ARTIFICIAL SATELLITES: RESONANCE EFFECTS PRODUCED BY TERRESTRIAL TIDE

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Abstract: Effects due to resonances in the orbital motion of artificial satellites disturbed by the terrestrial tide are analyzed. The nodal co-rotation resonance, apsidal co-rotation resonance and the Lidov-Kozai's mechanism are studied. The effects of the resonances are analyzed through the variations of the metric orbital elements. Libration and circulation motions for high orbits with high eccentricities are verified for the Lidov-Kozai's mechanism.

Keywords: Artificial Satellites. Resonances. Terrestrial Tide.

1 Introduction

Recent applications of artificial satellites require the description of the orbital motion under a precision of centimeters. In order to attain such actual expected level, several perturbations must be considered simultaneously, as well as resonant effects. Also for the analysis of the coupled effects it is mandatory the knowledge of each effect take separately.

The resonant dynamics involving the orbital motion of artificial satellites have been extensively used for communication and navigation, for example, justifying the study of resonant orbits in the last years (Rossi 2008, Formiga and Vilhena de Moraes 2008, Sampaio et. al. 2011). This studies are done using orbital perturbations such as due to the geopotential, lunisolar perturbations, solar radiation pressure, spin-orbit coupling, considering commensurabilities between the artificial satellite's mean motion and the Earth's rotational motion. The perturbation considered in this work is the terrestrial tide.

The influence of resonances in the orbital motion problem perturbed by tides has been observed by Kaula (1969), Kozai (1965), Sampaio and Vilhena de Moraes (2008) and Sampaio (2009).

In this work the objective is to analyze the nodal co-rotation resonance, apsidal co-rotation resonance and the Lidov-Kozai's mechanism related to this problem.

2 The terrestrial tide effect

2.1 The disturbing function

The disturbing function due to the tide effect can be written as (Kozai 1973, Kozai 1965):

$$R_{OE} = n_1^2 \beta \frac{R^5}{r^3} \left(\frac{a_1}{r_1}\right)^3 k_2 P_2(\cos(\theta)) \tag{1}$$

where k_2 is the Love's number; β is the reduced mass $m_1/(m+m_1)$; n_1 is given by $G(m+m_1)/a_1^3$, G is the gravitational constant, m is the mass of the Earth, m_1 is the mass of the Moon and a_1 is the semi-major axis of the Moon around the Earth; r is the geocentric distance of the satellite; r_1 is the geocentric distance of the Moon; $P_2(cos(\theta))$ is the second order Legendre polynomial in the development of the potential that describes the perturbation due to the tide.

The disturbing function can be written as:

$$R_{OC} = R_{OC_S}(a, a_1, e, I, I_1) + R_{OC_{IP}}(a, a_1, e, I, I_1, \omega, \Omega, \Omega_1)$$
(2)

and then, the secular part can be put in the following form:

$$R_{OC_S} = \frac{1}{32a^3} n_1^2 \beta R^5 k_2 (2 + 27 e^2 (\cos(I))^2 (\cos(I_1))^2 +18 (\cos(I))^2 (\cos(I_1))^2 - 9 e^2 (\cos(I_1))^2 -9 e^2 (\cos(I))^2 - 6 (\cos(I_1))^2 + 3 e^2 - 6 (\cos(I))^2)$$
(3)

The long period terms are given by:

$$\begin{split} R_{OCLP} &= -\frac{3}{128a^3} n_1^2 \beta \, R^5 k_2 (-6 \, e^2 (\cos{(I)})^2 \cos{(2\omega)} + 6 \, e^2 \cos{(2\omega)} \\ &- 12 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I_1)} \cos{(2\omega - \Omega + \Omega_1)} \\ &+ 12 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(-2\omega - \Omega + \Omega_1)} \\ &- 48 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I)} \cos{(I_1)} \cos{(2\Omega_1 - 2\Omega)} \\ &+ 12 \, e^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega)} \\ &+ 3 \, e^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &+ 3 \, e^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 6 \, e^2 \cos{(I)} \cos{(I_1)}^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 6 \, e^2 \cos{(I)} \cos{(I_1)}^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 12 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &+ 3 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &+ 3 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 6 \, e^2 \cos{(I)} (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &+ 3 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &+ 3 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &+ 18 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &+ 18 \, e^2 (\cos{(I)})^2 (\cos{(I_1)})^2 \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &+ 12 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 3 \, e^3 \cos{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &+ 12 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &+ 12 \, e^2 \sin{(I)} \sin{(I_1)} \cos{(I_1)} \cos{(I_1)} \cos{(2\Omega_1 - 2\Omega - 2\omega)} \\ &- 3 \, e^2 (\cos{(I)})^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 6 \, e^2 \cos{(I)} \cos{(2\Omega_1 - 2\Omega + 2\omega)} \\ &- 3 \, e^2 \cos{(2\Omega_1 - 2\Omega - 2\omega)} + 8 \, (\cos{(I)})^2 \cos{(2\Omega_1 - 2\Omega)} \end{split}$$

3 The nodal co-rotation resonance

Initially, the analysis of the resonance will be done through the nodal co-rotation resonance, due to the argument $(\Omega - \Omega_1)$ in the long period part of the disturbing function. Considering that $\Omega = \Omega_0 + n_\Omega t$, will be considered here the 1:1 resonance between the ascending node longitude of the satellite and the disturbing body, in this case the Moon.

3.1 Terrestrial tide

Through the Lagrange planetary equations the following result for the precession of the ascen-ding node longitude Ω can be obtained:

$$n_{\Omega} = -\frac{3}{16} \frac{n_1^2 \beta R^5 k_2 \cos(I)}{n a^5 \sqrt{1 - e^2}} (9 e^2 (\cos(I_1))^2 + 6 (\cos(I_1))^2 - 3 e^2 - 2)$$
(5)

with

$$n^2 = \frac{Gm}{a^3} \tag{6}$$

The family of orbits with nodal co-rotation resonance can be obtained isolating the semi-major axis (a) and using the Eqs. (5) and (6) we get:

$$a = \sqrt[7]{\frac{9}{256} \frac{1}{Gmn_{\Omega}^{2}(1 - e^{2})}} (n_{1}^{2}\beta^{2}R^{10}k_{2}^{2}cos(I)^{2}(9e^{2}cos(I_{1})^{2} + 6cos(I_{1})^{2} - 3e^{2} - 2)^{2})^{1/7}$$

$$(7)$$

Due to the nodal co-rotation condition we get:

$$n_{\Omega} = n_{\Omega_1} \tag{8}$$

where the period of n_{Ω_1} is about 18.6 years (Roncoli 2005). We also have:

$$n_{\Omega_1} = \frac{2\pi}{T} \tag{9}$$

being T the period of 18.6 years.

Therefore, it was derived an equation for the semi-major axis of the satellite as a function of the eccentricity and inclination. The other terms that appear in the Eq. (7) are constants.

The variation of a as a function of e for some values of the inclination is given in Fig. 1.

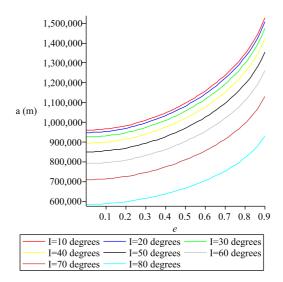


Figure 1. Semi-major axis a function of the eccentricity for some inclination values (Nodal co-rotation resonance)

The analysis of this type of resonance is not viable for the exact 1:1 resonance, since, in this case we will get semi-major axis smaller than the Earth's radius. But it can be studied what happens when n_{Ω} approaches to zero in the region next to the 1:1 resonance. It can be observed that when n_{Ω} decreases about two orders of magnitude, possible values for the semi-major axis begin to appear considering high eccentricities.

Figure 2 shows a simulation considering n_{Ω} near to zero.

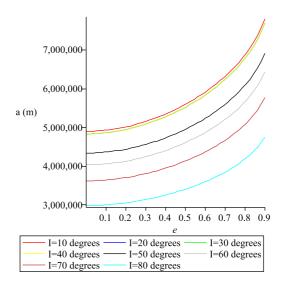


Figure 2. Variation of the semi-major axis with the eccentricity for some inclinations (nodal co-rotational resonance for n_{Ω} near to zero)

It is interesting to question how the occurrence of a quasi-commensurability can affect the motion of an artificial satellite. Of course, the more next to an entire number is the ratio between the periods, but the artificial satellite can be affected with this effect (Callegari Jr 2006). This can be observed in Fig. 2.

4 The apsidal co-rotation resonance

Another analysis that is also done in this work is about the argument $(2\omega - \Omega + \Omega_1)$ present in the disturbing function due to the terrestrial tide. In this case, the exact resonance between the argument of perigee and the longitude of the ascending node of the disturbing body is 2:1.

With the same considerations done in the previous topics, when analyzing the nodal co-rotational resonance, we get the following equation for n_{ω} :

$$n_{\omega} = \frac{3}{16na^{5}\sqrt{1-e^{2}}} n_{1}^{2} \beta R^{5} k_{2} (15 (\cos(I))^{2} (\cos(I_{1}))^{2} - 3 (\cos(I_{1}))^{2} + 3 e^{2} (\cos(I_{1}))^{2} - 5 (\cos(I))^{2} + 1 - e^{2})$$

$$(10)$$

Inserting in the Eq. (10) the mean motion of the satellite given by Eq. (6) and isolating the value of the semi-major axis (a) we get:

$$a = \sqrt[7]{\frac{9}{256} \frac{n_1^4 \beta^2 R^{10} k_2^2}{Gm n_{\omega}^2 (1 - e^2)}} ((15\cos^2(I)\cos^2(I_1) - 3\cos^2(I_1) + 3e^2\cos^2(I_1) - 5\cos^2(I) + 1 - e^2)^2)^{1/7}$$
(11)

Figure 3 shows the variation of a with respect the eccentricity $(0.0001 \le e \le 0.9)$, considering some values for the inclination.

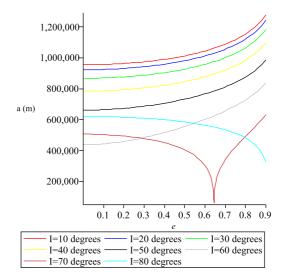


Figure 3. Apsidal co-rotation resonance: Variation of the semi-major axis with respect the eccentricity

In the Fig. (3), a great variation in the semi-major axis can be observed for some given inclinations and eccentricities. A simulation shows that for small variations of inclination, above 60° , and for high eccentricities, large variations occur in the semi-major axis. This phenomenon motivated the study of the Lidov-Koza's mechanism that will be seen in the next section.

5 Lidov-Kozai's mechanism

In this section an analysis of resonance, involving the argument 2ω , is done through the disturbing function.

This kind of phenomenon was first observed by Kozai (1962) and Lidov (1962) and is known as the Lidov-Kozai's mechanism. The Lidov-Kozai's mechanism has been studied for asteroids as in Kozai (1962), for Uranus's satellites as Kinoshita and Nakai (1999, 2007), for Jupiter's satellites as in Yokoyama et. al. (2003) and for artificial satellite orbiting the Moon as in Carvalho et. al. (2008).

The disturbing function, considered only the secular terms and periodic terms involving the argument 2ω , is:

$$U_{LK} = \frac{1}{32a^3} n_1^2 \beta R^5 k_2 (2 + 27 e^2 (\cos(I))^2 (\cos(I_1))^2 + 18 (\cos(I_1))^2 (\cos(I))^2$$

$$-9 e^2 (\cos(I_1))^2 - 9 e^2 (\cos(I))^2 - 6 (\cos(I_1))^2 + 3 e^2 - 6 (\cos(I))^2$$

$$+ \frac{3}{128a^3} n_1^2 \beta R^5 k_2 (6 e^2 (\cos(I))^2 \cos(2\omega) - 6 e^2 \cos(2\omega)$$

$$+18 e^2 (\cos(I_1))^2 \cos(2\omega) - 18 e^2 (\cos(I))^2 (\cos(I_1))^2 \cos(2\omega)$$
(12)

As it was done by Kinoshita and Nakai (1999, 2007), graphics for curves of the same energy in the (ω,e) plane will be done here. The study of the Lidov-Kozai's mechanism is based on the parameter h, related with the z component of the angular momentum, given by:

$$h = (1 - e^2)\cos^2(I) = const.$$
 (13)

To generate the energy's curves, firstly the Eq. (12) must be written in terms of the eccentricity, of the argument of perigee and of the parameter h.

This can be done using Eq. (13).

As an example, it will be initially considered here a semi-major axis of about 6960 Km for the orbit of the artificial satellite.

Figures (4) to (8) present the (ω, e) plane for some values of h.

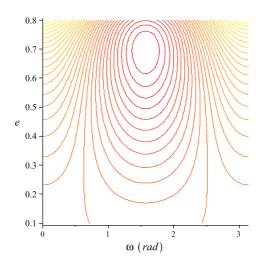


Figure 4. (ω, e) plane for h=0.1

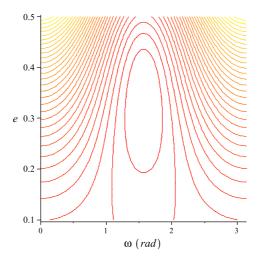


Figure 5. (ω , e) plane for h=0.3

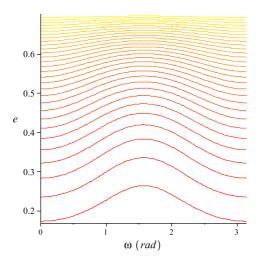


Figure 6. (ω, e) plane for h=0.5

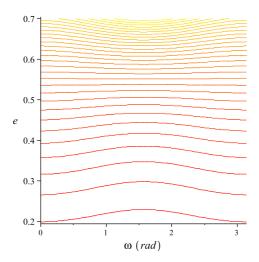


Figure 7. (ω, e) plane for h=0.7

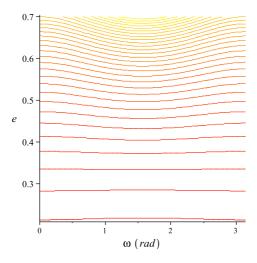


Figure 8. (ω , e) plane for h=0.9

For the considered semi-major axis we found a libration motion for small values of h (h=0.1 and h=0.3) and circulation for values near to 1 (h=0.7 and h=0.9). However, the libration and circulation motions shown in Figs. (4) to (8) occur for high eccentricities, which would be a not practical orbit. In fact, with the adopted semi-major axis, this would result perigee distance shorter than the Earth's radius.

For an artificial satellite orbiting the Earth, the Lidov-Kozai's mechanism would have influence, through the tide perturbation, for orbital semi-major axis greater than the one presented previously.

Analyzing the orbit of a satellite with semi-major axis of about 26500km, it is observed that as the eccentricity is greater than 0.75, the distance of perigee is near to the terrestrial surface and can be affected significantly by other disturbing forces such as atmospheric drag, or even collide with the Earth's surface if the eccentricity reach 0.8. Starting from (e=0.75), when the eccentricity decreases, the perigee distance of the satellite became not as near from the terrestrial surface as in the precedent case.

Figures (9) to (17) show the (ω, e) plane for h varying from 0.1 to 0.9.

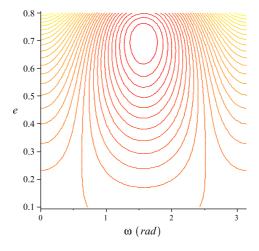


Figure 9. (ω, e) plane for h=0.1

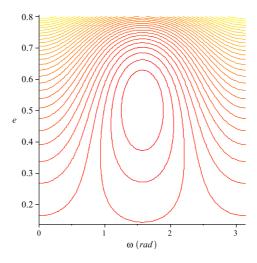


Figure 10. (ω, e) plane for h=0.2

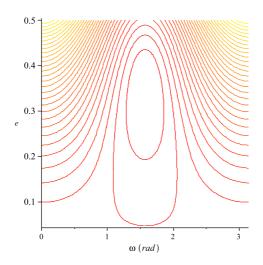


Figure 11. (ω, e) plane for h=0.3

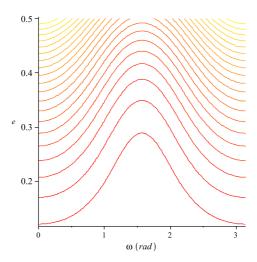


Figure 12. (ω, e) plane for h=0.4

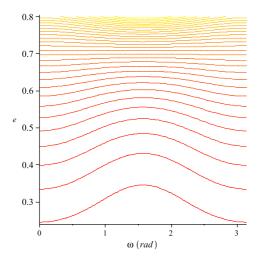


Figure 13. (ω , e) plane for h=0.5

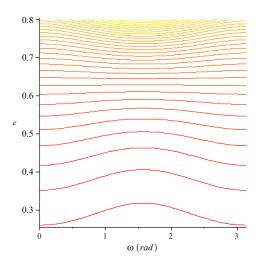


Figure 14. (ω, e) plane for h=0.6

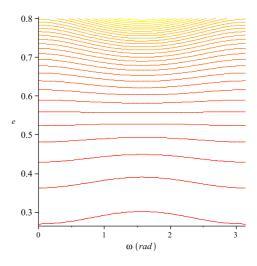


Figure 15. (ω, e) plane for h=0.7

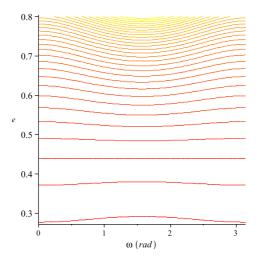


Figure 16. (ω , e) plane for h=0.8

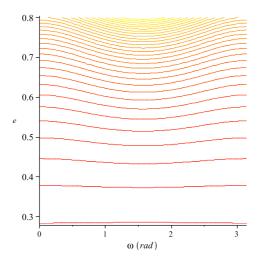


Figure 17. (ω, e) plane for h=0.9

For a satellite with the considered semi-major axis, and with the considered ranges for the variation of the constant h, a libration motion is possible when $0.1 \le h \le 0.3$. This can be observed in the Figs. (9) to (17). For values of h near to 0.1 librations occur but due to the high eccentricities, collision can occur with the Earth.

6 Conclusion

Some influences of the terrestrial tide on the orbital motion of artificial satellites were analyzed and the existence of resonances that can affect the motion was studied. Three types of resonance were analyzed: the nodal co-rotation resonance, the apsidal resonance and the Kozai's resonance.

According to Kozai (1965), the most important resonant term expected in the present study is the term with argument $\Omega - \Omega_1$ in the Lagrange equation providing time variation for the inclination. The Lagrange equations for the time variation of the eccentricity and for the longitude of the ascending node, also present terms with this argument.

Beyond the nodal co-rotation resonance, was also analyzed the influence on the orbital motion of the apsidal co-rotation resonance, relating the argument of pericentre and the longitude of the ascending node of the Moon, through a resonance of the type 2:1.

The sign of the variables of the arguments, as well as, the sign of the solutions for n_{Ω} has influence, if the motion is prograde or retrograde.

Now analyzing the Lidov-Kozai's mechanism, it is observed that for the low altitude satellite considered, the values of the eccentricity are large enough to occur collision with the Earth's surface. Now, for a satellite with semi-major

axis of about 26500 km, where the tidal effects in the orbital elements are still appreciable, there are possibilities of libration for h=0.2 and h=0.3 and circulation for values greater than h=0.3. For h=0.2, considering the range of values of eccentricity varying from 0.1 to 0.7, the inclination varies with values ranging from 63.29^0 to 51.23^0 for the prograde motion and 116.71^0 to 128.77^0 for the retrograde motion. For h=0.3 the eccentricity varies from 0.1 to 0.5. This corresponds to a variation of the inclination of 56.60^0 to 50.77^0 for the prograde motion and for the retrograde motion of 123.40^0 to 129.23^0 .

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