Vacuumless kink systems from vacuum systems: An example

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Some years ago, Cho and Vilenkin, introduced a model which presents topological solutions, despite not having degenerate vacua as is usually expected. Here we present a new model with topological defects, connecting degenerate vacua but which in a certain limit recovers precisely the one proposed originally by Cho and Vilenkin. In other words, we found a kind of parent model for the so called vacuumless model. Then the idea is extended to a model recently introduced by Bazeia et al. Finally, we trace some comments the case of the Liouville model.

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Usually the topological objects like domain walls, strings and monopoles appears when the models support at least two degenerate vacua. Notwithstanding, there are some models which defy this common sense, like the Liouville model [1–3], the vacuumless (VL) model introduced originally by Cho and Vilenkin [4–6] and, more recently a model where the kink interpolates between two inflection points instead vacua [7]. Here we are going to concentrate our attention to the VL case, which was originally studied regarding gravitational aspects of the topological defect [4], and then regarding its topological properties [5], and after that make a discussion in general lines about how to implement a similar procedure in the other two cited cases. The Lagrangian density of the model we are going to introduce here is the usual one for a scalar field,

\[ \mathcal{L} = \frac{1}{2} \partial_\mu \varphi \partial^\mu \varphi - V(\varphi) \]  

where the potential is given by

\[ V(\varphi) = \frac{1}{2} (A \cosh(\varphi) - B \text{sech}(\varphi))^2. \]  

Note that, if \( A = 0 \) and \( B = \pm \mu \), we recover the usual vacuumless potential [5]

\[ V(\varphi) = \frac{\mu^2}{2} (\text{sech}(\varphi))^2. \]  

Let us use the BPS approach [8], in order to present the solution of this and the new model we introduced above. For this, one can write the potential in terms of the so called superpotential, which is given by

\[ V(\phi) = \frac{1}{2} W_\phi^2. \]  

from which the energy of the static configuration can be obtained as

\[ E_{BPS} = \frac{1}{2} \int_{-\infty}^{\infty} dx \left[ \left( \frac{d\phi}{dx} - W_\phi \right)^2 + W_\phi \frac{d\phi}{dx} \right]. \]  

Observing this equation, we note that the field configuration which minimizes the energy will obey the first-order differential equation

\[ \frac{d\phi}{dx} = \frac{d}{dx} \]  

and its energy is written as

\[ E_{BPS} = |W(\phi(\infty)) - W(\phi(-\infty))|. \]  

Let us now apply this machinery to the above mentioned models. In the case of the VL model, one can check that the superpotential is given by [5]

\[ W(\phi) = -B \tan^{-1} \sinh(\phi), \]  

and its slowly divergent kink looks like

\[ \phi(x) = \sinh^{-1}(Bx). \]  

On the other hand, in the case of the model which we are introducing here (2), the superpotential has the appearance

\[ W(\phi) = A \sinh(\phi) - B \tan^{-1} \sinh(\phi), \]  

and the corresponding kink and antikink are expressed as

\[ \phi(x) = \pm \sinh^{-1} \left[ \frac{B}{A} \tanh(\sqrt{A(B-A)x}) \right]. \]  

from which it can be verified that the expected limit (9) when \( A \to 0 \) is really achieved. It is possible to observe too, from the Fig. 1, that when \( A \to 0 \) the vacua of the model becomes more and more far from each other, in such a way that one can think the VL model [4], as a limit of this model with usual degenerate vacua. Once in this case, the limit of the field configuration at \( x \to \pm \infty \), are the vacua of the model, we can assure that in these limits, the field given
The energy density of the model we are studying is in (11) goes to
\[ \phi(\pm \infty) = \pm \cosh^{-1}\left(\frac{B}{A}\right) \] (12)

Note that, for consistency, the model will have two minima provided that \( B > A > 0 \), up to overall sign. Otherwise the potential has only one minimum and the solution of the Eq. (11) presents singularities at finite points in the space, so rendering itself as a nonphysical solution.

The BPS energy of this configuration will then be given by
\[ E_{BPS}(A, B) = 2 \left( B - A - B \tan^{-1}\left[\frac{B - A}{A}\right] \right). \] (13)

Let us now analyze the limit of this energy when \( A \to 0 \). The first term vanishes obviously, and in the second we see that the argument of the function diverges and, as we know, the inverse function of the hyperbolic cosine diverges too, but the hyperbolic tangent of infinity is simply one. As a consequence we conclude that the limit of the above energy is simply given by
\[ E_{BPS}(0, B) = \pi B, \] (14)

which is in absolute accordance with the expected for the VL model [5]. The energy density of the model we are studying is
\[ \varepsilon(x) = \left( W(\phi_k(x)) \right)^2 \]
\[ = \frac{(A - B)^2 \text{sech}(\sqrt{A(B - A)x})^4}{(1 + (B/A - 1) \tanh(\sqrt{A(B - A)x})^2)}, \] (15)

and, as expected, have the correct limit when \( A \to 0 \), becoming itself equal to that of the VL model
\[ \varepsilon(x) = \frac{B^2}{(1 + B^2x^2)}, \] (16)

but for a fixed value of the parameter \( B \), the VL model have a bigger and less concentrated energy density, as can be seen in the Fig. 2. On the other hand, it is interesting to note that one could introduce an alternative model through the superpotential
\[ W(\phi) = A \sinh(\phi) + |B| \tan^{-1}[\sinh(\phi)] - 2\sqrt{A|B|} \phi, \] (17)

which, for \( B < 0 \) and \( A > 0 \), and \( |B| > A \), generates a kind of asymmetrical version of the model above introduced.

Now, we can discuss the linear stability of the model here presented. In fact, as shown in [9] for the case of coupled scalar fields, the linear stability of the model with one scalar field can be done as usual by performing small perturbations on the kink solution,
\[ \phi(x, t) = \phi_k(x) + \eta(x, t). \] (18)

Taking into account only up to the first-order terms in the perturbation, which leads to a Schroedinger-like equation for the perturbation field
\[ \left( -\frac{d^2}{dx^2} + V_{\phi\phi}(\phi = \phi_k(x)) \right) \eta(x) = \omega^2 \eta(x), \] (19)

where \( \eta(x, t) = \sum_{\alpha} \eta_{\alpha}(x) \cos(\omega_{\alpha} t) \). It is not difficult to see that the above equation can be achieved from the following ladder operators,
\[ a_\pm = \pm \frac{d}{dx} + W_{\phi\phi}, \] (20)

whose Hamiltonian operator \( \hat{H} = a_+ a_- \), as shown in [10] for general coupled real scalar fields, have their eigenvalues positive definite and, as a consequence, the models are stable under small quantum fluctuations.

In our case, the potential to which the small fluctuations feel, once again has the VL one as its limit, coming from above as can be observed in Fig. 3.

The bosonic ground stated, which is granted by the translational invariance in this case, in general can be obtained through the solution of the equation,
\[ \left( -\frac{d}{dx} + W_{\phi\phi} \right) \psi_0(x) = 0, \] (21)

FIG. 1. The potential as a function of the scalar field \( \varphi \). A typical profile for \( A \) significantly different of zero (thin line) and when \( A \) is close to zero.

FIG. 2. The energy density dependence in \( x \) when \( B = 2 \) and \( A = 0.5 \) (thin line) and the vacuumless case.
where, as a simplified notation, from now on we define that $W_{\phi\phi} = W_{\phi\phi}(\phi = \phi_{\text{kink}})$. Here we note that, one can rewrite the above equations as

$$\frac{d\psi_0(x)}{\psi_0(x)} = W_{\phi\phi} dx,$$  \hspace{1cm} (22)

but we know from the BPS equation that $dx = \frac{d\phi}{W_{\phi\phi}}$, in such a way that a direct relation between the bosonic zero-mode and the superpotential can be obtained,

$$\psi_0(x) = N_0 W_{\phi} = N_0 \frac{\sqrt{A - B}(\text{sech}(\sqrt{A(B - A)x}))}{\sqrt{1 + (B - A)(\tanh(\sqrt{A(B - A)x}))^2}},$$  \hspace{1cm} (23)

where $N_0$ is the normalization constant, and his shape is quite similar to that of the VL model. This allow us to show that the normalization of the zero-mode is related to the BPS energy through

$$\int |\psi_0(x)|^2 dx = N_0^2 \int W_{\phi}^2 dx = N_0^2 \int W_{\phi} d\phi = N_0^2 E_{\text{BPS}} = 1,$$  \hspace{1cm} (24)

and we get finally the normalized bosonic zero-mode

$$\psi_0(x) = \frac{1}{\sqrt{E_{\text{BPS}}}} W_{\phi},$$  \hspace{1cm} (25)

apart from an arbitrary constant phase factor. Let us now try to calculate the fermionic zero-mode. Using in this case, as done by Bazela in [5], the Yukawa coupling giving by $f(\phi)\bar{\psi}\psi$, where it is chosen $f(\phi) = g W_{\phi\phi}$ ($g = 1$), in order to get a supersymmetric version of the model [11]), we reach the following equation for Dirac fermions

$$i \gamma^1 \frac{d\Psi}{dx} + f(\phi) \Psi = 0, \quad \Psi = \begin{pmatrix} \psi_+ \\ \psi_- \end{pmatrix}.$$  \hspace{1cm} (26)

and using the representation where $i \gamma^1 \rightarrow \sigma_3$ we obtain the following equations for the spinor components,
FIG. 4. The potential as a function of the scalar field $\varphi$. A typical profile for $A$ significantly different of zero and for the BLM model (thin line).

Now, considering the cases where a supersymmetric extension of the model is allowed [11], $g = \pm 1$. The normalization of the fermionic zero-mode, becomes quite similar to that of its bosonic counterpart,

$$C_{\pm} = \sqrt{\frac{1}{E_{BPS}}}.$$  \hspace{1cm} (34)

Let us now briefly discuss the extension of this idea to other unusual kink models. For instance we take as our next example, the model introduced recently by Bazeia, Losano and Malbouisson (BLM) [7]. This model is unbounded from below and presents no vacua, just a maximum at the origin. Notwithstanding, it has a kink (and antikink) connecting their two inflection points. Concretely, his potential is given by

$$V_{BLM}(\phi) = \frac{1}{2}(1 - \phi^2)^3.$$ \hspace{1cm} (35)

Following the idea above introduced, we now propose an alternative model which presents two local minima. In fact it is not yet a standard one, once it is also unbounded from below. For this case the “parent” model is defined as

$$V_{P}(\phi) = \frac{1}{2}(1 - \phi^2)(A - 1 + \phi^2)^2.$$ \hspace{1cm} (36)

Both potentials are plotted in Fig. 4. Once again, when one takes the limit $A \rightarrow 0$, the BLM model is recovered. Again there is no problem in considering $g = \pm \frac{1}{2}$, when calculating the fermionic zero mode. The kink solution of the parent model in this case is given by

$$\phi(x) = \pm \tanh \left( \frac{1}{A} \tanh \left( \sqrt{A(1-A)x} \right) \right).$$ \hspace{1cm} (37)

In fact this is nothing but the deformation of the first model proposed here, precisely in the same way in which the BLM model can be viewed as a deformation of the VL model [7].

Finally, let us make a brief comment about the case of the Liouville model, where

$$V(\phi) = \left( \frac{m}{\beta} \right)^2 e^{\beta \phi},$$ \hspace{1cm} (38)

which evidently does not presents any vacuum. It is possible to create a model composing a series of exponential factors, in such a way that we could have a parent model also here. However, at least this simple extension is not exactly solvable. In this case only a numerical solution is available in principle, and we are not going to consider it.

Our last comment in this work, is that we think that it is possible to find orthodox parent kink models for those which unorthodox features, like the VL, BLM and Liouville models. At least when it is possible, as shown in the case of the VL model here, we get a kind of regularization of the kink features, softening some of his properties.

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