\alpha_3}^0$$

$$[\varepsilon_+, E_{\alpha_1+\alpha_2}^n] = -h_1^{n+1} - h_2^{n+1} - c n \delta_{n,-1}$$

$$[\varepsilon_+, E_{-\alpha_1-\alpha_2}^n] = h_1^n + h_2^n$$

$$[\varepsilon_+, E_{\alpha_2+\alpha_3}^n] = h_2^{n+1} + h_3^{n+1} + c n \delta_{n,-1}$$

$$[\varepsilon_+, E_{-\alpha_2-\alpha_3}^n] = -h_2^n - h_3^n$$

$$\text{Agora, } [\varepsilon_+, F_4^+] =$$

$$= \sum_n [\varepsilon_+, h_1^n] z^{-2n} + 2 \sum_n [\varepsilon_+, h_2^n] z^{-2n} + \sum_n [\varepsilon_+, h_3^n] z^{-2n} +$$

$$- \sum_n [\varepsilon_+, E_{\alpha_1+\alpha_2}^n] z^{-2n-1} + \sum_n [\varepsilon_+, E_{\alpha_2+\alpha_3}^n] z^{-2n-1}$$

$$+ \sum_n [\varepsilon_+, E_{-\alpha_1-\alpha_2}^n] z^{-2n+1} - \sum_n [\varepsilon_+, E_{-\alpha_2-\alpha_3}^n] z^{-2n+1}$$

substituindo os comutadores em ordem

$$= \sum_n (E_{-\alpha_1-\alpha_2}^{n+1} + E_{-\alpha_2-\alpha_3}^{n+1} - E_{\alpha_1+\alpha_2}^n - E_{\alpha_2+\alpha_3}^n) z^{-2n}$$

$$+ 2 \sum_n (E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} - E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n) z^{-2n}$$

$$+ \sum_n (-E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} + E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n) z^{-2n} +$$

$$- \sum_n (-h_1^{n+1} - h_2^{n+1} - c n \delta_{n,-1}) z^{-2n-1}$$

$$+ \sum_n (h_2^{n+1} + h_3^{n+1} + c n \delta_{n,-1}) z^{-2n-1}$$

$$+ \sum_n (h_1^n + h_2^n) z^{-2n+1}$$

$$\begin{aligned}
& - \sum_n (-h_2^n - h_3^n) z^{-2n+1} = \\
& \quad \text{dão} \\
& = 2 \sum_n \left(E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} - E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n} + \\
& \quad + \sum_n \left(h_1^{n+1} + h_2^{n+1} \right) z^{-2n-1} - cz^{-2(-1)-1} \\
& + \sum_n \left(h_2^{n+1} + h_3^{n+1} \right) z^{-2n-1} - cz^{-2(-1)-1} + \sum_n \left(h_1^n + h_2^n \right) z^{-2n+1} \\
& \quad + \sum_n \left(h_2^n + h_3^n \right) z^{-2n+1} = \\
& = 2 \sum_n \left(E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} - E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n} + \\
& \quad + \sum_n \left(h_1^{n+1} + 2h_2^{n+1} + h_3^{n+1} \right) z^{-2n-1} + \sum_n \left(h_1^n + 2h_2^n + h_3^n \right) z^{-2n+1} - 2cz
\end{aligned}$$

com a mudança $m=n+1$ nos operadores h_1^{n+1} temos

$$\begin{aligned}
& = 2 \sum_n \left(E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} - E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n} + \\
& \quad + 2 \sum_n \left(h_1^n + 2h_2^n + h_3^n \right) z^{-2n+1} \\
& = 2 \sum_n \left(E_{-\alpha_1-\alpha_2}^{n+1} - E_{-\alpha_2-\alpha_3}^{n+1} \right) z^{-2n} + \\
& + 2 \sum_n \left(-E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n} + 2 \sum_n \left(h_1^n + 2h_2^n + h_3^n \right) z^{-2n+1} - 2cz
\end{aligned}$$

fazendo $m=n+1$ na primeira soma,

$$\begin{aligned}
& = 2 \sum_n \left(E_{-\alpha_1-\alpha_2}^m - E_{-\alpha_2-\alpha_3}^m \right) z^{-2m+2} + 2 \sum_n \left(-E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n} + \\
& + 2 \sum_n \left(h_1^n + 2h_2^n + h_3^n \right) z^{-2n+1} - 2cz
\end{aligned}$$

fatorando $2z$

$$\begin{aligned}
& = 2z \left[\sum_n \left(E_{-\alpha_1-\alpha_2}^m - E_{-\alpha_2-\alpha_3}^m \right) z^{-2m+1} + \sum_n \left(-E_{\alpha_1+\alpha_2}^n + E_{\alpha_2+\alpha_3}^n \right) z^{-2n-1} \right. \\
& \quad \left. + \sum_n \left(h_1^n + 2h_2^n + h_3^n \right) z^{-2n} - c \right]
\end{aligned}$$

isto é $[\varepsilon_+, F_4^+] = 2z F_4^+$

4. Cálculo de w_+ na equação $[\varepsilon_+, F_6^+] = w_+ F_6^+$ onde

$$F_6^+ = \sum_n E_{-\alpha_2}^n z^{2n} - \sum_n E_{\alpha_1+\alpha_2+\alpha_3}^n z^{2n-1}$$

usamos representação matricial, pois ε_+ e F_6^+ não tem geradores em comun.

$$[\varepsilon_+, F_6^+] = \sum_n [\varepsilon_+, E_{-\alpha_2}^n] z^{2n} - \sum_n [\varepsilon_+, E_{\alpha_1+\alpha_2+\alpha_3}^n] z^{2n-1}$$

$$\varepsilon_+ = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ \lambda & 0 & 0 & 0 \\ 0 & -\lambda & 0 & 0 \end{pmatrix} \quad E_{-\alpha_2}^0 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$E_{\alpha_1+\alpha_2+\alpha_3}^0 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$[\varepsilon_+, E_{-\alpha_2}^0] = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} = E_{\alpha_1}^0 + E_{\alpha_3}^0,$$

$$[\varepsilon_+, E_{\alpha_1+\alpha_2+\alpha_3}^0] = \begin{pmatrix} 0 & \lambda & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda \\ 0 & 0 & 0 & 0 \end{pmatrix} = E_{\alpha_1}^1 + E_{\alpha_3}^1$$

$$\begin{aligned} [\varepsilon_+, F_6^+] &= \sum_n [\varepsilon_+, E_{-\alpha_2}^n] z^{2n} - \sum_n [\varepsilon_+, E_{\alpha_1+\alpha_2+\alpha_3}^n] z^{2n-1} \\ &= \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^n - \sum_n (E_{\alpha_1}^{n+1} + E_{\alpha_3}^{n+1}) z^{n+1} \end{aligned}$$

mudando o índice de soma $n = m - 1$ na segunda soma,

$$= \sum_n (E_{\alpha_1}^n + E_{\alpha_3}^n) z^n - \sum_n (E_{\alpha_1}^m + E_{\alpha_3}^m) z^n = 0$$

