

Environmental dependence of the galaxy stellar mass function in the Dark Energy Survey Science Verification Data

J. Etherington,^{1★} D. Thomas,^{1,2} C. Maraston,^{1,2} I. Sevilla-Noarbe,³ K. Bechtol,^{4,5}
J. Pforr,⁶ P. Pellegrini,^{7,8} J. Gschwend,^{7,8} A. Carnero Rosell,^{7,8} M. A. G. Maia,^{7,8}
L. N. da Costa,^{7,8} A. Benoit-Lévy,^{9,10} M. E. C. Swanson,¹¹ W. G. Hartley,¹²
T. M. C. Abbott,¹³ F. B. Abdalla,^{14,15} S. Allam,¹⁶ R. A. Bernstein,¹⁷ E. Bertin,^{9,18}
D. Brooks,¹⁴ E. Buckley-Geer,¹⁶ M. Carrasco Kind,^{19,20} J. Carretero,^{21,22}
F. J. Castander,²¹ M. Crocce,²¹ C. E. Cunha,²³ S. Desai,²⁴ P. Doel,¹⁴ T. F. Eifler,^{25,26}
A. E. Evrard,^{27,28} A. Fausti Neto,⁸ D. A. Finley,¹⁶ B. Flaugher,¹⁶ P. Fosalba,²¹
J. Frieman,^{16,29} D. W. Gerdes,²⁸ D. Gruen,^{23,30} R. A. Gruendl,^{19,20} G. Gutierrez,¹⁶
K. Honscheid,^{31,32} D. J. James,¹³ K. Kuehn,³³ N. Kuropatkin,¹⁶ O. Lahav,¹⁴
M. Lima,^{8,15} P. Martini,^{31,34} P. Melchior,³⁵ R. Miquel,^{22,36} J. J. Mohr,^{37,38,39} B. Nord,¹⁶
R. Ogando,^{7,8} A. A. Plazas,²⁶ A. K. Romer,⁴⁰ E. S. Rykoff,^{23,30} E. Sanchez,³
V. Scarpine,¹⁶ M. Schubnell,²⁷ R. C. Smith,¹³ M. Soares-Santos,¹⁶ F. Sobreira,^{8,41}
G. Tarle,²⁸ V. Vikram,⁴² A. R. Walker¹³ and Y. Zhang¹⁶

Affiliations are listed at the end of the paper

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ABSTRACT

Measurements of the galaxy stellar mass function are crucial to understand the formation of galaxies in the Universe. In a hierarchical clustering paradigm, it is plausible that there is a connection between the properties of galaxies and their environments. Evidence for environmental trends has been established in the local Universe. The Dark Energy Survey (DES) provides large photometric data sets that enable further investigation of the assembly of mass. In this study, we use ~ 3.2 million galaxies from the (South Pole Telescope) SPT-East field in the DES science verification (SV) data set. From grizY photometry, we derive galaxy stellar masses and absolute magnitudes, and determine the errors on these properties using Monte Carlo simulations using the full photometric redshift probability distributions. We compute galaxy environments using a fixed conical aperture for a range of scales. We construct galaxy environment probability distribution functions and investigate the dependence of the environment errors on the aperture parameters. We compute the environment components of the galaxy stellar mass function for the redshift range $0.15 < z < 1.05$. For $z < 0.75$, we find that the fraction of massive galaxies is larger in high-density environment than in low-density environments. We show that the low-density and high-density components converge with increasing redshift up to $z \sim 1.0$ where the shapes of the mass function components are indistinguishable. Our study shows how high-density structures build up around massive galaxies through cosmic time.

Key words: galaxies: clusters: general – galaxies: evolution – galaxies: formation – galaxies: photometry – galaxies: statistics.

* E-mail: james.etherington@port.ac.uk

1 INTRODUCTION

Establishing an understanding of the assembly of mass in galaxies is a key goal in modern extragalactic physics and cosmology. Measurements of the galaxy stellar mass function through cosmic time for different populations of galaxies and as a function of environment are vital to inspect the nature of the assembly and also constrain models of the physical processes.

It is widely assumed that dark matter accumulated and collapsed in a hierarchical fashion (White & Frenk 1991). Λ CDM simulations (Boylan-Kolchin et al. 2009) are able to emulate the clustering of structure observed in large-scale galaxy surveys in the local Universe (Springel, Frenk & White 2006). However, there are unresolved issues. The observed pattern of ‘downsizing’ (Cowie et al. 1996) remains a challenge even though some aspects of it can be understood in Λ CDM models assuming that there is some threshold of halo mass for efficient star formation (Conroy & Wechsler 2009). Several flavours (Fontanot et al. 2009) of downsizing have now been observed: chemo archaeological (Worthey, Faber & Gonzalez 1992), archaeological (Thomas et al. 2005; Thomas et al. 2010), downsizing in the star formation rate (SFR; Conselice et al. 2007), stellar mass (Pozzetti et al. 2007; Maraston et al. 2013), metallicity (Maiolino et al. 2008), nuclear activity (Cristiani et al. 2004; Hasinger, Miyaji & Schmidt 2005) and most recently black hole growth (Hirschmann et al. 2012).

The question of galaxy assembly is undoubtedly tied to the old adage: ‘nature versus nurture’. Disentangling the internal and external physical processes involved is a taxing business. Modern works are providing clues; some by examining the environmental dependence of central and satellite galaxies separately (e.g. for groups – Carollo et al. 2013; Cibinel et al. 2013; Pipino et al. 2014). The mass, either the stellar mass or the total mass of the dark matter halo, is widely thought to be the primary driver of galaxy evolution. This is a secular channel of evolution championing the ‘nature’ argument. In the hierarchical clustering paradigm where a tree of haloes merges and accretes forming larger structures, it may follow that a galaxy’s environment also has a role to play.

Galaxies are subject to several external physical processes including ram pressure stripping (Boselli & Gavazzi 2014; Fumagalli et al. 2014), galaxy harassment (Farouki & Shapiro 1981), strangulation (Larson, Tinsley & Caldwell 1980) and cannibalism (Nipoti et al. 2003). These processes are certainly capable of stripping gas, shutting down star formation and transforming a galaxy’s morphology. But to what degree are these processes ubiquitous in the Universe?

In a hierarchical scenario, it is clear that a galaxy’s environment is not constant through cosmic time. It is in fact changing. The key parameter may therefore be the galaxy’s integrated environment through time. Devising an observational proxy for this is challenging, perhaps even intractable with the snapshot observations we capture with modern galaxy surveys. The problem is not merely one of data collection but also of definition. In simulations for example, how do you define or even identify a galaxy’s environment when its constituent parts have not yet assembled?

Galaxy surveys such as the SDSS have revolutionized the study of the galaxy population at low redshift (Blanton & Moustakas 2009). Surveying large areas provides large statistics and reduces the error associated with cosmic variance. The first measurements of the galaxy stellar mass function of the local Universe were obtained by converting luminosity functions by simple modelling of the M/L of galaxies (Cole et al. 2001; Bell et al. 2003; Kodama & Bower 2003). There are now several measurements of the galaxy

stellar mass function for the local Universe (Baldry, Glazebrook & Driver 2008; Li & White 2009; Baldry et al. 2012) based on stellar masses derived from galaxy photometry. The GAMA survey has augmented SDSS with additional spectroscopic data to obtain mass complete samples to $\sim 10^8 M_\odot$ yielding the current state-of-the-art mass function measurements in the local Universe (Baldry et al. 2012).

Investigations of the redshift evolution of the stellar mass function have until recently been restricted to data collected from spectroscopic pencil beam surveys. However, the BOSS survey enabled Maraston et al. (2013) to study the evolution of the massive end of the stellar mass function using a sample of 400 000 LRGs to a redshift of ~ 0.6 . The massive end of the mass function was found to be consistent with passive evolution in agreement with other works (Ilbert et al. 2010, 2013; Pozzetti et al. 2010).

Pencil beam surveys such as the DEEP2 (Newman et al. 2013) and zCOSMOS (Lilly et al. 2007) surveys have typically captured data for no more than a few square degrees of the sky but they are complete to relatively high redshifts. These analyses exploit the measurements of 1000s to several tens of 1000s of galaxies. Some studies focus on the mass functions for the total galaxy population whereas others have also investigated the contributions made by different galaxy types; split by morphology and colour. There are relatively few works that have examined the role of galaxy environment on the stellar mass function. The earliest of these studies split galaxies into two types: field or cluster (Balogh et al. 2001; Kodama & Bower 2003). More recent studies have quantified the environments and then examined the mass function for different environment bins for the local Universe (McNaught-Roberts et al. 2014), intermediate redshifts (Bundy et al. 2006; Bolzonella et al. 2010; Vulcani et al. 2011) and high redshifts (Mortlock et al. 2015). The main finding of these works is that the massive end of the galaxy stellar mass function is dominated by galaxies that reside within high-density environments at low and intermediate redshifts, but at higher redshifts the mass function is independent of environment. Davidzon et al. (2016) show the weakening of the environmental dependence of the mass function between redshifts of 0.5 and 0.9.

Future studies of the galaxy stellar mass function require surveys of larger cosmological volumes. This is currently only feasible with large-scale photometric surveys as spectroscopic surveys with a similar volume to DES, for example, would be too costly and slow. Large number statistics therefore come at the cost of redshift precision.

The aim of this work is to study the contributions to the stellar mass function from different environments as a function of redshift exploiting the Dark Energy Survey (DES) science verification (SV) data taken before the first season of the survey’s operation.

The paper consists of six sections. In Section 2, we describe the data and the galaxy parameters. In Section 3, we present the galaxy environment measurements. In Section 4, we show the mass function analysis. In Section 5, we discuss the robustness of the main results and lastly in Section 6, we present our conclusions.

In this work, we have assumed a Salpeter (1955) initial mass function, a cosmology with $\Omega_m = 0.286$, $\Omega_\Lambda = 0.714$ and $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$ and have adopted comoving coordinates (e.g. Cooper et al. 2006) to calculate the distances between galaxies.

2 DATA AND GALAXY PARAMETERS

The DES is a multiband (g, r, i, z, Y) photometric survey performed with the Dark Energy Camera (DECam; Flaugher et al. 2015) mounted on the 4-metre Blanco Telescope at Cerro Tololo

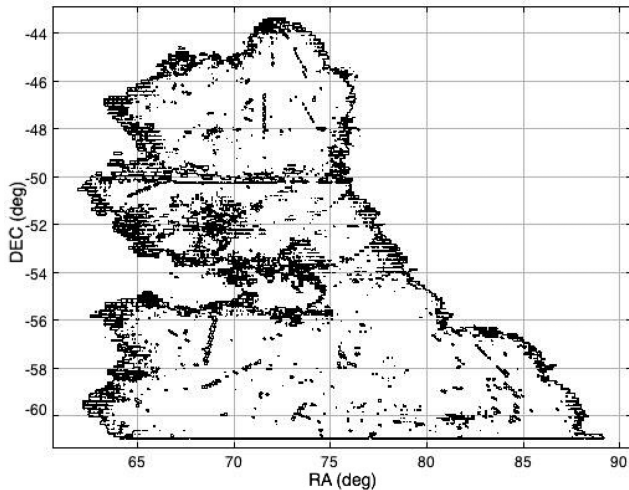


Figure 1. Edges and holes of the SPT-E field. The field has a uniform depth of 23 mag in *i*-band integrated apparent magnitude.

Inter-American Observatory (CTIO), aimed at imaging 5000 deg² of the southern sky out to redshift ~ 1.4 . The survey started in 2013 February but from 2012 November to 2013 February, DES carried out an SV survey. These observations provide science quality data for more than 250 deg² at close to the main survey's nominal depth (*i*-band 2-arcsec aperture magnitude $\simeq 24$ mag) for standard survey fields (e.g. SPT-E field) and/or deeper fields (used for calibration and/or supernovae studies). A number of analyses of the SV data have now been released (Dark Energy Survey Collaboration et al. 2016; Palmese et al. 2016) including weak lensing shear measurements (Jarvis et al. 2016), CMB lensing tomography (Giannantonio et al. 2016), systematics (Leistedt et al. 2016; Crocce et al. 2016), LRG selection (Rozo et al. 2016) and a study of the galaxy populations in massive clusters (Hennig et al. 2016).

The data stored in the catalogue of the SV co-added imaging created by the DES Data Management (DESDM) pipeline (Sevilla et al. 2011; Desai et al. 2012; Mohr et al. 2012) were then thoroughly tested and analysed by a team of DES scientists, who were able to construct a new photometric catalogue, called the *SV Annual 1 (SVA1) Gold* catalogue, containing 25 227 559 objects and extending over an area ~ 250 deg². This catalogue is now publicly available.¹

In this work, we use the Portsmouth Constant Mag_Mode1 Depth Originated Region (COMMODORE) galaxy catalogue (see Capozzi et al., in preparation), a subsample of the Gold SVA-1 catalogue. The COMMODORE catalogue was constructed to have homogeneous depth (*i*-band integrated magnitude = 23 mag) so that it could be used for galaxy evolution studies and a bright end limit (*i*-band integrated magnitude = 16 mag) to aid star–galaxy separation. The total area covered by this catalogue is ~ 155 deg². However, this area is not contiguous and for galaxy environment studies that require area contiguity, a subsample of the COMMODORE catalogue must be selected. In this paper, we select from the COMMODORE catalogue only the galaxies in the SPT-E (~ 130 deg²) field (which is the largest field in the SV data set) to ensure the contiguity requirement is met. Fig. 1 shows the perimeter of the SPT-E field and the holes in the data (due to bright stars) after all of the processing steps have been applied.

2.1 Photometric redshifts

There are two types of methods used to measure photometric redshifts: template methods and training methods. Sánchez et al. (2014) performed extensive tests on the SV data using 13 different photometric redshift codes. The codes were trained with ~ 6000 spectroscopic redshifts obtained from existing data sets including VVDS Deep (Le Fèvre et al. 2005, 2013), VVDS Wide (Garilli et al. 2008), SDSS/BOSS (Eisenstein et al. 2001; Strauss et al. 2002; Ahn et al. 2012), ACES (Cooper et al. 2012) and 2dFGRS (Colless et al. 2001) that matched the DES SV photometry. Sánchez et al. (2014) found that two of the training methods, one based on artificial neural networks (ANNz; Collister & Lahav 2004) and the other on prediction trees and random forests, called *Trees for Photo-z* or TPZ (Carrasco Kind & Brunner 2013), performed the best. The scatter of the difference between the photometric redshifts and the test set of spectroscopic redshifts for these methods was $\delta_{68} = 0.08$.

In this paper, we utilize the output from the TPZ code because in addition to the best estimate of the redshift, this code provides photometric redshift probability distribution functions (PDFs) for each galaxy. The photo-*z* PDFs consist of 200 bins spanning the redshift range: 0–1.8. Each bin has a width of 0.009 in redshift.

We computed the 1σ width of each photo-*z* PDF and identified the galaxies at the 16th, 50th and 84th percentiles in the distribution of widths. The half-widths at these percentiles are: 0.041, 0.055 and 0.079, respectively. We note that the 1σ width of the photo-*z* PDFs as measured here for all of the SPT-E galaxies is a different quantity from the scatter (δ_{68}) measured between the peaks of the PDFs and the spectroscopic redshifts measured in Sánchez et al. (2014).

In this paper, we are interested in the propagation of the redshift errors into the derived galaxies properties: mass, absolute magnitude and galaxy environment. This in turn enables us to quantify errors on the environment components of the galaxy stellar mass function.

2.2 *K*-corrections, absolute magnitudes and stellar masses

The galaxy properties used in our study are taken from the COMMODORE catalogue, which provides both galaxy physical properties (e.g. age, star formation history and stellar mass) and detectability related properties (e.g. *k*-correction, maximum accessible volumes and completeness factors as function of apparent magnitude and surface brightness). The physical properties are obtained via spectral energy distribution (SED) fitting, using 32 sets of theoretical templates (as in Maraston et al. 2006 and Capozzi et al. 2016) constructed with the evolutionary stellar population synthesis models by Maraston (2005) and Maraston et al. (2009) under the assumption of a Salpeter (1955) initial mass function (IMF). These templates consist of four types of star formation histories including: single bursts (SSPs), exponentially declining, truncated SFR and constant SFR. The SED fitting was performed by means of the template fitting code HYPERZ (Bolzonella, Miralles & Pelló 2000), using the DES photometry and fixing galaxy redshifts at the photometric values provided by the TPZ code. For each galaxy, we then calculated detectability using the real observed-frame magnitudes calculated at given redshift for the galaxy's best-fitting model found above. We use tables² that provide for each of the 32 sets of templates, their observed-frame magnitudes (assuming a standard cosmology) for a fine grid of redshifts including $z = 0$. The difference between the model magnitude at given z and the same at $z = 0$ is then the

¹ <http://des.ncsa.illinois.edu/releases/SVA1>.

² Maraston, in preparation, available upon request.

exact value of the fainting or brightening to be applied in the exact filter, without going through approximated k -corrections. These Δ s are then applied to the i -band absolute magnitudes.

In evolutionary studies, it is important to estimate the completeness of the galaxy sample in absolute magnitude and stellar mass as a function of redshift. To do this, we follow a similar procedure as described in Pozzetti et al. (2010). We obtain the completeness limits by computing the 90th percentiles of the limiting stellar mass and absolute magnitudes within redshift bins for the faint and bright ends of the sample. Limits are constructed for the bright end in addition to the faint end because of the i -band apparent magnitude selection (see Section 2) applied to construct the COMMODORE catalogue. We refer the reader to Capozzi et al. (in preparation), where the Portsmouth COMMODORE catalogue, the completeness limits and the galaxy property calculations are presented in detail.

2.3 Error analysis

The main aim of this section is to quantify the errors on the derived galaxy properties, i.e. the stellar masses and the i -band absolute magnitudes due to the errors on the photometric redshifts. We adopt a Monte Carlo approach and generate many realizations of the SPT-E catalogue by drawing redshifts from the photo- z PDFs. An alternative is to start with the errors on the photometry itself and propagate them forward (e.g. Taylor et al. 2009). We use the photo- z PDFs as this makes our study easier to reproduce or modify as the SV photo- z PDFs are publicly available (see Section 2). Since the TPZ photo- z PDFs are constructed using the photometric errors, these approaches are comparable.

In Section 2.3.1, we present a series of tests on the redshift draws to: (i) verify that the draws are representative of the photo- z PDFs and (ii) quantify the difference between the statistics of the draws and the photo- z PDFs as a function of the number of catalogue realizations. We compute the stellar masses and i -band absolute magnitudes for the galaxies in each of the realizations of the SPT-E catalogues using HYPERZ as described in Section 2.2. In Section 2.3.2, we present the distributions of the galaxy properties and their errors.

2.3.1 Sampling tests

To investigate the variability due to the photometric redshift errors, we generated 100 realizations of the SPT-E catalogue drawing redshifts from the photo- z PDFs. To do this, we constructed the photo- z cumulative distribution functions from the photo- z PDFs for each galaxy. The cumulative distribution function maps the range 0–1 to the possible redshifts for a galaxy. We drew random numbers from a uniform distribution spanning 0–1 and used the mappings to obtain redshift draws.

To verify that the sampled redshift draws were representative of the photo- z PDFs, we calculated summary statistics. We obtained the ‘true’ mean and variance of each photo- z PDF. The mean is simply the expectation of the distribution:

$$\mu = E(z) = \sum z_i p_i. \quad (1)$$

It is the sum of the redshift mid positions of the bars multiplied by the probabilities (heights) of the bars. The variance is the expectation of the squared distribution minus the expectation squared:

$$\sigma^2 = E(z^2) - (E(z))^2, \quad E(z^2) = \sum z_i^2 p_i. \quad (2)$$

The mean of the randomly generated redshift draws was calculated using:

$$\hat{z} = \frac{1}{N_{\text{draws}}} \sum z \quad (3)$$

and the variance of the redshift draws was calculated using:

$$\hat{\sigma}^2 = \frac{1}{N_{\text{draws}} - 1} \sum (z - \hat{z})^2. \quad (4)$$

The range of 5–100 draws of each galaxy was investigated.

Using these summary statistics, the biases and root mean squared errors (RMSE) between the ‘true’ statistics (mean and variance) and the statistics from the samples as a function of the number of draws were calculated. The bias and RMSE of the mean are given by

$$\text{Bias of the mean} = \frac{1}{N_{\text{gal}}} \sum (\mu - \hat{z}), \quad (5)$$

$$\text{RMSE of the mean} = \sqrt{\frac{1}{N_{\text{gal}}} \sum (\mu - \hat{z})^2} \quad (6)$$

and the bias and RMSE of the variance are given by

$$\text{Bias of the variance} = \frac{1}{N_{\text{gal}}} \sum (\sigma^2 - \hat{\sigma}^2), \quad (7)$$

$$\text{RMSE of the variance} = \sqrt{\frac{1}{N_{\text{gal}}} \sum (\sigma^2 - \hat{\sigma}^2)^2}. \quad (8)$$

Fig. 2 shows the bias (top) and RMSE (bottom) for the mean (left) and variance (right) as a function of the number of redshift draws for each galaxy. Plots (a) and (b) show that the bias of the mean and the variance are approximately zero. This is expected as these estimators are unbiased. The plots show the random errors generated from the sampling process are of the order of $\sim 10^{-5}$ centred on zero. The RMSE for the mean decreases as approximately the square root of the number of redshift draws of each galaxy. The RMSE for the variance falls off slightly more rapidly with the number of draws, with a power of -0.52 .

For 100 random catalogues, the RMSE of the mean is 0.0076 and RMSE of the variance is 0.0028 as shown in Fig. 2. In addition, we found that the RMSE of the standard deviation for the 100 catalogues is 0.0082. These numbers are between 5 and 10 times smaller than the typical width of the photo- z PDFs. Individual examples have been examined and with 100 draws minor offsets between the statistics of the samples and the PDFs can be introduced. PDFs that have multiple peaks, separated by relatively large redshifts can be sampled less effectively with only a small number of draws. Nevertheless, the precision quoted here is sufficient for the purposes of this study. Since the errors decrease approximately as the square root of the number of draws, 4 times as many random catalogues (i.e. 400 catalogues) would be required to halve the RMSEs.

2.3.2 Galaxy properties: distributions and errors

In this section, we present the collated results for the galaxy properties: redshifts, i -band absolute magnitudes and stellar masses derived from the 100 Monte Carlo simulations.

For each of the 3 207 756 galaxies in the SPT-E field we computed the median, 16th and 84th percentiles (out of the 100 values) of the drawn redshifts, i -band absolute magnitudes and stellar masses. We

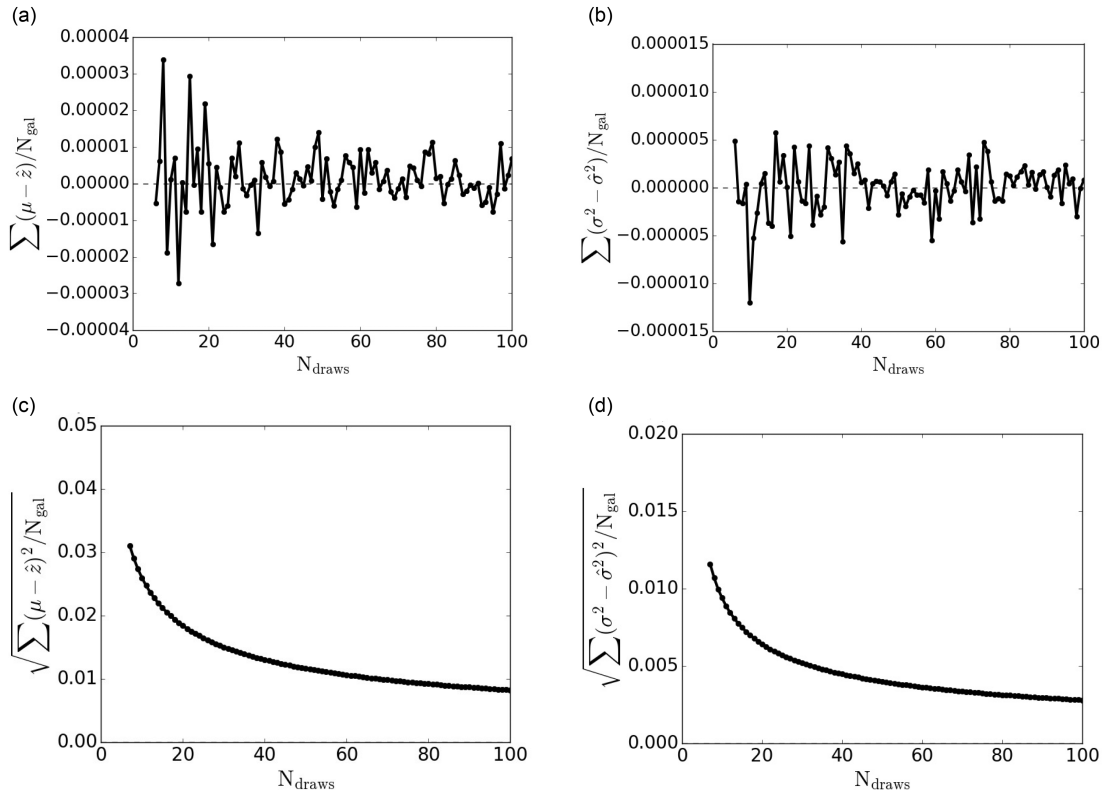


Figure 2. Top: bias for the mean (left) and variance (right) as a function of the number of draws. Bottom: RMSE for the mean (left) and variance (right) of the redshift draws as a function of the number of draws.

quote the 1σ error (for each property) for each galaxy as half the difference between the 84th and 16th percentiles.

Fig. 3 shows the (median) distributions of the redshifts, i -band absolute magnitudes and stellar masses in the first row, the distribution of errors on the properties in the second row, the TPZ redshift dependence of the property errors in the third row and the dependence of the property errors on the properties themselves in the fourth row. The left-hand column shows the galaxy redshifts. The middle column shows i -band absolute magnitudes and the right-hand column shows the galaxy stellar masses. Throughout this paper, the units of stellar mass are solar masses and stellar mass is plotted on a logarithmic scale. In the first row, the vertical red dashed lines show the median values and the vertical blue dashed lines show the 16th and 84th percentiles of the redshift, i -band absolute magnitude and mass distributions. We quote the ranges of the property distributions in the plots as the difference between the 84th and 16th percentiles. In the second row, the red vertical dashed lines mark the median property errors. We quote the median errors for comparison with the ranges of the distributions themselves quoted in the first row.

The ranges of the distributions are: 0.56, 2.62 and 1.36 for redshift, i -band absolute magnitude and stellar mass, respectively, and in the same order the median errors for these quantities are 0.054, 0.256 and 0.118. The ratios of the ranges of the property distributions to the median property errors are: 10.3, 10.2 and 11.5 for redshift, i -band absolute magnitude and mass, respectively. This quantification suggests that all three of these properties can be studied, as the median error due to the photometric redshifts is an order of magnitude smaller than the ranges of the distributions of these properties.

The third row of plots in Fig. 3 shows the median errors (in redshift bins) on the properties as a function of the galaxies' TPZ

redshifts. The redshift error corrected by a factor of $1+z$ is essentially constant at ~ 0.035 across the redshift range $0 < z < 1.0$. The error at $z \sim 0.7$ is slightly smaller compared to the rest of the range. This is around the peak of the redshift distribution shown in plot (a). The errors on the i -band absolute magnitudes and stellar masses behave in a similar way to each other. The errors are particularly large for $z < 0.25$ and increase as the redshift is decreased. The errors stabilize at larger redshifts to values of < 0.4 and < 0.2 for the i -band absolute magnitude and stellar mass, respectively. There is a 'sweet' spot for both properties in the redshift range $0.6 < z < 0.7$ where the error is < 0.2 for the i -band absolute magnitude and < 0.1 for the stellar mass.

The fourth row of plots in Fig. 3 shows the average 16th and 84th percentile property errors as a function of the median values of the properties themselves. As expected, the redshift error dependence on the median redshift shown in plot (j) is similar to the dependence on the TPZ redshift shown in plot (g). The error dependence for the i -band absolute magnitude and masses also mirror each other. The errors are largest for the least luminous and least massive galaxies. This is in line with expectation as fainter galaxies are more difficult to measure. The i -band absolute magnitude error is relatively stable and < 0.25 for galaxies with an absolute magnitude brighter than -20.0 . Similarly, the mass error is relatively constant at < 0.2 for $\log(M) > 8.5$.

3 GALAXY ENVIRONMENT

In this section, we present the galaxy environment measurements. We proceed with the Monte Carlo approach and compute galaxy environments for all 100 catalogue realizations to determine the error on the environment measurements of each galaxy. In Section 3.1,

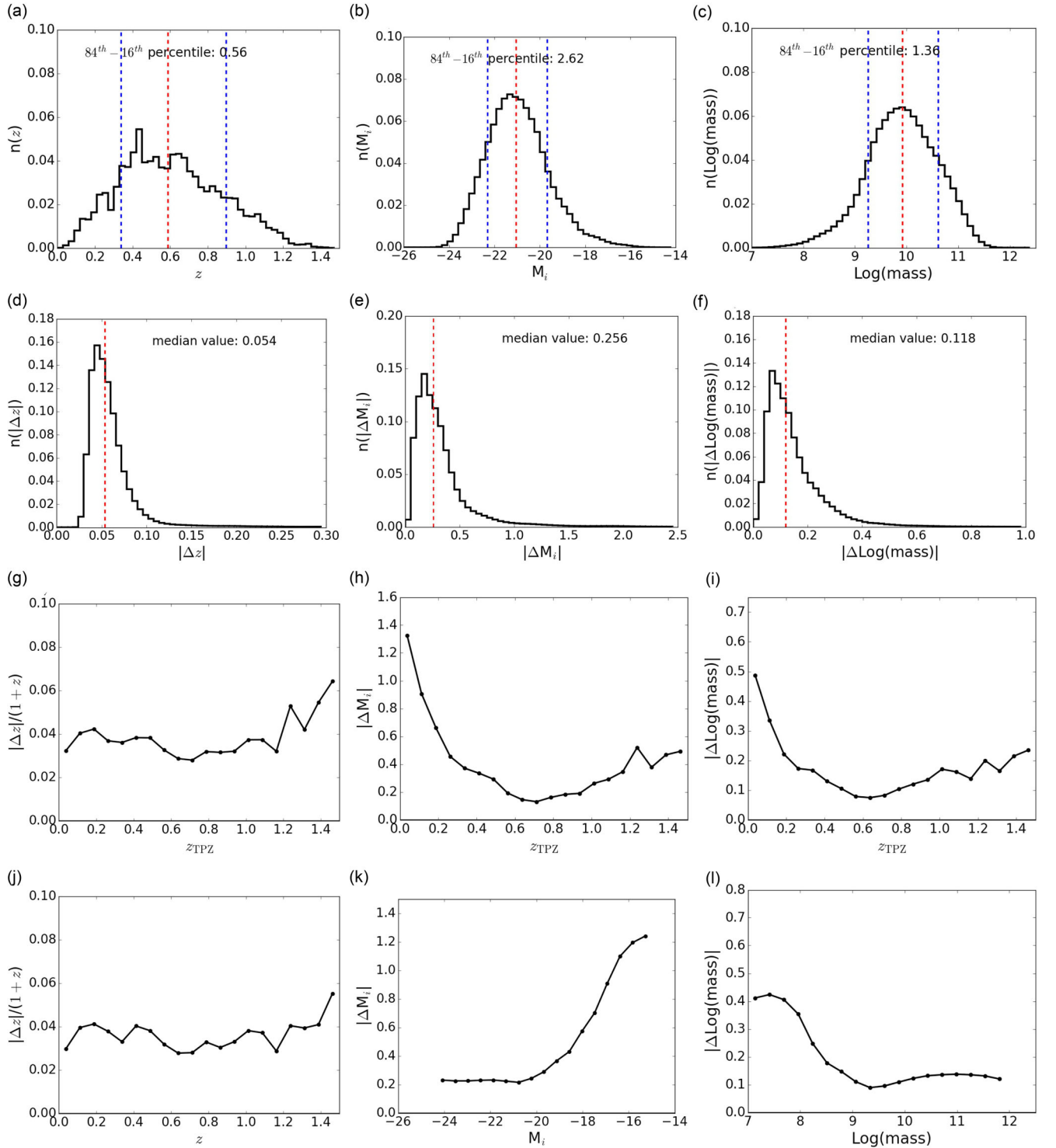


Figure 3. First row: property distributions, second row: error distributions, third row: TPZ redshift dependence of the property errors and fourth row: property dependence of the errors. The first column is for redshift, the second column is for the i -band absolute magnitude and the third column is for the stellar masses. Stellar mass has units of solar masses. The red vertical dashed lines show the median values. The blue vertical dashed lines show the 16th and 84th percentiles.

we describe the method we use to quantify galaxy environment. In Section 3.2, we study the environment measurements and their errors as a function of the aperture parameters. In Section 3.3, we characterize the environment measurements that we employ later in the galaxy stellar mass function analysis. In Section 3.4, we present the results of the Monte Carlo simulations as environment PDFs.

3.1 Environment measurements

In preparation for photometric surveys, there have been a number of studies that have investigated the impact of redshift precision on measurements of galaxy environment. Cooper et al. (2005) concluded that for pencil beam surveys such as DEEP2 redshift measurements with errors >0.02 were unsuitable to measure

local galaxy densities. However, more recently Fossati et al. (2015) showed using a semi-analytical model that it is possible to measure trends with galaxy environment. Etherington & Thomas (2015) examined the impact of redshift precision with a focus on large-scale surveys using the SDSS data and found that the environmental signal in photometric data can be measured but needs to be optimized with a careful choice of aperture parameter values.

3.1.1 Method

Galaxy environment has been measured with a variety of methods (e.g. Carollo et al. 2013) including Voronoi Tessellation, fixed aperture, N th nearest neighbour methods and numerous variants of these. (see Muldrew et al. 2012 and Haas et al. 2012 for compilations).

In this work, we employ a fixed aperture method. In this method, a number density is calculated by counting the number of density tracing galaxies (see Section 3.1.2) found within an aperture centred on the target galaxy (the target galaxy is not included within the count) and dividing this by the volume of the aperture. There are three reasons for this choice of method: (i) fixed aperture methods are arguably easier to interpret because they compute densities over fixed scales, (ii) Shattow et al. (2013) showed that fixed aperture methods provide more robust measurements over cosmic time and (iii) fixed aperture methods are computationally less expensive compared to N th nearest neighbour methods.

Several different aperture volumes have been used in previous studies including spheres (Croton et al. 2005), cylinders (Gallazzi et al. 2009), annuli (Wilman, Zibetti & Budavári 2010), cones (Etherington & Thomas 2015) and ellipsoids (Schawinski et al. 2007; Thomas et al. 2010). In photometric surveys, the errors in the redshift measurements along the line of sight are much greater than the errors in the angular measurements. The most appropriate aperture for a photometric survey is therefore conical in shape as this volume most effectively encompasses adjacent lines of sight.

The aperture that we adopt is approximately a conical frustum, i.e. the volume that is left when you slice off the top of a cone. The volume is therefore calculated by taking the difference of two cones. We control the volume of the aperture with two parameters: the radius (r) of the cross-section of the cone at the target galaxy and the (Δz) half-length of the aperture. In this study, we investigate a range of radii: 0.1–3.0 Mpc and half-lengths: 0.08–0.3 (in redshift). We count the number of density tracing galaxies (see Section 3.1.2) within the aperture and compute a density. Apertures that are found to be devoid of galaxies are assigned a nominal minimum density of 0.5 galaxies per aperture. The density for each galaxy is then turned into a density contrast with respect to the mean density ρ_m using the equation below:

$$\delta = (\rho - \rho_m) / \rho_m \quad (9)$$

The mean density ρ_m is calculated within a redshift window centred on the target galaxy. We compute $\text{Log}(1 + \delta)$ and refer to this quantity as the galaxy environment.

3.1.2 Density defining populations

The distribution of stellar matter is a biased tracer (Kaiser 1984) of the large-scale structure in the Universe. Maps of the total mass, baryonic and dark matter combined, have now been created using weak lensing measurements from the DES (Vikram et al. 2015).

We follow the approach that has been adopted in previous galaxy environment studies (e.g. Baldry & Balogh 2006; Peng et al. 2010;

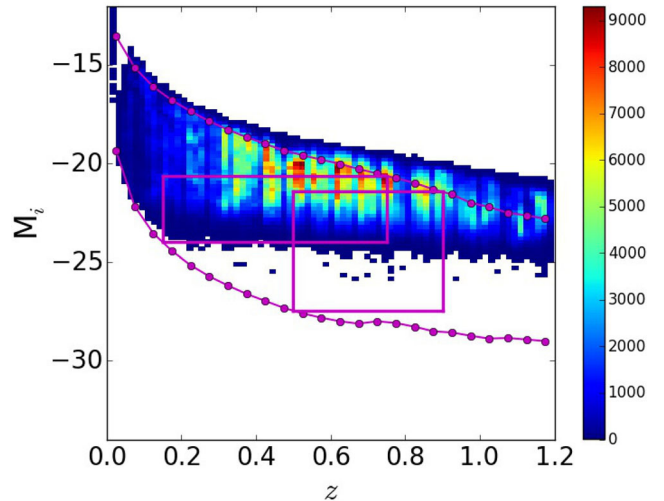


Figure 4. Sample selection in the M_i -redshift plane. In this example, the TPZ redshifts are used. The vertical magenta lines mark the redshift bounds. The number of galaxies in each two-dimensional bin is represented with a colour as indicated in the colour bar. The magenta curves mark the lower and upper i -band absolute magnitude completeness limits. The magenta rectangular regions enclose the faint (low redshift) and bright (high redshift) density tracers. There is an overlapping redshift range between the faint and bright tracers that enables comparisons. Selection for each of the 100 Monte Carlo simulations is performed in the same way using the redshifts drawn from the photo- z PDFs and the corresponding i -band absolute magnitudes.

Thomas et al. 2010) and use only the galaxy distribution and assume this is an adequate proxy to trace the underlying density field.

Populations of intrinsically faint galaxies are not detectable through the entire survey volume. To fairly trace the galaxy distribution, we constructed volume limited samples. We employed two density defining populations that we called the faint and bright tracers because of the cuts on the absolute magnitudes of the galaxies. We employ luminosity cuts on the sample, rather than cuts in stellar mass because luminosities are more closely related to the observations and are less model dependent.

Fig. 4 shows an example of the sample selection of the galaxies from the SPT-E field using the i -band absolute magnitudes and in this example their TPZ redshifts. The colour bar indicates the number of galaxies in each grid cell. The upper and lower magenta curves mark the i -band absolute magnitude completeness limits. The faint and bright tracers consist of the galaxies within the magenta rectangles. The completeness limits were used to determine the extremities of the tracers. The faint tracer has a redshift range $0.15 < z < 0.75$ and an i -band absolute magnitude range $-24.0 < M_i < -20.63$. The bright tracer has a redshift range $0.6 < z < 1.05$ and an i -band absolute magnitude range $-27.91 < M_i < -22.37$. We purposely designed an overlap of the redshift ranges of the two tracers to enable comparisons between the two tracers. Table 1 summarizes the properties of the faint and bright tracers. Selection for each of the 100 Monte Carlo simulations is performed in the same way using the redshifts drawn from the photo- z PDFs and the corresponding i -band absolute magnitudes.

3.1.3 Survey edge and holes

Galaxy environment measurements require contiguous regions to ensure densities are not underestimated. The boundaries of the homogenized SPT-E field are not regular and there are holes in the

Table 1. Density defining population properties.

Property	Faint tracer	Bright tracer
z	$0.15 < z < 0.75$	$0.6 < z < 1.05$
M_i	$-24.00 < M_i < -20.63$	$-27.91 < M_i < -22.37$
Radius	$r = 1.0$ Mpc	$r = 1.4$ Mpc
Half-depth	$\delta z = 0.1$	$\delta z = 0.2$
Range $\text{Log}(1+\delta)$	0.36	0.42
Median $\Delta\text{Log}(1+\delta)$	0.096	0.11
Ratio	3.8	3.8

data caused by bright stars. It is therefore important that the edges of the data are determined and appropriately managed. We used the HEALPix (Górski et al. 2005) software to identify the pixels that contained galaxies and those that did not. We populated the cells with random points. The density of random points was >10 times the average density of the galaxies. We then computed the angular distance between points that were inside the data footprint and the points outside of the footprint. We identified the set of points that were inside the footprint but were the closest to any point outside of the footprint. This set of random points defines the edge of the SPT-E data that we used in the scientific analysis. Fig. 1 shows the positions of the set of points that defines the edges of the footprint. To ensure the periphery of the data did not impact the environment measurements, we applied a conservative cut and discarded galaxies that were less than 0.1 away from an edge point but inside the footprint. After applying this cut, the area of the footprint was 78.09 deg^2 .

We manage the redshift boundaries by adjusting the depth of the aperture in the cases where the aperture would cross over the boundary. We reduce the half depth of the aperture (of the infringing half) to be the comoving distance from the target to the boundary. This ensures the aperture fits inside the redshift range. The depth of the other half of the aperture that resides within the redshift range is not changed.

3.2 Environments as a function of the aperture parameters

To investigate the impact of the aperture parameters on the environment measurements, we tested apertures with radii of 0.1 – 3.0 Mpc at 0.1 Mpc increments and half-depths of 0.08 – 0.3 at 0.02 increments in redshift.

Fig. 5 shows the range of the environment distribution of the galaxies in the density defining population as a function of the aperture parameters in the left column; the median error of the environment measurements as a function of the aperture parameters in the middle column and the ratio of the range to the environment error as a function of the aperture parameters in the right column. The top row is for the faint, low- z tracer. The bottom row is for the bright, high- z tracer. We define the range of the environment distribution as the difference between the 84th and 16th percentiles of the distribution.

The range of the environment distribution of the density defining population depends strongly on aperture radius and weakly on the aperture half-depth for both the faint and bright tracers. For both tracers, the environment range becomes larger as the radius decreases from 3.0 Mpc. This trend continues for the faint tracers

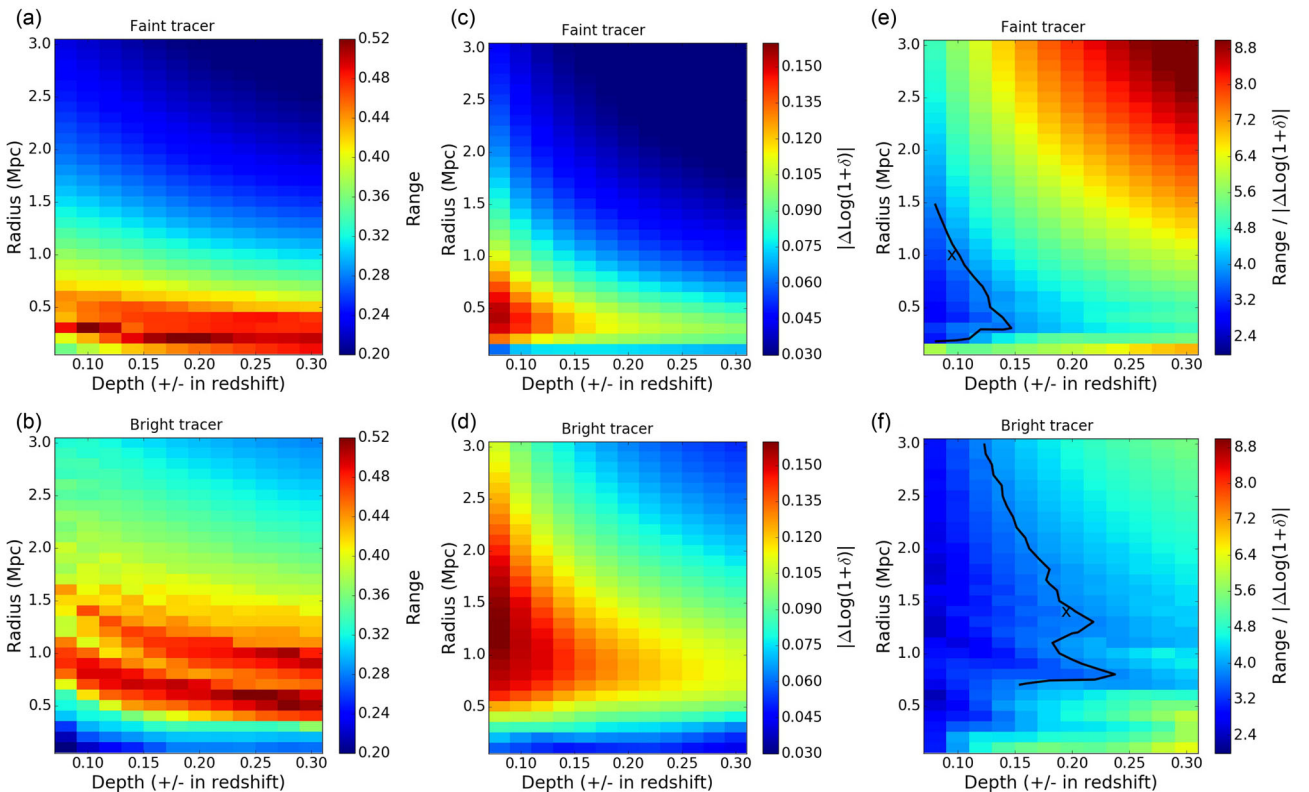


Figure 5. Left column: range of the environment distributions (difference between the 84th and 16th percentiles) as a function of the radius and depth of the aperture. Middle column shows the median error of the environment measurements as a function of the radius and depth. Right column shows the ratio of the range of the environment distribution to the median error as a function of the radius and depth. Top row is for the faint tracer and the bottom row is for the bright tracer. The contour lines in plots (c) and (f) are for a ratio of 3.8.

until a radius of 0.2 Mpc and for the bright tracer until a radius of 0.6 Mpc. Apertures with radii smaller than these values poorly sample the tracing population, because many apertures are devoid of galaxies. A larger aperture is required for the bright tracer because this tracer samples the density field more sparsely.

The middle column shows that the median environment error is a smooth function of both the aperture radius and half depth. The general trend is that the median environment error decreases as the volume of the aperture increases. Probing environments on large scales homogenizes the measurements as local contrasts are smoothed out. The median error is also small for radii less than 0.3 Mpc for the faint tracer and less than 0.6 Mpc for the bright tracer. These scales are approaching or beneath the average sampling scale of the tracing populations. The small environment errors at these scales are an artificial effect and these scales should not be employed for scientific analysis.

The ideal scenario is to have a large environment range and small measurement errors. However, the trends of increasing range and decreasing error depend on the aperture parameters, especially the radius in a counteracting fashion.

The right column shows the ratio of the tracing population environment range to the median environment error as a function of the aperture parameters. The black lines overplotted mark a constant ratio of 3.8. The black crosses mark the aperture parameters that we select to employ later. The plots show that the ratio increases with increasing depth and radius for both the faint and bright tracers. However, the trend is stronger for the faint tracer, illustrated with the stronger colour gradient. On the one hand, it is desirable for this ratio to be as large as possible to minimize contamination between environment bins but on the other hand it is necessary to probe signal from the scales where environmental processes have a role.

Previous studies have reported that environmental processes occur most readily on scales of ~ 1 Mpc or less (Blanton & Berlind 2007; Wilman et al. 2010). For scientific analysis employing the faint tracer, we therefore opt for a radius of 1 Mpc. The choice of depth for the faint tracer is a trade off between maximizing the ratio (between the range of the environment distribution and the median environment error) and the goal of measuring *local* environment. We opt for a half-depth of 0.1 (in redshift). The ratio with these aperture parameter values is ~ 3.8 . The choice for the bright tracer is more constrained. For the purposes of comparison between the faint and bright tracers, we choose aperture parameter values for the bright that lead to a similar ratio. For the bright tracer, we therefore choose a radius of 1.4 Mpc and a half-depth of 0.2 (in redshift) that also gives a ratio of ~ 3.8 . We note that with this choice of parameters the half-depths of the aperture are at least twice as large as the 1σ photometric redshift errors (see Fig. 3) across the whole range of redshifts we study and this ensures that the environment measurements are not severely affected by signal to noise issues. The number of apertures that are devoid of density defining population galaxies is less than 0.2 and 4.0 percent for the faint and bright tracers, respectively.

The ratio between the range of the distribution and the average error for the other galaxy properties (redshift, mass and *i*-band absolute magnitude) was ~ 10 – 12 as shown in Section 2.3.2. The environment measurements therefore have a distinguishing power that is only about 3 times less than the other parameters.

3.3 Environment characterization

We now characterize in more detail the environment measurements obtained with the aperture parameters chosen in Section 3.2. The

key properties, such as the redshift ranges, aperture parameters and environment properties are listed in Table 1.

Fig. 6 shows the environment distribution in the top left; the median environment error distribution in the top right; the median environment error as a function of the TPZ redshift in the bottom left and the median environment error as a function of the median environment in the bottom right for the faint (black) and bright (blue) tracers.

The environment distributions for both the faint and the bright tracers are approximately Gaussian and have widths of 0.36 and 0.42, respectively. The apertures are sufficiently large that a negligible number are devoid of galaxies and the distributions are roughly symmetrical. The shape and range of the faint and bright environment distributions are similar despite the fact that the apertures probe different volumes and different tracing populations. The environment distribution for the faint tracer is slightly narrower and more peaked than the distribution for the bright tracer. The error distributions shown in plot (b) have extended tails at the high error end. The median environment error for the faint and brighter tracer are 0.096 and 0.11. The faint tracer has a slightly smaller median error than the bright tracer. The ratio of the distribution width to the median environment error is approximately 3.8 for both tracers by construction. This value is sufficient to study trends with environment. The similarities in the overall properties of the environments for the faint and bright tracer are due to the constraint on this ratio. Plot (c) shows that the error on the environment measurements is relatively constant as a function of the TPZ redshift. The error increases slightly for each tracer as the TPZ redshift increases.

The errors for the faint and bright tracers are approximately the same in the redshift region ($z = 0.65$) where the tracers overlap. Plot (d) shows that the median error on the environment measurements decreases with increasing environment for both tracers from 0.2 for sparse environments to 0.05 for the most dense environments. The main reason for this is that high-density environments by definition contain many galaxies. Perturbing the number of galaxies in high-density regions due to the imprecise redshift measurements therefore has a much smaller effect than perturbing the number of galaxies in a low-density region because of the logarithmic definition of environment that is adopted in this work.

3.4 Environment PDFs

Using the results from the 100 Monte Carlo realizations, the environment measurements for each galaxy can be presented as PDFs. This is achieved for a galaxy by constructing a histogram of the relative frequencies of each environment from the 100 measurements. Fig. 7 shows three examples of environment PDFs based on the faint tracer. The top plot shows a galaxy in a low-density environment, the middle plot shows a galaxy in an intermediate-density environment and the bottom plot shows a galaxy in a high-density environment. The red histogram shows the distribution of median environments for the whole population of galaxies (i.e. it is the same as plot a) in Fig. 6). The vertical dashed line marks the median values of the environment PDFs. The distributions for these galaxies are peaked and their widths are clearly smaller than the distribution of environments for the entire population. With such environment PDFs, it is possible to split the galaxies into bins of environment, albeit with some unavoidable contamination. The impact of any contamination, however, is negligible given the large statistical sample in this study.

These three galaxies also illustrate the trend that as the environmental density increases, the error on the environment measurement

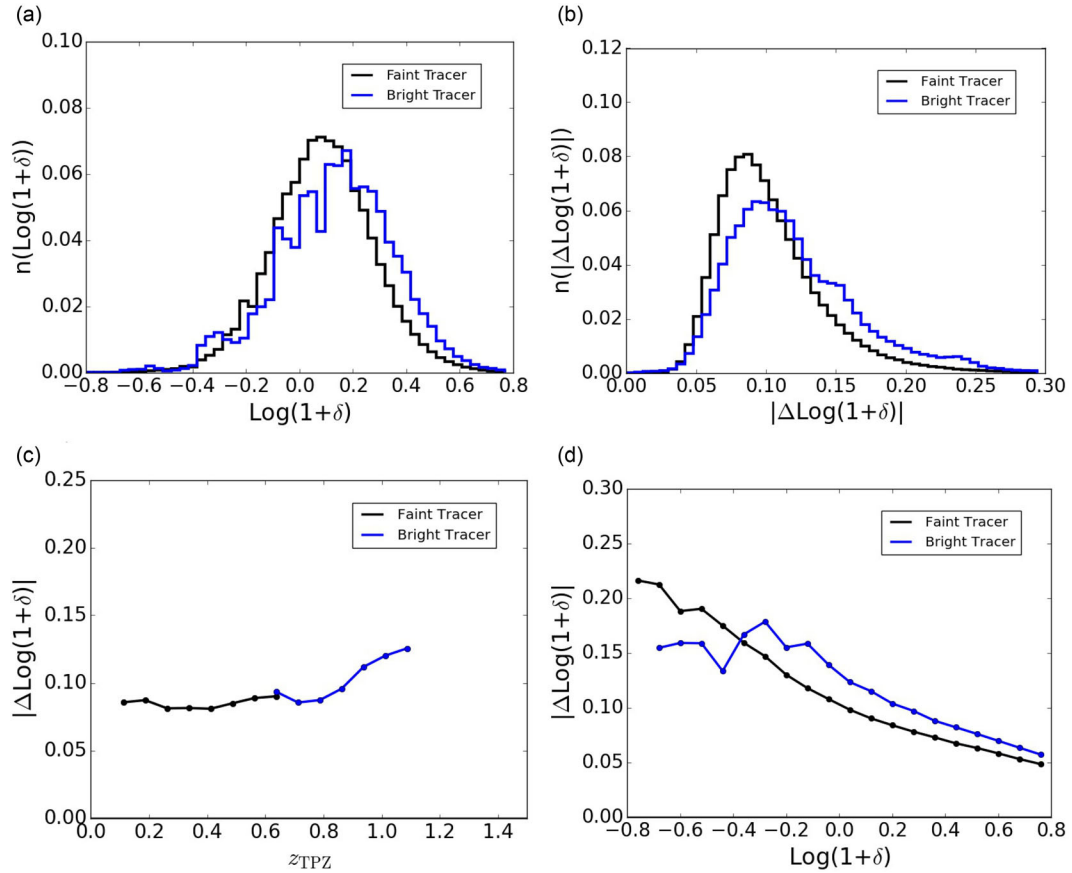


Figure 6. (a) environment distribution, (b) distribution of environment error, (c) TPZ redshift dependence of the environment error and (d) environment error as a function of environment for the faint (black) and bright (blue) tracers.

decreases. As the environmental density increases, the environment PDFs become more peaked and narrower.

The environment PDFs presented here enable more sophisticated statistical studies of galaxy environment in photometric surveys. The median environment measurement for each galaxy can be employed with an associated error or the complete environment PDFs can be folded into analyses. We demonstrate such an analysis in Section 4 by studying the environmental components of the galaxy stellar mass function.

4 MASS FUNCTION ANALYSIS

Analysis of the total galaxy stellar mass function for the DES SV data together with a detailed comparison with the literature is presented in Capozzi et al. (in preparation). In this section, we present an analysis of the environmental components of the galaxy stellar mass function using the mass and environment measurements we have described in the previous sections. We adopt a similar approach to Bundy et al. (2006), Bolzonella et al. (2010) and Davidzon et al. (2016). In Section 4.1, we describe the method we use to compute the mass functions. In Section 4.2, we present the results that are split into four parts: (i) the local Universe in Section 4.2.1, (ii) environmental components of the mass function for complete mass ranges in Section 4.2.2, (iii) the redshift evolution of the environmental components of the mass function for common mass ranges in Section 4.2.3 and (iv) the evolution of the environmental ratio of effective number of galaxies per unit volume in Section 4.2.4.

4.1 Method

We adopt the standard Schmidt–Eales ($1/V_{\max}$; Schmidt 1968) method to calculate the galaxy stellar mass function. The number of galaxies per comoving volume $\phi(M)$ for the mass interval ΔM is given by the sum over the N galaxies observed within this interval:

$$\phi(M) = \frac{1}{\Delta M} \sum_{i=1}^N \frac{1}{V_{\max,i} \cdot C_i} \quad (10)$$

In this equation, $V_{\max,i}$ is the maximum volume accessible by the i th galaxy. It is calculated by determining the minimum and maximum redshifts ($z_{\max,i}$ and $z_{\min,i}$) at which the galaxy could be detected in the survey, given the flux detection limits. These minimum and maximum redshifts are dependent on the galaxy SED and in particular on k -correction. C_i is the completeness factor of the i th galaxy. It depends on the galaxy’s surface brightness and apparent magnitude and takes a value between 0 and 1. The quantities used for determining $V_{\max,i}$ (i.e. $z_{\max,i}$ and $z_{\min,i}$) and the completeness factors C_i were provided by the COMMODORE catalogue as described in Section 2.2 and in more detail in Capozzi et al. (in preparation).

4.1.1 Evaluation of errors

In this analysis, we consider two main sources of errors: statistical errors and the propagated errors due to the imprecise photometric redshift measurements.

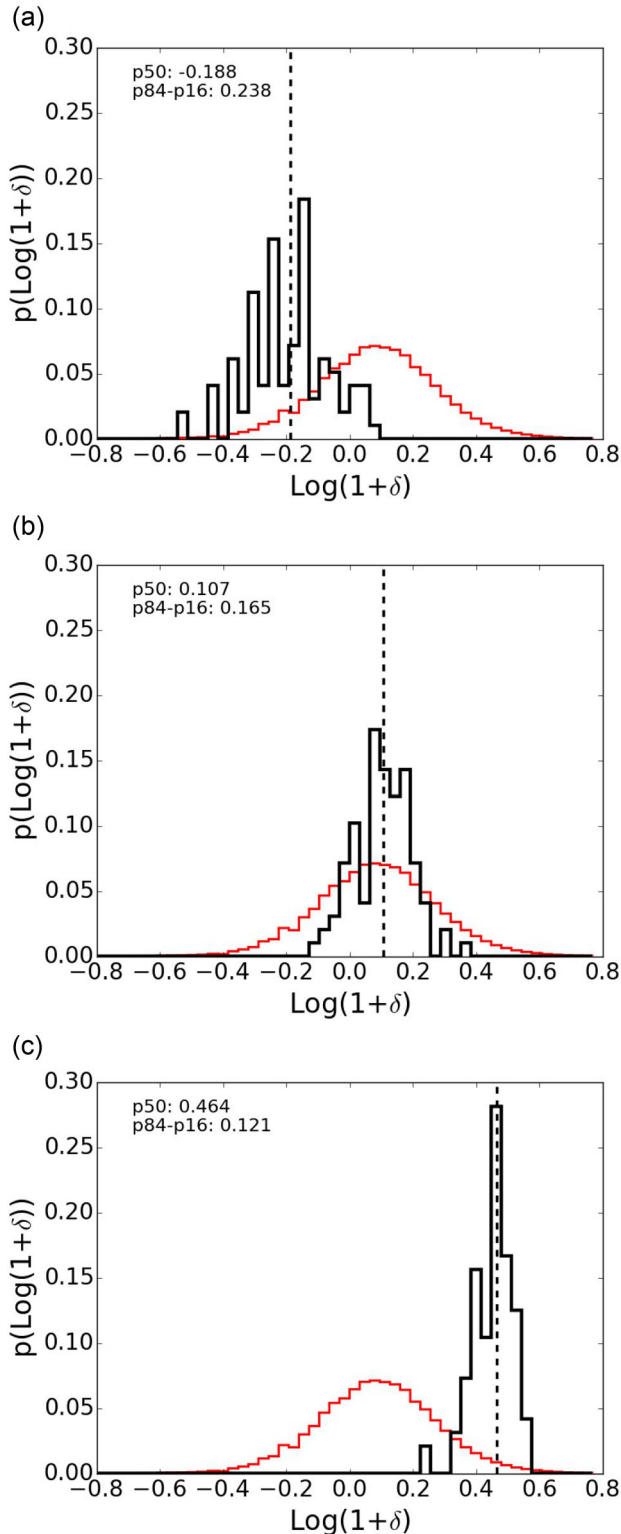


Figure 7. Three examples of environment PDFs: (a) low density (large error), (b) intermediate density (medium error) and (c) high density (small error) are shown in black. The environment distribution for the whole population of galaxies is shown in red in each plot. The vertical dashed lines marks the median of the environment PDFs. The difference between the 84th and 16th percentiles for the environment PDFs are quoted to quantify the width of the PDFs.

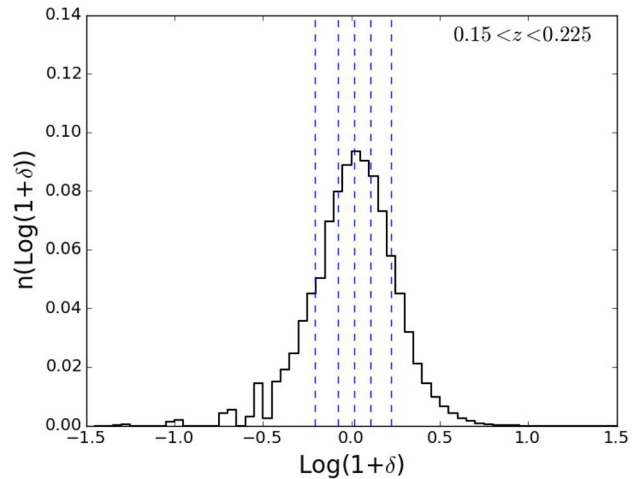


Figure 8. Environment distribution and dividing values for environment bins for the redshift range $0.15 < z < 0.225$. Environments are based on the faint tracer.

The statistical errors depend upon the number of galaxies in the sample in each bin of mass, redshift and environment. Analytical expressions for the statistical errors (Poisson statistics) are available but these usually assume the errors follow a Gaussian distribution. This is untrue particularly at the high-mass end. A further difficulty of adopting an analytical form for the statistical errors is incorporating the photometric redshift errors.

Therefore, we employ a bootstrap resampling scheme to evaluate the combined errors (statistical and redshift). This ensures that the redshift and environment PDFs of each galaxy are incorporated into the analysis. The 100 catalogue realizations form the basis of this scheme. We drew galaxies at random (with replacement) from the 100 catalogues to create 10 000 new catalogues. We divided the redshift range for each tracer into a number of bins. Each galaxy was weighted appropriately for the volume and surface brightness corrections and the environment distributions for each redshift bin in each resampled catalogue using only those galaxies within a particular mass range. We then split the environment distributions into a number (four or six) of equipercantage environment bins (for each redshift bin). Each environment bin therefore contained the same effective number of galaxies. To do this for each resampled catalogue, we determine the environments at the 25.0th, 50.0th and 75.0th percentiles for four environment bins or the 16.7th, 33.3rd, 50.0th, 66.7th and 83.3th percentiles for six environment bins. We computed the mean and standard deviation for each of these percentiles from the 10 000 catalogues to obtain robust dividing values between the environment bins. Fig. 8 shows the environment distribution for the redshift range $0.15 < z < 0.225$ divided into six environment bins. The dividing values between the bins are shown with the vertical dashed lines. Tables 2 and 3 list the limits of redshift, mass and environment bins for the analyses presented in Section 4.2. We note here that the percentile environment binning used in this study is not an evolving (in redshift) density cut as the large scale density contrast of the Universe evolves with time. Binning in this way allows us to study the relative shapes of the mass function components at different redshifts but not their absolute normalizations.

To calculate the number density error distributions, we identified the galaxies in each redshift, mass and environment bin in each of the resampled catalogues. We calculate the effective number of galaxies in each bin using the volume and surface brightness

Table 2. 16.67th, 33.33rd, 50.0th, 66.67th and 83.33rd percentile boundaries for the environment bins for the faint and bright tracers employing the complete mass range for each redshift bin. The numbers in brackets are the 1σ errors on the bin boundaries.

Tracer	Redshift range	Mass range	16.67th	33.33rd	50.0th	66.67th	83.33rd
Faint	0.15, 0.225	8.11, 11.35	−0.204 (0.0015)	−0.0776 (0.000 96)	0.0189 (0.0010)	0.110 (0.0014)	0.224 (0.0012)
	0.225, 0.3	8.61, 11.70	−0.173 (0.000 23)	−0.0669 (0.0016)	0.0365 (0.000 18)	0.126 (0.000 38)	0.229 (0.000 79)
	0.3, 0.375	8.88, 12.18	−0.163 (0.000 93)	−0.0529 (0.000 39)	0.0328 (0.000 62)	0.127 (0.000 43)	0.243 (0.0012)
	0.375, 0.45	9.33, 12.37	−0.165 (0.000 86)	−0.0332 (0.000 77)	0.0631 (0.0011)	0.154 (0.0013)	0.266 (0.000 87)
	0.45, 0.525	9.45, 12.61	−0.144 (0.000 70)	−0.0265 (0.000 55)	0.0640 (0.000 61)	0.151 (0.0013)	0.258 (0.000 65)
	0.525, 0.6	9.52, 12.68	−0.123 (0.000 87)	−0.0130 (0.000 55)	0.0687 (0.0013)	0.150 (0.000 88)	0.251 (0.0014)
	0.6, 0.675	9.72, 12.68	−0.126 (0.000 81)	−0.00392 (0.000 76)	0.0836 (0.000 68)	0.167 (0.000 80)	0.267 (0.0010)
	0.675, 0.75	9.87, 12.51	−0.113 (0.0015)	0.0158 (0.0013)	0.111 (0.0010)	0.202 (0.000 98)	0.310 (0.000 96)
Bright	0.75, 0.825	9.99, 12.54	−0.204 (0.000 24)	−0.0695 (0.000 85)	0.0399 (0.000 93)	0.164 (0.000 37)	0.275 (0.000 49)
	0.825, 0.9	10.2, 12.55	−0.194 (0.000 48)	−0.0465 (0.0020)	0.0756 (0.0021)	0.175 (0.000 55)	0.289 (0.0013)
	0.9, 0.975	10.5, 12.65	−0.173 (0.0027)	0.0127 (0.0027)	0.130 (0.0014)	0.228 (0.0017)	0.342 (0.0015)
	0.975, 1.05	10.7, 12.83	−0.0985 (0.0028)	0.0501 (0.0033)	0.170 (0.0016)	0.276 (0.0020)	0.392 (0.0028)

Table 3. 25.0th, 50.0rd and 75.0th percentile boundaries for the environment bins for the faint and bright tracers employing a common mass range for each tracer. The numbers in brackets are the 1σ errors on the bin boundaries. This binning scheme is used to study the redshift evolution of the components of the mass function.

Tracer	Redshift range	Mass range	25.0th	50.0rd	75.0th
Faint	0.3, 0.45	10.00, 12.00	−0.0571 (0.000 61)	0.0843 (0.000 84)	0.223 (0.000 77)
	0.45, 0.55	10.00, 12.00	−0.0550 (0.0022)	0.0845 (0.0012)	0.218 (0.000 96)
	0.55, 0.65	10.00, 12.00	−0.0471 (0.000 50)	0.0919 (0.000 59)	0.219 (0.000 55)
	0.65, 0.75	10.00, 12.00	−0.0391 (0.000 89)	0.113 (0.000 85)	0.251 (0.000 85)
Bright	0.65, 0.75	10.80, 12.40	−0.0373 (0.0010)	0.133 (0.0011)	0.278 (0.0024)
	0.75, 0.85	10.80, 12.40	−0.0645 (0.000 78)	0.110 (0.000 68)	0.272 (0.000 78)
	0.85, 0.95	10.80, 12.40	−0.0409 (0.0017)	0.127 (0.0020)	0.277 (0.0018)
	0.95, 1.05	10.80, 12.40	−0.0199 (0.0046)	0.161 (0.0030)	0.318 (0.0023)

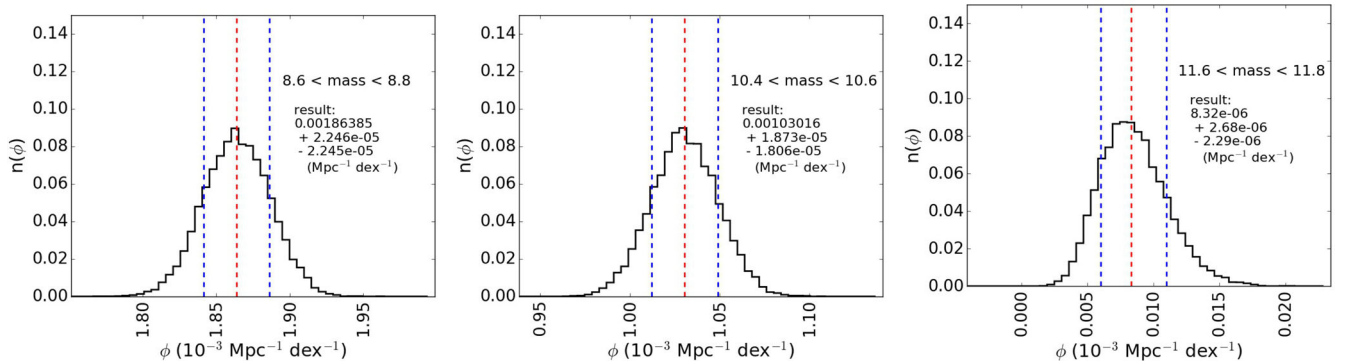


Figure 9. Three examples of the error distribution of the effective number density of galaxies in the redshift range: $0.16 < z < 0.25$ for a low-mass bin (left), intermediate-mass bin (middle) and a high-mass bin (right).

corrections and divide this by the survey volume for the associated redshift range. The variability in each bin between the 10 000 re-sampled catalogues is the number density error distributions. Fig. 9 shows three examples of the number density error distributions for the total mass function for the redshift range $0.15 < z < 0.225$. The left-hand plot is for a low-mass bin, the middle plot is for an intermediate-mass bin and the right plot is for a high-mass bin. The error as a fraction of the number density increases with mass as expected as the most massive galaxies in the Universe are the most rare. Nevertheless, the large number of galaxies within this sample leads to exquisite statistical errors. The error distributions are essentially Gaussian for the low- and intermediate-mass bins. The error distribution for the high-mass bin is not symmetrical and is skewed to larger values.

4.2 Results

We present two analyses of the environmental components of the galaxy stellar mass function. In the first analysis, we look at each redshift bin in turn and use the largest possible complete mass range for each redshift bin. We examine 12 redshift bins, the first starting at $z = 0.15$ and the last ending at $z = 1.05$. We employ the faint tracer for the eight lowest redshift bins and the bright tracer for the four highest redshift bins. In this analysis, all of the galaxies within the complete mass range are used to determine six equipercantage environment bins for each redshift bin. The redshift bins and the mass limits for this analysis are shown on the left-hand side of Fig. 10 and listed together with the environment boundaries in Table 2. This analysis enables a detailed examination of the mass

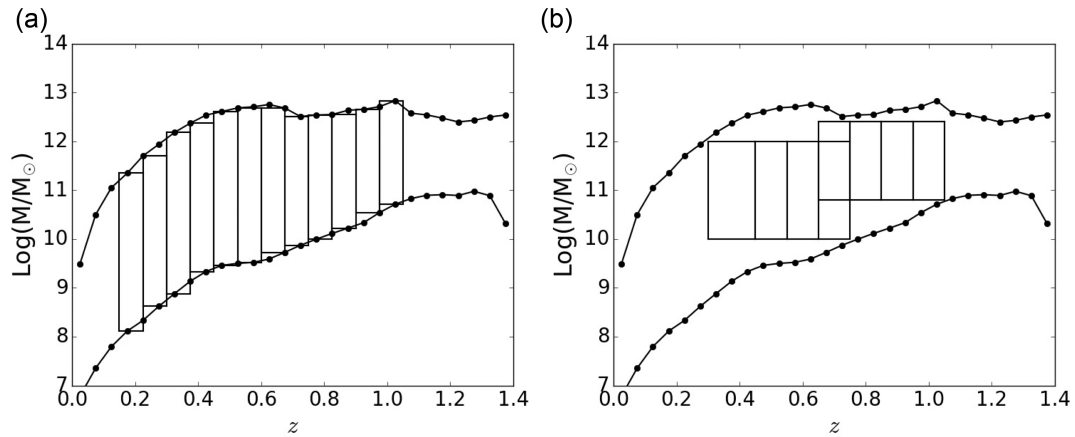


Figure 10. Curves show the mass completeness limits. The rectangles show the complete mass range for each redshift bin (left) and common mass ranges for the faint ($z < 0.75$) and bright ($z > 0.65$) tracers for the redshift evolution analysis (right).

function components for each redshift bin, but because different mass ranges are employed this analysis cannot be used to study the redshift evolution of the components of the mass function.

The second analysis employs common mass ranges for the redshift ranges traced by the faint and bright density defining populations. In this analysis, we split the environments into four equipercenage environment bins and investigate the redshift evolution of the lowest and highest environment components. The redshift bins and the common mass ranges for this analysis are shown on the right-hand side of Fig. 10 and listed together with the environment boundaries in Table 3.

4.2.1 Local Universe

Fig. 11 shows the environmental components of the galaxy stellar mass function for 12 redshift bins covering the range $0.15 < z < 1.05$. Each plot shows a different redshift bin. The first eight bins employ the faint tracer and the last four bins employ the bright tracer. These tracing populations were used to compute six equipercenage environment bins. The redshift, mass and environment bins used are listed in Table 2 and illustrated in the left-hand plot in Fig. 10. The total mass function is shown in black. The lowest environment components are shown in blue, the intermediate environment components are shown in green and the densest environment components in red. The vertical dashed black lines mark the mass completeness limits. These limits change with redshift. The range of complete masses generally decreases with redshift. This is mainly due to the increase in the low-mass limit with redshift. At higher redshifts, galaxies must be brighter (more massive) to be detected. The upper mass limit also increases with redshift, particularly for the first few redshift bins. This is due to the increase in detectable volume as the redshift increases; enabling rarer species of galaxies to be found (e.g. the most massive galaxies).

In this section, we focus on the four lowest redshift bins (i.e. $0.15 < z < 0.45$) that are shown in plots (a) to (d). Comparisons with other studies are tricky because of different definitions of environment, measurement methods (photometric versus spectroscopic) and mass completeness limits. Nevertheless, it is interesting to compare the environment components of the mass function with those obtained by Bolzonella et al. (2010) from zCOSMOS data shown in their fig. 3. The zCOSMOS study is based on spectroscopic measurements for an area of $\sim 1.5 \text{ deg}^2$ and the fifth nearest neighbour method is employed to quantify environment. Conversely in this

study, we have photometric measurements only, but for a much larger area $\sim 78 \text{ deg}^2$ and we employ a fixed aperture method to quantify environment. The mass function components in Bolzonella et al. (2010) are anchored at high mass, whereas the environment components in this study separate at high mass. The anchoring seen in Bolzonella et al. (2010) is by construction because the environments of only the massive galaxies ($\log(M) > 10.51$) are used to determine the boundaries of the environment bins. As noted by the authors, the effective (i.e. weighted by the volume corrections etc.) number of galaxies in each of their environment bins for the complete mass range is therefore not equal. In this study, we used Monte Carlo simulations to derive statistically robust equipercenage environment bins for the mass range between the completeness limits. This difference accounts for the larger (smaller) separation we see at high (low) mass compared with Bolzonella et al. (2010). Strikingly, the shapes of the components of the mass functions are very similar. The difference is the relative normalizations of the low and high environment curves. Bolzonella et al. (2010) finds an upturn in the highest density component at low mass ($\log(M) = 9.5$). There is evidence of this upturn in our data too (particularly in plot b)), but the upturn appears slightly less pronounced. Importantly, consistent with (Bolzonella et al. 2010) and also SDSS (Baldry & Balogh 2006) and GAMA (McNaught-Roberts et al. 2014) studies, for the low-redshift regime, we find that the fraction of massive galaxies is larger in high-density environments than low-density environments and the converse for the fraction of less massive galaxies (e.g. $\log(M) = 9.0$). The normalized mass function components for the intermediate environments uniformly (and in order) populate the range in between the lowest and highest components.

Despite the cruder redshift and environment measurements for individual galaxies in this study, because of the large sample, we are able to distinguish between the lowest and highest environment components of the galaxy stellar mass function in the local Universe.

4.2.2 Environmental components for complete mass ranges

We now move on to examine the environment components of the mass function at higher redshifts by continuing the discussion of Fig. 11. The figure shows that the environmental trends found at low redshift are maintained to high redshifts and the shapes of the environment components are distinguishable up to $z \sim 0.8$. However, the narrowing of the complete mass range with redshift tends to increasingly anchor the mass function components, in a way similar

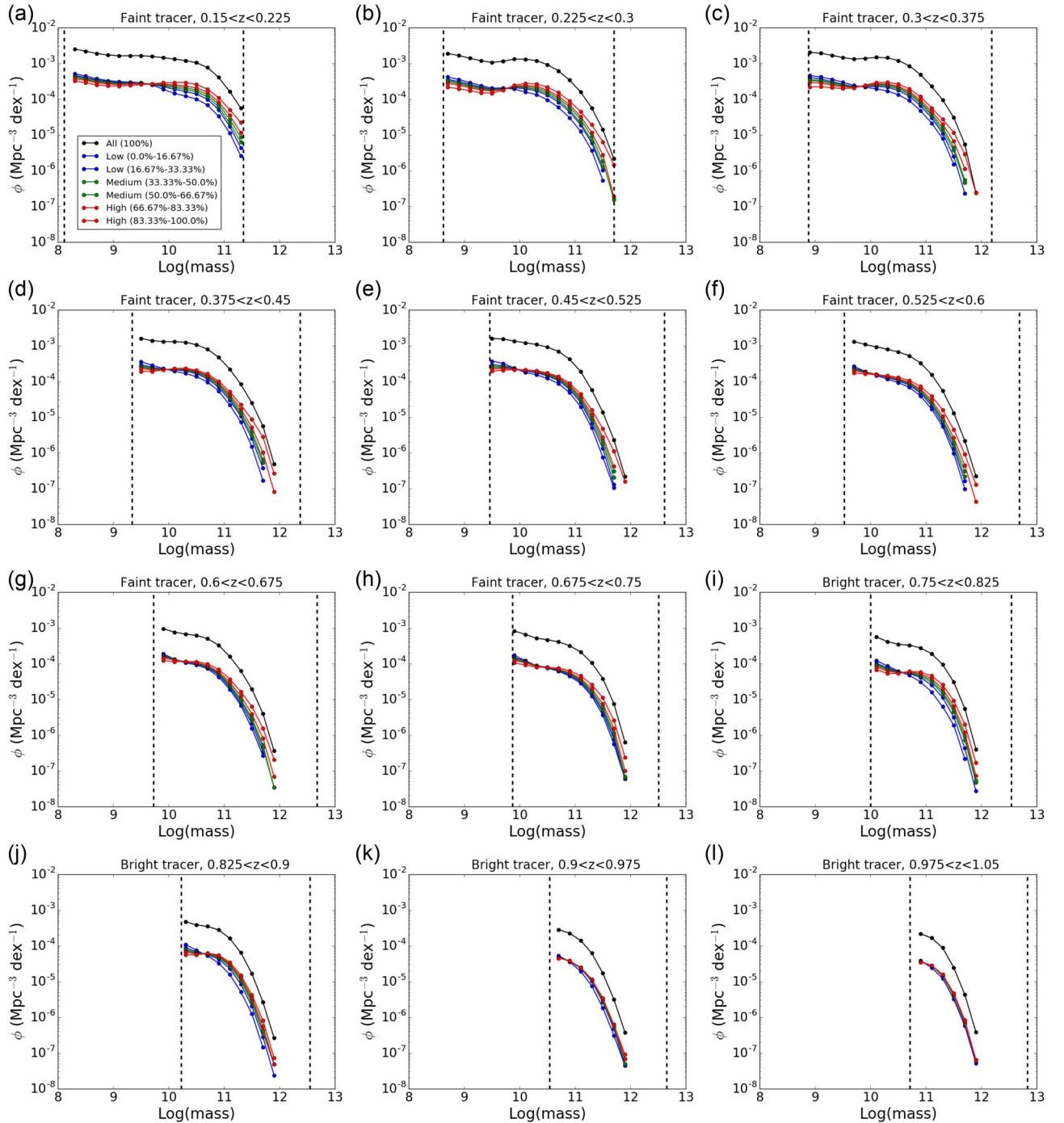


Figure 11. Galaxy stellar mass functions for the lowest (blue), intermediate (green), highest (red) and all (black) environment bins for 12 redshift bins. The environments for plots (a)–(h) are based on the faint tracer and the environments for plots (i)–(l) are based on the bright tracer. The vertical dashed lines indicate the mass completeness limits of each redshift bin. For clarity, error bars are not shown in this figure.

to that discussed in the previous section. Since the environment components are constructed to contain the same effective number of galaxies, this has the effect of driving the mass function components together. The final two redshift bins hint that the shapes of the environments components of the mass function increasingly converge with redshift. However, from these plots it is difficult to disentangle whether this is a real effect or due to the narrowing of the complete mass range. In the next section, we investigate this further by adopting common mass ranges over redshift bins.

4.2.3 Redshift evolution for common mass ranges

In this section, we repeat the analysis but use two common mass ranges, one for the faint tracer: $10.0 < \log(M) < 12.0$ and one for the bright tracer: $10.8 < \log(M) < 12.4$ for the redshift ranges $0.3 < z < 0.75$ and $0.65 < z < 1.05$, respectively. These common mass ranges are within the completeness limits for the corresponding redshift ranges. We split each of the redshift ranges into four redshift bins as shown in the right-hand plot of Fig. 10. Using these mass and redshift bins, we compute the environment boundaries to give four

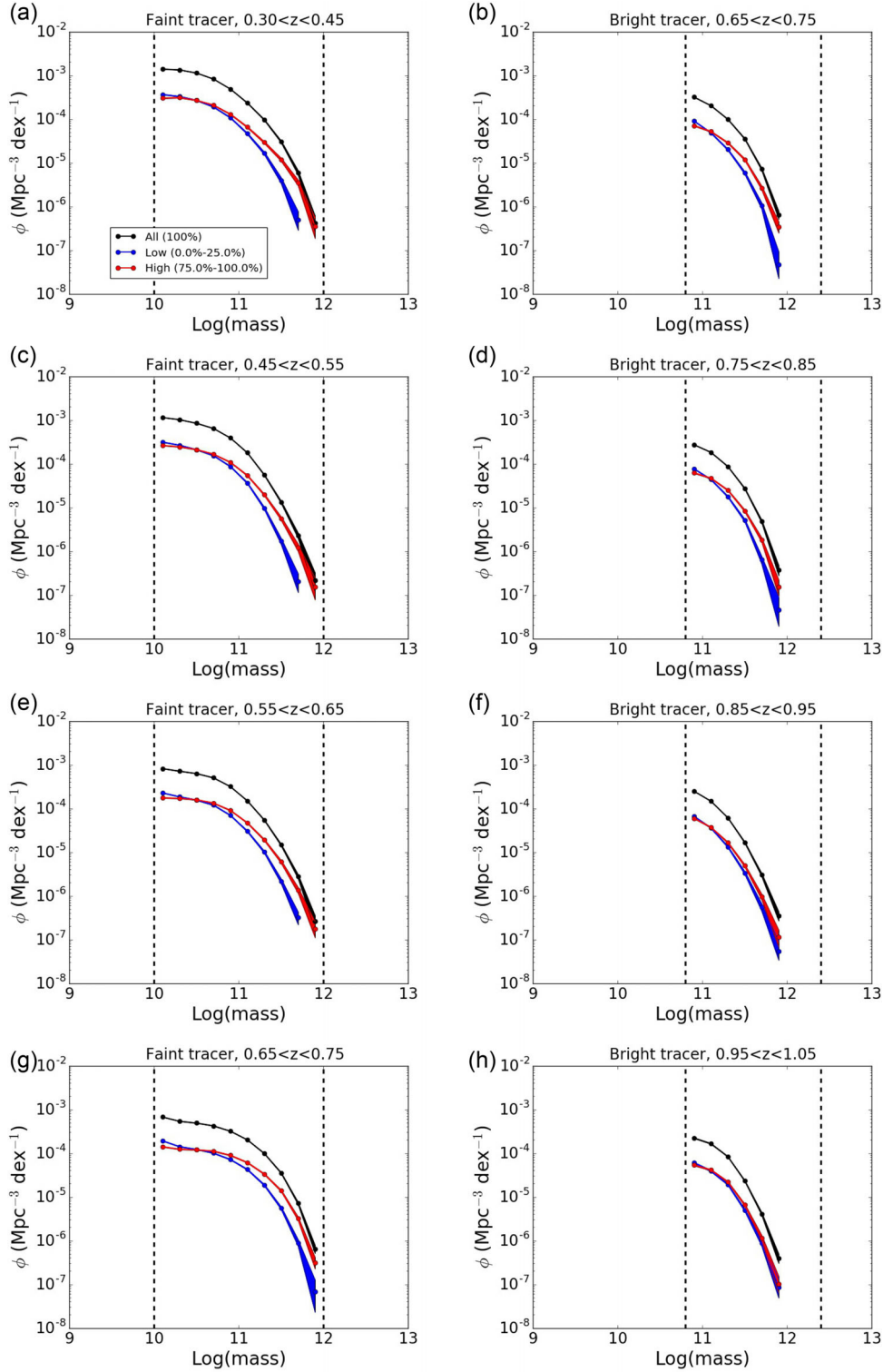


Figure 12. Galaxy stellar mass functions for the lowest (blue), highest (red) and all (black) environment bins for seven redshift bins. The environments for the plots on the left are based on the faint tracer and the environments for the plots on the right are based on the bright tracer. The vertical dashed lines mark the bounds of the common mass range. The shaded regions show the 1σ errors on the low- and high-density environment mass functions.

equipercantage environment bins. The details of the redshift, mass and environment bins are listed in Table 3.

Fig. 12 shows the lowest (blue) and highest (red) density environment components of the galaxy stellar mass function for the faint tracer (left) and the bright tracer (right). The lowest bin consists

of the bottom 25 percent of the environment distribution whereas the highest bin consists of the top 25 percent of the environment distribution. The red and blue shaded regions show the 1σ errors on the effective number density of galaxies in each bin. The vertical dashed lines mark the limits of the common mass ranges.

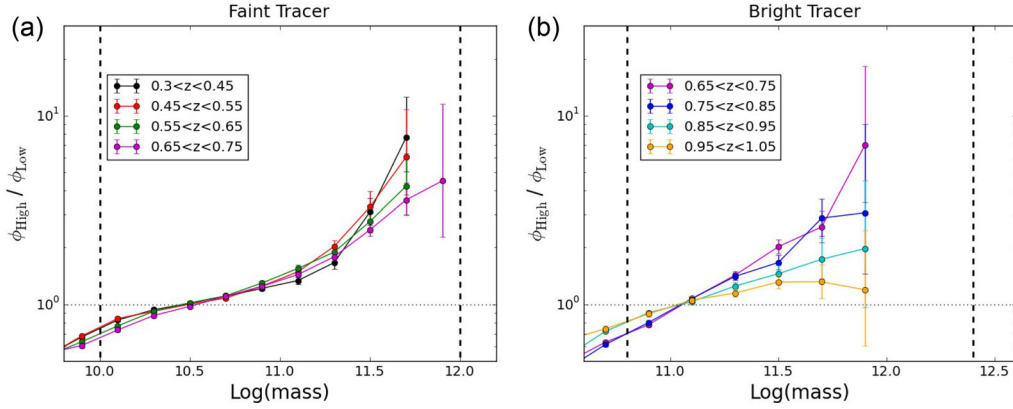


Figure 13. Ratio of the effective number of galaxies in high and low environment bins as a function of mass for the faint tracer (left) and the bright tracer (right) for different redshift bins. The error bars show the 1σ errors on the ratios. The vertical dashed lines mark common mass ranges within the completeness limits for the range of redshifts for the faint and bright tracers. The horizontal dotted line marks a ratio of unity.

The low- and high-density environment components behave consistently with the trends shown in Fig. 11. It is clear, especially for the bright tracer, that the shape of the environmental components converge with increasing redshift. For $\log(M) > 11.0$ and within the limits of the 1σ errors at a redshift of $z \sim 1.0$, the environmental components are indistinguishable. This result is consistent with recent work from Davidzon et al. (2016) that examines the redshift range: $0.51 < z < 0.9$ using data from VIPERS (Garilli et al. 2014) that contains 57 204 spectra and covers $\sim 10 \text{ deg}^2$ of the sky.

To illustrate this further, we examine the ratio between the effective number density of galaxies in the high and low environment components. Fig. 13 shows this ratio as a function of mass for different redshift bins for the faint tracer (left) and the bright tracer (right). The vertical dashed lines mark the limits of the common mass ranges. The error bars show the 1σ errors on the ratios. For low masses, the ratio at all redshifts and both tracers is < 1.0 . In this regime per unit volume of space, there is a larger number of galaxies in low-density environments than in high-density environments. As the mass increases, the ratio becomes > 1.0 and here the opposite is true. Per unit volume of space there is a larger number of galaxies in high-density environments than low-density environments. For $\log(M) < 11.2$, the ratio varies little with redshift. This changes for $\log(M) > 11.2$. Although the errors are large, in this mass range the ratio between the effective number density of galaxies in the high and low environment components decreases with redshift for both tracers, falling to nearly unity for the highest (mass and) redshift bin.

In an effort to connect the results based on the faint tracer to those on the bright tracer, we now compare the mass functions for the two tracers in the overlapping redshift range: $0.65 < z < 0.75$. Fig. 14 shows the low (cyan) and high (magenta) density mass function components for the faint (solid) and bright (dashed) tracers. The vertical black lines show the common mass ranges associated with the faint (solid) and bright (dashed) tracers. Despite using different-sized apertures to quantify galaxy environment and employing different common mass ranges, the low- and high-density environmental components of the mass function for $\log(M) > 11.2$ are strikingly similar for the faint and bright tracers. The difference in number density between the faint and bright tracers is smaller than the 1σ errors for the massive galaxies.

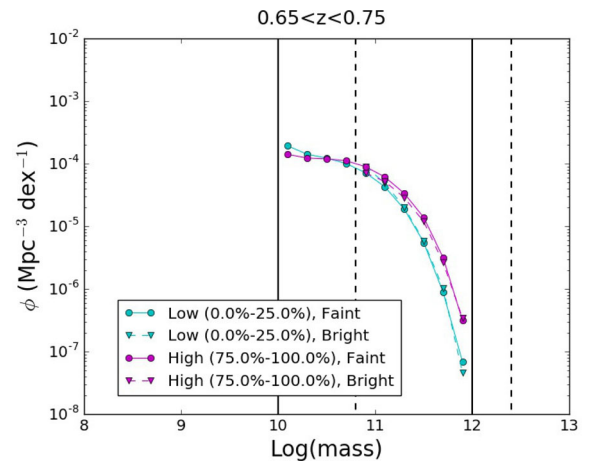


Figure 14. Comparison of the low (cyan) and high (magenta) density mass functions components for the faint (solid) and bright (dashed) tracers for the redshift range $0.65 < z < 0.75$ where the tracers overlap. The black vertical lines show the mass limits for the faint (solid) and bright (dashed) tracers.

4.2.4 Evolution of the environmental ratio of effective number of galaxies per unit volume

We are now in the position to investigate the evolution of the ratio of the effective number of galaxies per unit volume in the high- and low-density environment components. Fig. 15 shows the ratio of the effective number of galaxies per unit volume in the high- and low-density environment components as a function of cosmic time for a range of different masses. The redshift is shown on the upper horizontal axis. Exploiting the good agreement between the mass function components for the faint and bright tracers (for $\log(M) > 11.2$) shown in Fig. 14 in this figure we connect the results from the two tracers. The results on the left of the vertical dashed line ($z = 0.65$) are based on the bright tracer and the those on the right are based on the faint tracer. The ratio of the number of galaxies per unit volume in high-density environments to the number in low-density environments does not evolve with cosmic time for galaxies with $\log(M) < 11.2$. Conversely, this ratio evolves considerably for more massive galaxies and increases with cosmic time. For example, for galaxies with masses in range: $11.6 < \log(M) < 11.8$ (purple), the

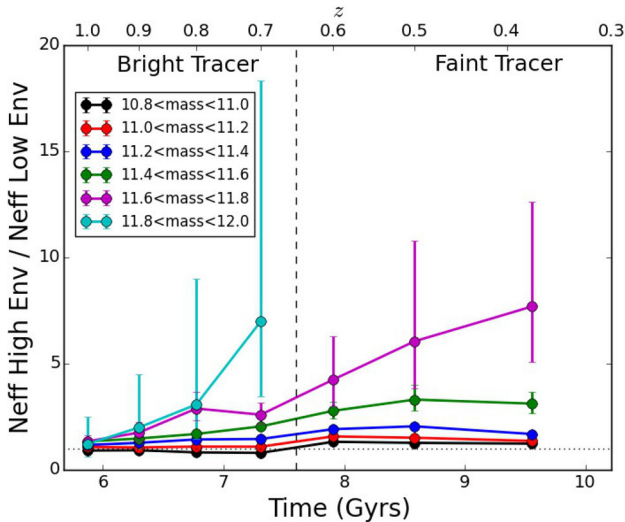


Figure 15. Ratio of the effective number of galaxies in high and low environment as a function of cosmic time for different mass bins. The bright tracer was used for the points on the left and the faint tracer was used for the points on the right of the vertical dashed line. The upper horizontal axis shows the redshift. The error bars show the 1σ errors on the ratios. The vertical dashed line marks the redshift that separates the measurements made with the faint and bright tracers.

ratio increases from ~ 1 to ~ 8 between $z = 1.0$ (6 Gyr) and $z = 0.375$ (9.5 Gyr). At $z \sim 1$, the lines for the different mass bins converge to a ratio of ~ 1.0 . At this redshift, the number density of galaxies in the low and high environment components becomes equal. Stated another way at $z \sim 1.0$, the probability of finding a massive galaxy in the highest density quartile is the same as finding it in the lowest density quartile, whilst at low-redshift massive galaxies preferentially reside in the high-density quartile. Assuming that most of the massive galaxies ($\log(M) > 11.8$) have formed at $z > 1.0$ (i.e. downsizing – Pozzetti et al. 2010; Thomas et al. 2010), this figure suggests that as cosmic time proceeds high-density structures form around the massive galaxies, such that at $z = 0.375$ the fraction of massive galaxies is ~ 8 times larger in high-density environments than in low-density environments. The convergence point at $z \sim 1.0$ is important because it marks the transition between an earlier epoch where the mass distribution of galaxies is independent of galaxy environment (Mortlock et al. 2015) and the later epoch where the mass distribution of galaxies does depend on environment.

5 DISCUSSION

We have tried to diligently deal with the errors on the galaxy mass, redshift and especially environment by using bins in these quantities that have a similar scale or are larger than the errors. Nevertheless, it is important to consider the possibility that the results for the highest redshift bin (i.e. Fig. 12 h and the convergence point in Fig. 15 at $z \sim 1.0$) could be partially driven by contamination due to the scattering of galaxies from adjacent bins. The highest redshift bin is potentially the most vulnerable to this effect because the photometric redshift error increases with redshift. For example, Fig. 3 g shows that $\Delta z \sim 0.08$ at $z \sim 1.0$. There is a slight upturn in the error on the mass estimates with $\Delta \log(\text{mass}) \sim 0.2$ at $z \sim 1.0$ as shown in Fig. 3 i

and the environment error also increases with redshift for the bright tracer with $\Delta \log(1 + \delta) \sim 0.12$ at $z \sim 1.0$ as shown in Fig. 6 c.

We think our result is robust at $z \sim 1.0$ because we have employed an aperture with a half depth, $\delta z = 0.2$, mass bins of size 0.2 dex and split the environments, low from high, using the first and fourth quartiles. These choices ensure we capture the vast majority of galaxies at $z \sim 1.0$ and even those with the largest photometric errors.

Since we have not considered the errors in the mass estimates attributed to different SED modelling efforts in this analysis, it is conceivable that there is some scattering between adjacent mass bins. This would lead to a shallowing (i.e. the Eddington bias) of both the low and high environmental components of the mass function. We would not expect there to be a differential effect between the components adversely affecting our result.

Table 3 shows that the difference between the 25th and 75th environmental percentiles at $z \sim 1.0$ is ~ 0.3 . This is 2.5 times larger than the median environmental error of 0.12 at $z \sim 1.0$. This means that there should be minimal contamination between the low and high environmental bins. We therefore believe that our results are robust and that the low and high components of the mass function converge with increasing redshift.

We find that the convergence point is $z \sim 1.0$. It is possible that contamination between environments, mass and redshift bins partially contributes to the convergence meaning that the true transition is at a slightly higher redshift. This may explain the difference between the converge redshift found in this paper compared to Mortlock et al. (2015) that find $z \sim 1.5$.

6 CONCLUSIONS

The main objective of this paper is to analyse the environmental components of the galaxy stellar mass function using the DES science verification data set. The DES is wide-area photometric survey imaging galaxies to a redshift of about 1.4.

Specifically, we studied the SPT-E field that is the largest contiguous field in the data set and has an area of approximately 130 deg^2 . The SPT-E field contains approximately 3.2 million galaxies.

We adopted a Monte Carlo approach and used the photometric redshift PDFs to propagate the errors into the derived galaxy properties: the stellar masses and *i*-band absolute magnitudes. We found that the ratio between the range of the property distributions and the median errors was approximately 10–12 and this was sufficient for further analyses.

We constructed two density defining populations: one for the redshift range $0.15 < z < 0.75$ that we call the faint tracer and one for $0.6 < z < 1.05$ that we call the bright tracer. We used the tracing populations and a fixed aperture method to compute galaxy environments for a range of aperture parameters. We used Monte Carlo realizations to quantify the errors on the environment measurements. This enabled the selection of a set of aperture parameters for the faint and bright tracers that resulted in similar environmental properties. The ratio between the range of environments and the median error on the environments was 3.8, only 3 times smaller than the ratios for the absolute magnitudes and stellar masses. We showed that environment PDFs could be constructed from the Monte Carlo realizations. We found that the error on the environment measurements increased as a function of environment but was relatively constant as a function of redshift.

We calculated volume and surface brightness corrections for each galaxy and used them to construct weighted environment distributions. We used Monte Carlo realizations to derive statistically

robust equipercentage environment bins for a set of redshift bins. We carefully controlled the mass ranges (for each redshift bin) and used the environmental components to conduct two analyses of the galaxy stellar mass function. In the first, we studied the environmental components using the largest possible complete mass range for each redshift bin. In the second, we employed common mass ranges across redshift bins to study the redshift evolution of the environmental components. We computed the environment components of the galaxy stellar mass function for the redshift range $0.15 < z < 1.05$. We found a clear separation between the shapes of the environmental components of the stellar mass function at low and intermediate redshift. For $z < 0.75$, we found that the fraction of massive galaxies is larger in high-density environments than low-density environments and the converse for the fraction of less massive galaxies ($\log(M) < 9.0$). The low- and high-density components converge with increasing redshift up to $z \sim 1.0$ where their shapes are indistinguishable. This redshift is important because it marks the transition between an earlier epoch where the mass distribution of galaxies is independent of environment and a later epoch where the mass distribution does depend on galaxy environment. We studied the ratio between the high and low environment components of the stellar mass function as a function of cosmic time and showed the buildup of high-density structures around the most massive galaxies.

The science verification data is the first data set from the DES. We have demonstrated with approximately 2 percent of the total area of the full survey an analysis of the evolving population of galaxies and their environments. Future data sets from the DES will provide the opportunity to study different components of the galaxy stellar mass function including colour, SFR and morphology, unlocking more clues.

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- ³Centro de Investigaciones Energeticas, Medioambientales y Tecnológicas (CIEMAT), Complutense 40, E-28040 Madrid, Spain
- ⁴Wisconsin IceCube Particle Astrophysics Center (WIPAC), Madison, WI 53703, USA
- ⁵Department of Physics, University of Wisconsin-Madison, Madison, WI 53706, USA
- ⁶Aix Marseille Université, CNRS, LAM (Laboratoire d'Astrophysique de Marseille) UMR 7326, F-13388 Marseille, France
- ⁷Observatório Nacional, Rua Gal. José Cristino 77, Rio de Janeiro RJ 20921-400, Brazil
- ⁸Laboratório Interinstitucional de e-Astronomia-LIneA, Rua Gal. José Cristino 77, Rio de Janeiro RJ 20921-400, Brazil
- ⁹Institut d'Astrophysique de Paris, Sorbonne Universités, UPMC Univ Paris 6 et CNRS, UMR 7095, 98 bis bd Arago, F-75014 Paris, France
- ¹⁰Astrophysics Group, Department of Physics and Astronomy, University College London, 132 Hampstead Road, London NW1 2PS, UK
- ¹¹National Center for Supercomputing Applications, 1205 West Clark St, Urbana, IL 61801, USA
- ¹²ETH Zürich, Institut für Astronomie, Wolfgang-Pauli-Str. 27, CH-8093 Zürich, Switzerland
- ¹³Cerro Tololo Inter-American Observatory, National Optical Astronomy Observatory, Casilla 603, La Serena, Chile
- ¹⁴Department of Physics and Astronomy, University College London, Gower Street, London WC1E 6BT, UK
- ¹⁵Department of Physics and Electronics, Rhodes University, PO Box 94, Grahamstown 6140, South Africa
- ¹⁶Fermi National Accelerator Laboratory, PO Box 500, Batavia, IL 60510, USA
- ¹⁷Carnegie Observatories, 813 Santa Barbara St, Pasadena, CA 91101, USA
- ¹⁸CNRS, UMR 7095, Institut d'Astrophysique de Paris, F-75014 Paris, France
- ¹⁹Department of Astronomy, University of Illinois, 1002 W. Green Street, Urbana, IL 61801, USA
- ²⁰National Center for Supercomputing Applications, 1205 West Clark St, Urbana, IL 61801, USA
- ²¹Institut de Ciències de l'Espai, IEEC-CSIC, Campus UAB, Carrer de Can Magrans, s/n, E-08193 Bellaterra, Barcelona, Spain
- ²²Institut de Física d'Altes Energies (IFAE), The Barcelona Institute of Science and Technology, Campus UAB, E-08193 Bellaterra (Barcelona), Spain
- ²³Kavli Institute for Particle Astrophysics and Cosmology, PO Box 2450, Stanford University, Stanford, CA 94305, USA
- ²⁴Department of Physics, IIT Hyderabad, Kandi, Telangana 502285, India
- ²⁵Department of Physics and Astronomy, University of Pennsylvania, Philadelphia, PA 19104, USA
- ²⁶Jet Propulsion Laboratory, California Institute of Technology, 4800 Oak Grove Dr., Pasadena, CA 91109, USA
- ²⁷Department of Astronomy, University of Michigan, Ann Arbor, MI 48109, USA
- ²⁸Department of Physics, University of Michigan, Ann Arbor, MI 48109, USA
- ²⁹Kavli Institute for Cosmological Physics, University of Chicago, Chicago, IL 60637, USA
- ³⁰SLAC National Accelerator Laboratory, Menlo Park, CA 94025, USA
- ³¹Center for Cosmology and Astro-Particle Physics, The Ohio State University, Columbus, OH 43210, USA
- ³²Department of Physics, The Ohio State University, Columbus, OH 43210, USA
- ³³Australian Astronomical Observatory, North Ryde, NSW 2113, Australia
- ³⁴Department of Astronomy, The Ohio State University, Columbus, OH 43210, USA
- ³⁵Department of Astrophysical Sciences, Princeton University, Peyton Hall, Princeton, NJ 08544, USA
- ³⁶Institució Catalana de Recerca i Estudis Avançats, E-08010 Barcelona, Spain
- ³⁷Faculty of Physics, Ludwig-Maximilians-Universität, Scheinerstr. 1, D-81679 Munich, Germany

¹Institute of Cosmology and Gravitation, University of Portsmouth, Portsmouth PO1 3FX, UK

²SEPnet, South East Physics Network, (www.sepnet.ac.uk)

³⁸*Excellence Cluster Universe, Boltzmannstr. 2, D-85748 Garching, Germany*

³⁹*Max Planck Institute for Extraterrestrial Physics, Giessenbachstrasse, D-85748 Garching, Germany*

⁴⁰*Department of Physics and Astronomy, Pevensey Building, University of Sussex, Brighton BN1 9QH, UK*

⁴¹*Instituto de Física Teórica, Universidade Estadual Paulista, Rua Dr. Bento T. Ferraz, 271, São Paulo, SP 01140-070, Brazil*

⁴²*Argonne National Laboratory, 9700 South Cass Avenue, Lemont, IL 60439, USA*

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