

A BIVARIATE GENERALIZED EXPONENTIAL DISTRIBUTION DERIVED FROM COPULA FUNCTIONS IN THE PRESENCE OF CENSORED DATA AND COVARIATES

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ABSTRACT. In this paper, we introduce a Bayesian analysis for a bivariate generalized exponential distribution in the presence of censored data and covariates derived from Copula functions. The generalized exponential distribution could be a good alternative to analyze lifetime data in comparison to usual existing parametric lifetime distributions as Weibull or Gamma distributions. We have been using standard existing MCMC (Markov Chain Monte Carlo) methods to simulate samples for the joint posterior of interest. Two examples are introduced to illustrate the proposed methodology: an example with simulated bivariate lifetime data and an example with a real lifetime data set.

Keywords: Bivariate generalized exponential distribution, copula function, Bayesian analysis, censored data, covariates.

1 INTRODUCTION

In medical, engineering or other lifetime data applications, we could have more than one lifetime associated to each unit. A special situation is the presence of two lifetimes T_1 and T_2 associated to each unit. In this situation, we could consider some existing bivariate lifetime distribution that has been introduced in the literature (see for example, Gumbel, 1960; Freund, 1961; Marshall & Olkin, 1967; Downton, 1972; Block & Basu, 1974; Sarkar, 1987; Hawkes, 1988).

Usually these bivariate lifetime distributions generalize some popular existing univariate lifetime distributions as exponential, Weibull, Gamma or a log-normal distribution (see for example, Lawless, 1982).

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Other parametrical lifetime distributions could be generalized for the bivariate case. One of these models is given by the generalized exponential distribution (see for example, Gupta & Kundu, 1999; Raqab & Ahsanullah, 2001; Raqab, 2002; Zheng, 2002; Gupta & Kundu, 2007; Sarhan, 2007). Kundu & Gupta (2009) introduced a singular bivariate Generalized Exponential (BVGE) distribution to analyze lifetime data.

An alternative and flexible way to derive different bivariate lifetime distributions could be given by copula functions (see, for example, Trivedi & Zimmer, 2005a,b; Nelsen, 2006). There are several copula functions in the literature for construction of multivariate lifetime distributions where the most used are Farlie-Gumbel-Morgenstern (Morgenstern, 1956), and the Archimedean copulas as Clayton (1978), Gumbel (1960) and Frank (1979).

Recently, new copulas have been proposed as the class of Archimedean copulas in d -dimension given in McNeil & Neslehová (2009). McNeil & Neslehová (2010) also generalise the Archimedean copulas to obtain the Liouville copula. Marshall-Olkin Copulas (see Li, 2012) and the Generalized Farlie-Gumbel-Morgenstern copula (Bekrizadeh et al., 2012) are other examples.

Achcar & Santos (2010) construct bivariate Weibull distributions suitable for survival analysis by using different copula functions. The bivariate Birnbaum-Saunders distribution proposed by Kundu et al. (2010) show that it can be obtained as a Gaussian copula. More recently, Kundu introduced the bivariate Sinh-normal distribution, which can be obtained as a bivariate Gaussian copula.

Kundu & Gupta (2011) also derived an absolute continuous bivariate Generalized Exponential distribution based on the Clayton copula.

In this paper, we introduce other bivariate generalized exponential distributions derived from the Farlie-Gumbel-Morgenstern to analyze lifetime data. We also investigate the performance of this new distribution.

Inferences for these different versions of bivariate lifetime models could present some difficulties using standard classical inference methods, especially in the presence of censored data and covariates, a usual situation in applications.

In this way, we consider the use of Bayesian methods where the samples for the joint posterior distribution of interest are simulated using MCMC (Markov Chain Monte Carlo) methods as the popular Gibbs sampling algorithm (see for example, Gelfand & Smith, 1990; or Casela & George, 1992) or the Metropolis-Hastings algorithm (see for example, Chib & Greenberg, 1995).

The paper is organized as follows: in Section 2, we introduce some concepts of copula functions; in Section 3, we present the generalized exponential distribution; in Section 4, we derive a bivariate generalized exponential distribution from a Copula function; in Section 5, we introduce a Bayesian analysis in the presence of censored data; in Section 6, we consider the presence of covariates and censored data; in Section 7, we introduce two examples; finally in Section 8, we present some concluding remarks.

2 COPULA FUNCTIONS

Copula functions can be used to link marginal distributions with a joint distribution. For specified univariate marginal distribution functions $F_1(t_1), F_2(t_2), \dots, F_m(t_m)$, the function,

$$C(F_1(t_1), F_2(t_2), \dots, F_m(t_m)) = F(t_1, t_2, \dots, t_m) \tag{1}$$

which is defined using a copula function C , results in a multivariate distribution function with univariate marginal distributions specified as $F_1(t_1), F_2(t_2), \dots, F_m(t_m)$, (see for example, Frees (1998) or Nelsen (1999)).

It is important to point out that any multivariate distribution function F can be written in the form of a copula function (Sklar, 1959); that is, if $F(t_1, t_2, \dots, t_m)$ is a joint multivariate distribution function with univariate marginal distribution functions $F_1(t_1), F_2(t_2), \dots, F_m(t_m)$, thus there exists a copula function $C(U_1, U_2, \dots, U_m)$ such that (1) occurs.

If every F_i is continuous, then C is unique.

In the bivariate cases, let T_1 and T_2 be two random variables with continuous distribution functions F_1 and F_2 .

The probability integral transform can be applied separately to the two random variables to define $U = F_1(t_1)$ and $V = F_2(t_2)$, where U and V have uniform $(0, 1)$ distributions, but are usually dependent if T_1 and T_2 are dependent (T_1 and T_2 independent, implies that U and V are independent).

Specifying dependence between T_1 and T_2 is the same as specifying dependence between U and V .

With U and V uniform random variables, the problem reduces to specifying a bivariate distribution between two uniforms, that is, a copula.

3 GENERALIZED EXPONENTIAL DISTRIBUTION

A generalized exponential distribution (see Gupta & Kundu, 1999) can be a good alternative to the usual Gamma and Weibull distributions commonly used to analyse lifetime data (see also, Raqab & Ahsanullah, 2001; Raqab, 2002; Zheng, 2002; Gupta & Kundu, 2007, 2008; Sarhan, 2007).

The generalized exponential distribution with two parameters has density given by,

$$f(t; \alpha, \lambda) = \alpha\lambda[1 - \exp(-\lambda t)]^{\alpha-1} \exp(-\lambda t), \tag{2}$$

where $t > 0$, $\alpha > 0$, and $\lambda > 0$, are respectively, shape and scale parameters.

The density (2) has great flexibility of fit depending on the parameter α : if $\alpha < 1$, we have a decreasing function and if $\alpha > 1$, we have a unimodal function with mode given by $\lambda^{-1} \log \alpha$.

Observe that if $\alpha = 1$, we have an exponential distribution with parameter λ .

The survival and hazard functions associated to (2), are given, respectively, by,

$$S(t; \alpha, \lambda) = P\{T > t\} = 1 - \left(1 - \exp(-\lambda t)\right)^\alpha \tag{3}$$

and

$$h(t; \alpha, \lambda) = \frac{f(t; \alpha, \lambda)}{S(t; \alpha, \lambda)} = \frac{\alpha\lambda[1 - \exp(-\lambda t)]^{\alpha-1} \exp(-\lambda t)}{1 - \left(1 - \exp(-\lambda t)\right)^\alpha} \tag{4}$$

Observe that the hazard function $h(t; \alpha, \lambda)$ is increasing from 0 to λ if $\alpha > 1$; decreasing if $\alpha < 1$ and constant if $\alpha = 1$.

This behavior of the hazard function is similar to the behavior of the hazard function of the gamma distribution.

The moment generation function for a random variable T with a generalized exponential distribution with density (2) is given (see Gupta & Kundu, 2008) by,

$$M(s) = E[e^{sT}] = \frac{\Gamma(\alpha + 1)\Gamma(1 - s/\lambda)}{\Gamma(\alpha + 1 - s/\lambda)}, \tag{5}$$

for $s < \lambda$; $\Gamma(x)$ is the gamma function.

From (5), we get the moments of interest. The mean and variance of T are given, respectively, by,

$$E(T) = \frac{1}{\lambda} [\psi(\alpha + 1) - \psi(1)] \quad \text{and} \tag{6}$$

$$var(T) = \frac{1}{\lambda^2} [\psi'(1) - \psi'(\alpha + 1)],$$

where $\psi(\cdot)$ is the digamma function given by

$$\psi(x) = \frac{d}{dx} \log \Gamma(x) = \frac{\Gamma'(x)}{\Gamma(x)}.$$

4 A BIVARIATE GENERALIZED EXPONENTIAL DISTRIBUTION DERIVED FROM THE FARLIE-GUMBEL-MORGENSTERN COPULA

Different copula functions introduced in the literature could be used to obtain a bivariate generalized exponential distribution.

A special case is given by the Farlie-Gumbel-Morgensten Copula (see Morgensten, 1956) given by,

$$C(u, v) = [1 - e^{\ln(1-u)}][1 - e^{\ln(1-v)}] \left[1 + \theta \exp(\ln(1-u) + \ln(1-v)) \right] \tag{7}$$

where $-1 \leq \theta \leq 1$, $u = F_1(t_1)$ (marginal distribution for the random variable T_1) and $v = F_2(t_2)$ (marginal distribution for the random variable T_2).

Observe that θ is a parameter associated to the dependence between the random variables T_1 and T_2 and related to the Spearman's rank correlation $\rho_S(T_1, T_2)$ ("Spearman's rho") and Kendall's rank correlation $\rho_\tau(T_1, T_2)$ ("Kendall's tau") by the relations,

$$\begin{aligned} \rho_S(T_1, T_2) &= 12 \int_0^1 \int_0^1 [C(u, v) - uv] dudv \quad \text{and} \\ \rho_\tau(T_1, T_2) &= 4 \int_0^1 \int_0^1 C(u, v) dC(u, v) - 1. \end{aligned} \tag{8}$$

From (7), we get $\rho_S(T_1, T_2) = \theta/3$ and $\rho_\tau(T_1, T_2) = 2\theta/9$ (see for example, Nelsen, 1999).

From (8), we could use the information of experts to directly elicit a prior distribution for the correlation (a value between -1 and 1) between T_1 and T_2 ; another possibility is to use empirical Bayesian methods to choose a prior distribution for the dependence parameter θ using the relations given by (8). Some authors introduce different methods for eliciting a prior distribution for the correlation (see for example, Clemen, Fischer & Winkler, 2000).

Let us assume the marginal generalized exponential distributions (see (2)), given by,

$$\begin{aligned} u = F_1(t_1) &= P\{T_1 \leq t_1\} = \left(1 - \exp(-\lambda_1 t_1)\right)^{\alpha_1} \quad \text{and} \\ v = F_2(t_2) &= P\{T_2 \leq t_2\} = \left(1 - \exp(-\lambda_2 t_2)\right)^{\alpha_2} \end{aligned} \tag{9}$$

From (7), the joint distribution function for T_1 and T_2 is given by,

$$\begin{aligned} F(t_1, t_2 | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta) &= (1 - e^{-\lambda_1 t_1})^{\alpha_1} (1 - e^{-\lambda_2 t_2})^{\alpha_2} \\ &\times \left[1 + \theta \left(1 - (1 - e^{-\lambda_1 t_1})^{\alpha_1}\right) \left(1 - (1 - e^{-\lambda_2 t_2})^{\alpha_2}\right) \right] \end{aligned} \tag{10}$$

where $t_1 > 0$ and $t_2 > 0$.

The joint density function for T_1 and T_2 is given by,

$$f(t_1, t_2 | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta) = \frac{\partial^2 F(t_1, t_2)}{\partial t_1 \partial t_2} \tag{11}$$

That is, from (11), we have,

$$f(t_1, t_2 | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta) = f_1(t_1) f_2(t_2) + \theta f_1(t_1) f_2(t_2) \left(1 - 2F_1(t_1)\right) \left(1 - 2F_2(t_2)\right) \tag{12}$$

where $f_1(t_1)$ and $f_2(t_2)$ are the marginal densities for T_1 and T_2 with parameters (α_1, λ_1) and (α_2, λ_2) , respectively (see (2)), and $F_1(t_1)$ and $F_2(t_2)$ are given by (9).

Figure 1 displays the joint density $f(t_1, t_2 | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta)$ given in (12) for five different levels of dependence, assuming the parameters $\lambda_1 = 1, \lambda_2 = 1.5, \alpha_1 = 2$ and $\alpha_2 = 3$. Figures 1a and 1b show a three-dimensional plot and a contour plot of the bivariate density, respectively, when θ is 0.5. Figures 1c, 1d, 1e and 1f illustrate contour plots for different levels of dependence parameter, $\theta = 0.01, 0.9, -0.5$ and -0.8 , respectively.

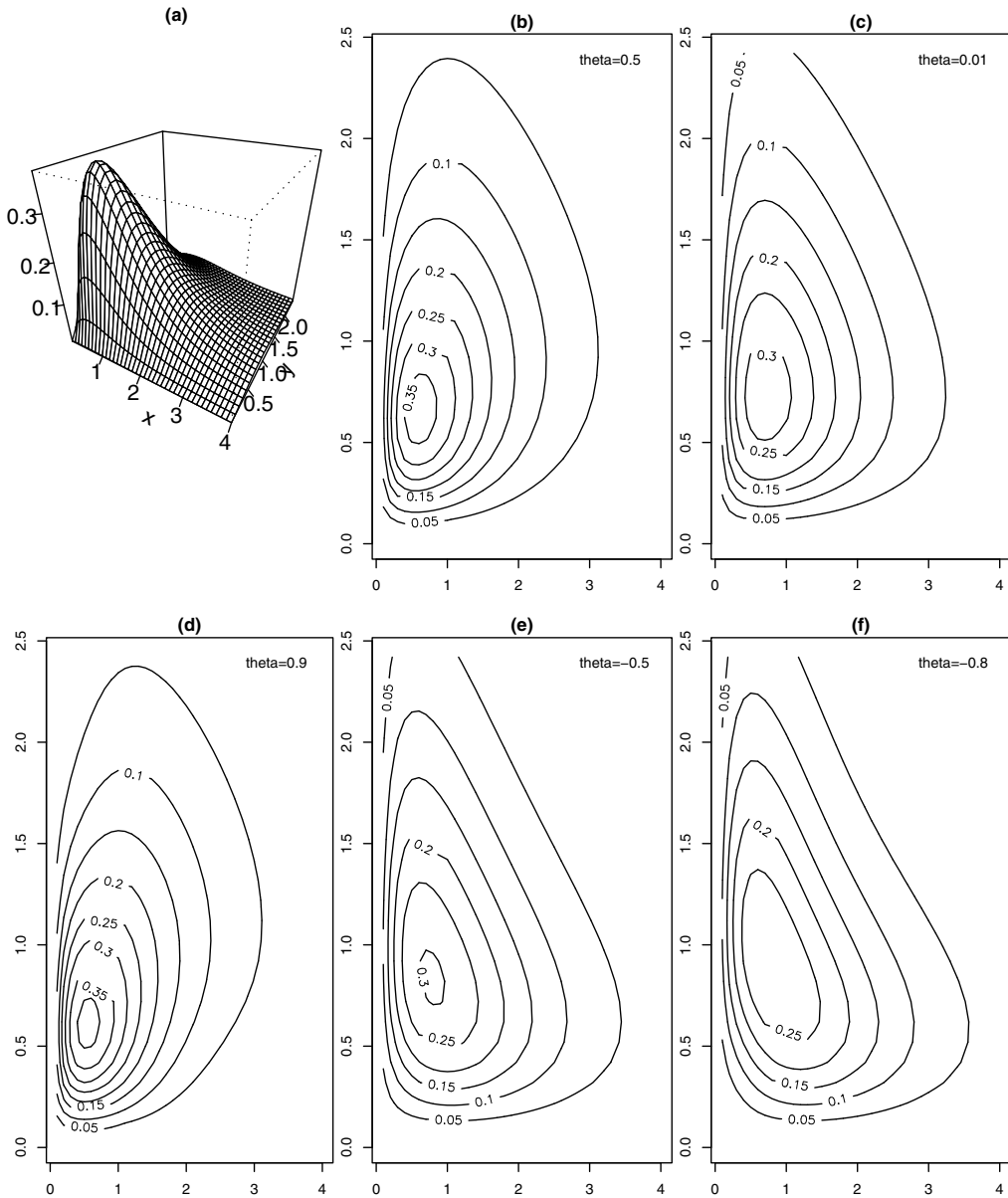


Figure 1 – Contour plots of bivariate density with generalized exponential marginal densities.

Through the Figure 1 we can verify if the dependence condition is confirmed by θ , looking at the contours of bivariate density $f(t_1, t_2 | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta)$. A variable T_1 is highly correlated (positively or negatively) with other T_2 , then it is expected the high density values are along a diagonal axis (see Figures 1b, d, e and f).

Also observe that the joint bivariate survival function for the lifetimes T_1 and T_2 is given by,

$$S(t_1, t_2) = P\{T_1 > t_1, T_2 > t_2\} = 1 - F_1(t_1) - F_2(t_2) + F(t_1, t_2), \tag{13}$$

where $F_1(t_1)$ and $F_2(t_2)$ are given by (9) and $F(t_1, t_2)$ is given by (10). That is,

$$S(t_1, t_2) = 1 - (1 - e^{-\lambda_1 t_1})^{\alpha_1} - (1 - e^{-\lambda_2 t_2})^{\alpha_2} + (1 - e^{-\lambda_1 t_1})^{\alpha_1} (1 - e^{-\lambda_2 t_2})^{\alpha_2} \times \left[1 + \theta \left(1 - (1 - e^{-\lambda_1 t_1})^{\alpha_1} \right) \left(1 - (1 - e^{-\lambda_2 t_2})^{\alpha_2} \right) \right] \tag{14}$$

5 A BAYESIAN ANALYSIS IN THE PRESENCE OF CENSORED DATA

Suppose either T_1 or T_2 can be censored and that censoring is independent of the lifetimes. Let us subdivide the n observations into four classes:

- C_1 : both t_{1i} and t_{2i} are observed lifetimes, $i = 1, \dots, n$;
- C_2 : t_{1i} is a lifetime and t_{2i} is a censoring time (that is, we only know that $T_{2i} \geq t_{2i}$);
- C_3 : t_{1i} is a censoring time and t_{2i} is a lifetime;
- C_4 : both t_{1i} and t_{2i} are censoring times.

The likelihood function for a continuous model (see for example, Lawless, 1982, page 479) is given by,

$$L = \prod_{i \in C_1} f(t_{1i}, t_{2i}) \prod_{i \in C_2} \left(-\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{1i}} \right) \prod_{i \in C_3} \left(-\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{2i}} \right) \prod_{i \in C_4} S(t_{1i}, t_{2i}) \tag{15}$$

where $f(t_{1i}, t_{2i})$ is the joint probability density function for T_{1i} and T_{2i} ; $S(t_{1i}, t_{2i})$ is the joint survival function; $\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{1i}}$ and $\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{2i}}$ are the partial derivatives of $S(t_{1i}, t_{2i})$ with respect to t_{1i} and t_{2i} , respectively.

Let us define the indicator variables δ_{1i} and δ_{2i} , by,

$$\delta_{ji} = \begin{cases} 1 & \text{if } t_{ji} \text{ is an observed lifetime} \\ 0 & \text{if } t_{ji} \text{ is a censored observation} \end{cases} \tag{16}$$

for $j = 1, 2$; $i = 1, \dots, n$, where n is the number of observations.

In this way, we rewrite the likelihood function (15) as,

$$L = \prod_{i=1}^n \left[f(t_{1i}, t_{2i}) \right]^{\delta_{1i} \delta_{2i}} \prod_{i=1}^n \left[-\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{1i}} \right]^{\delta_{1i} (1 - \delta_{2i})} \times \prod_{i=1}^n \left[-\frac{\partial S(t_{1i}, t_{2i})}{\partial t_{2i}} \right]^{(1 - \delta_{1i}) \delta_{2i}} \prod_{i=1}^n \left[S(t_{1i}, t_{2i}) \right]^{(1 - \delta_{1i}) (1 - \delta_{2i})} \tag{17}$$

Observe that if we do not have censored data, the likelihood function (17) reduces to,

$$L = \prod_{i=1}^n f(t_{1i}, t_{2i}) \tag{18}$$

In (17), we replace $S(t_{1i}, t_{2i})$ by (14), $f(t_{1i}, t_{2i})$ by (12), and $F_1(t_{1i})$ and $F_2(t_{2i})$ are given by (9), that is,

$$f(t_{1i}, t_{2i} | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta) = \alpha_1 \alpha_2 \lambda_1 \lambda_2 (1 - e^{-\lambda_1 t_{1i}})^{\alpha_1 - 1} (1 - e^{-\lambda_2 t_{2i}})^{\alpha_2 - 1} \times \exp(-\lambda_1 t_{1i} - \lambda_2 t_{2i}) \left[1 + \theta \left(1 - 2(1 - e^{-\lambda_1 t_{1i}})^{\alpha_1} \right) \left(1 - 2(1 - e^{-\lambda_2 t_{2i}})^{\alpha_2} \right) \right] \tag{19}$$

The first derivatives of $S(t_{1i}, t_{2i})$ with respect to t_{1i} and t_{2i} are given by,

$$\begin{aligned} - \frac{\partial S(t_{1i}, t_{2i})}{\partial t_{1i}} &= f_1(t_{1i}) \left\{ 1 - F_2(t_{2i}) \left[1 + \theta \left(1 - F_2(t_{2i}) \right) \left(1 - 2F_1(t_{1i}) \right) \right] \right\} \quad \text{and} \\ - \frac{\partial S(t_{1i}, t_{2i})}{\partial t_{2i}} &= f_2(t_{2i}) \left\{ 1 - F_1(t_{1i}) \left[1 + \theta \left(1 - F_1(t_{1i}) \right) \left(1 - 2F_2(t_{2i}) \right) \right] \right\} \end{aligned} \tag{20}$$

that is,

$$\begin{aligned} - \frac{\partial S(t_{1i}, t_{2i})}{\partial t_{1i}} &= \alpha_1 \lambda_1 (1 - e^{-\lambda_1 t_{1i}})^{\alpha_1 - 1} e^{-\lambda_1 t_{1i}} \left\{ 1 - (1 - e^{-\lambda_2 t_{2i}})^{\alpha_2} \right. \\ &\quad \left. \times \left[1 + \theta \left(1 - (1 - e^{-\lambda_2 t_{2i}})^{\alpha_2} \right) \left(1 - 2(1 - e^{-\lambda_1 t_{1i}})^{\alpha_1} \right) \right] \right\} \quad \text{and} \\ - \frac{\partial S(t_{1i}, t_{2i})}{\partial t_{2i}} &= \alpha_2 \lambda_2 (1 - e^{-\lambda_2 t_{2i}})^{\alpha_2 - 1} e^{-\lambda_2 t_{2i}} \left\{ 1 - (1 - e^{-\lambda_1 t_{1i}})^{\alpha_1} \right. \\ &\quad \left. \times \left[1 + \theta \left(1 - (1 - e^{-\lambda_1 t_{1i}})^{\alpha_1} \right) \left(1 - 2(1 - e^{-\lambda_2 t_{2i}})^{\alpha_2} \right) \right] \right\} \end{aligned} \tag{21}$$

For a Bayesian analysis, let us assume the following prior distribution for $\lambda_1, \lambda_2, \alpha_1, \alpha_2$ and θ :

$$\begin{aligned} \lambda_j &\sim U[a_j b_j] \\ \alpha_j &\sim U[c_j d_j] \\ \theta &\sim U[-1, 1] \end{aligned} \tag{22}$$

for $j = 1, 2$; $U[a, b]$ denotes an uniform distribution in the interval (a, b) ; a_j, b_j, c_j and d_j are known hyperparameters. We further assume prior independence among the parameters.

Other prior distributions also could be considered, as gamma priors for α_j and $\lambda_j, j = 1, 2$.

The joint posterior distribution for $\mathbf{v} = (\lambda_1, \lambda_2, \alpha_1, \alpha_2, \theta)'$ is given by,

$$\pi(\mathbf{v} | \mathbf{t}) \propto \pi(\mathbf{v}) L(\mathbf{v} | \mathbf{t}) \tag{23}$$

where $\pi(\mathbf{v})$ is the joint prior distribution for \mathbf{v} ; $L(\mathbf{v} | \mathbf{t})$ is the likelihood function (17) and $\mathbf{t} = (\mathbf{t}_1, \dots, \mathbf{t}_n), \mathbf{t}_i = (t_{1i}, t_{2i}), i = 1, \dots, n$ is a vector of observed lifetime data.

To get the posterior summaries of interest, we simulate samples for the joint posterior distribution (23) using MCMC methods.

In this way, we could simulate samples for the joint posterior distribution (23) from the conditional distributions $\pi(\lambda_1 | \lambda_2, \alpha_1, \alpha_2, \theta, \mathbf{t}), \pi(\lambda_2 | \lambda_1, \alpha_1, \alpha_2, \theta, \mathbf{t}), \pi(\alpha_1 | \lambda_1, \lambda_2, \alpha_2, \theta, \mathbf{t}),$

$\pi(\alpha_2 | \lambda_1, \lambda_2, \alpha_1, \theta, \mathbf{t})$ and $\pi(\theta | \lambda_1, \lambda_2, \alpha_1, \alpha_2, \mathbf{t})$ using the Gibbs sampling algorithm or the Metropolis-Hastings algorithm, when the conditional distributions are not identified as known distributions that are easy to simulate.

Considering the presence of a vector $\mathbf{X} = (X_1, X_2, \dots, X_p)'$ of covariates associated to each bivariate lifetime T_1 and T_2 , let us consider the following regression model:

$$\begin{aligned} \lambda_{1i} &= \gamma_1 \exp(\boldsymbol{\beta}'_1 \mathbf{x}_i) \\ \lambda_{2i} &= \gamma_2 \exp(\boldsymbol{\beta}'_2 \mathbf{x}_i) \end{aligned} \tag{24}$$

where $\boldsymbol{\beta}_j = (\beta_{j1}, \beta_{j2}, \dots, \beta_{jp})'$ is the regression parameter vector, $j = 1, 2$, associated to the covariate vector $\mathbf{x}_i = (x_{1i}, x_{2i}, \dots, x_{pi})'$, $i = 1, 2, \dots, n$.

We also assume the presence of censored observations.

For a Bayesian analysis, we assume the following prior distributions for γ_j , α_j , β_{jk} and θ :

$$\begin{aligned} \alpha_j &\sim U[a_j, b_j] \\ \gamma_j &\sim U[c_j, d_j] \\ \theta &\sim U[-1, 1] \\ \beta_{jk} &\sim N(0, g^2) \end{aligned} \tag{25}$$

for $j = 1, 2$; $k = 1, \dots, p$ and a_j, b_j, c_j, d_j and g are known hyperparameters and $N(0, g^2)$ denotes a normal distribution with mean zero and variance g^2 . We further assume prior independence among the parameters.

6 APPLICATIONS

6.1 Simulated data sets

As a first application, let us consider four simulated data sets from the bivariate generalized exponential distribution (10) in the presence of censored data with sample sizes $n = 10$ ($d_1 = 10, d_2 = 9$); $n = 20$ ($d_1 = 18, d_2 = 20$); $n = 30$ ($d_1 = 27, d_2 = 30$) and $n = 50$ ($d_1 = 44, d_2 = 47$) where d_1 is the number of uncensored lifetimes t_{1i} and d_2 is the number of uncensored lifetimes t_{2i} , $i = 1, 2, \dots, n$, and the following values for the parameters of the model: $\lambda_1 = 0.001$; $\lambda_2 = 0.005$; $\alpha_1 = 1$; $\alpha_2 = 0.5$ and $\theta = 0.5$.

We assume a reparametrization for λ_1 and λ_2 given by $\gamma_1^* = \log(\lambda_1)$ and $\gamma_2^* = \log(\lambda_2)$ to get better convergence for the Gibbs sampling algorithm using the software Winbugs (Spiegelhalter et al., 2003) which only requires the specification of the joint distribution for the data and prior distributions for the parameters. For all considered sample sizes, we assume the following prior distributions:

$$\gamma_1^* \sim U(-10, 0), \quad \gamma_2^* \sim U(-10, 0), \quad \alpha_1 \sim U(0, 3), \quad \alpha_2 \sim U(0, 2) \quad \text{and} \quad \theta \sim U(0, 1).$$

The selection of the hyperparameters is made so that the prior expectation of the parameters is close to their true values while the variances assume very small values in order to have

informative prior distributions. Thus, a sensitivity analysis was performed to determine a final specification of the parameters. Here we present only the best result we obtained for these priors.

In Table 1, we have the posterior summaries of interest obtained from a final simulated Gibbs sample of size 2000 of the joint posterior distribution for the parameters of the model after discarding the first 5000 Gibbs samples to eliminate the effect of the initial values for the Gibbs sampling algorithm. In Table 1, we also have the maximum likelihood estimates (MLE) and the 95% confidence intervals based on the asymptotical normality of the MLE.

Table 1 – Posterior summaries (simulated data sets) and MLE estimates.

Sample size	Parameter	Mean	95% credible interval	MLE	95% confidence interval
n = 10	α_1	1.241	(0.489; 2.334)	1.103	(-4.943; 7.149)
	α_2	0.672	(0.296; 1.229)	0.575	(-2.206; 3.357)
	γ_1^*	-6.656	(-7.656; -5.991)	-6.908	(-11.770; -2.046)
	γ_2^*	-5.411	(-6.663; -4.530)	-5.521	(-10.957; -0.084)
	λ_1	0.001	(0.000; 0.002)	0.001	(-0.005; 0.008)
	λ_2	0.005	(0.001; 0.011)	0.004	(-0.024; 0.033)
	θ	0.552	(0.035; 0.979)	0.447	(-9.652; 10.546)
n = 20	α_1	1.228	(0.666; 2.056)	1.138	(-1.748; 4.025)
	α_2	0.716	(0.399; 1.132)	0.709	(-0.929; 2.347)
	γ_1^*	-6.642	(-7.285; -6.128)	-6.908	(-8.917; -4.389)
	γ_2^*	-5.039	(-5.728; -4.432)	-5.116	(-7.645; -2.547)
	λ_1	0.001	(0.001; 0.002)	0.001	(-0.002; 0.004)
	λ_2	0.007	(0.001; 0.003)	0.006	(-0.011; 0.023)
	θ	0.526	(0.036; 0.976)	0.736	(-5.688; 7.160)
n = 30	α_1	1.057	(0.611; 1.642)	0.978	(-0.873; 2.829)
	α_2	0.459	(0.303; 0.666)	0.531	(-0.354; 1.415)
	γ_1^*	-6.827	(-7.399; -6.349)	-6.908	(-8.722; -4.996)
	γ_2^*	-5.170	(-5.823; -4.626)	-5.116	(-7.241; -2.902)
	λ_1	0.001	(0.001; 0.002)	0.001	(-0.001; 0.003)
	λ_2	0.006	(0.003; 0.010)	0.006	(-0.008; 0.021)
	θ	0.458	(0.027; 0.948)	0.300	(-3.547; 4.147)
n = 50	α_1	1.181	(0.789; 1.673)	1.180	(-0.477; 2.836)
	α_2	0.493	(0.345; 0.669)	0.539	(-0.119; 1.197)
	γ_1^*	-6.837	(-7.260; -6.480)	-6.908	(-8.106; -5.500)
	γ_2^*	-5.092	(-5.594; -4.666)	-5.116	(-6.732; -3.467)
	λ_1	0.001	(0.001; 0.002)	0.001	(-0.0003; 0.003)
	λ_2	0.006	(0.004; 0.009)	0.006	(-0.004; 0.016)
	θ	0.538	(0.056; 0.967)	0.568	(-2.090; 3.226)

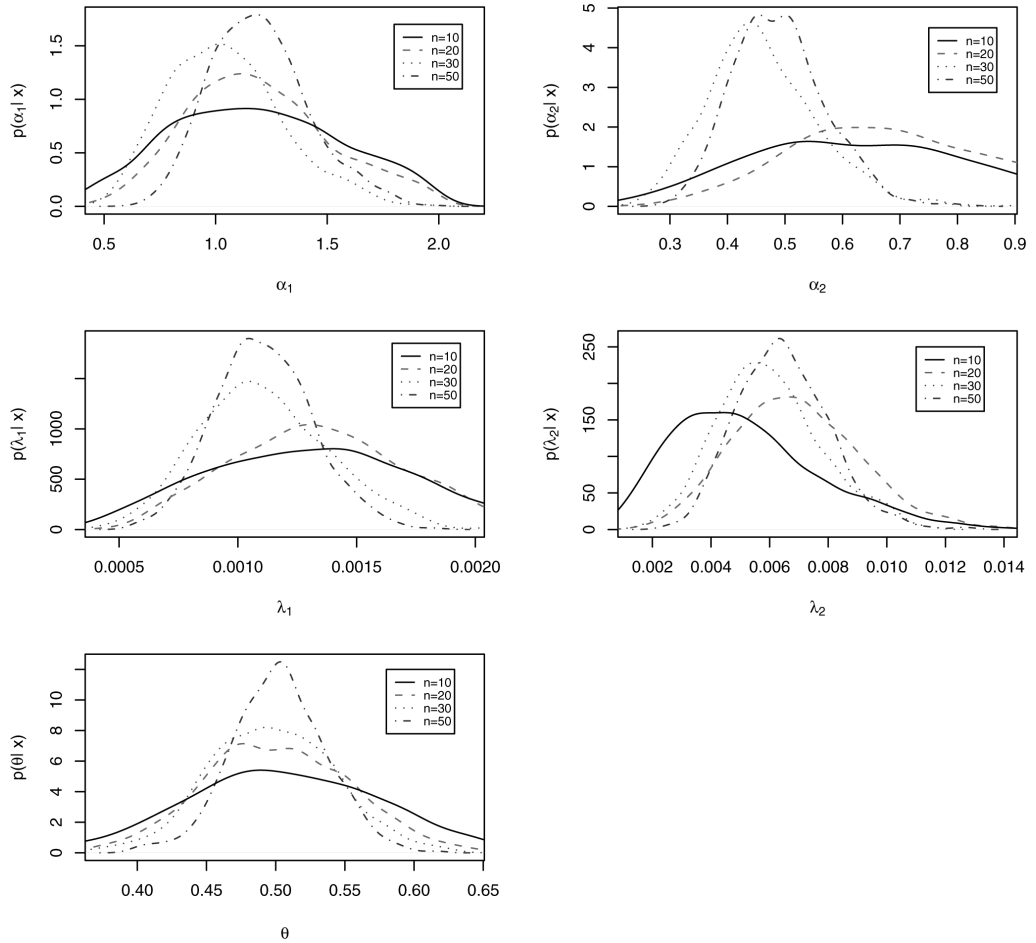


Figure 2 – Marginal posterior densities for each parameter with different sample sizes, $n = 10, 20, 50$ and 100 .

From the results of Table 1, we observe that we get accurate Bayesian inferences for the parameters of the model, especially considering large samples sizes. The only exception is the parameter θ , where the 95% credible intervals are very large considering the four simulated samples ($n = 10, n = 20, n = 30$ or $n = 50$).

Figure 2 illustrates the performance of marginal posterior densities for each parameter $\alpha_1, \alpha_2, \lambda_1, \lambda_2$ and θ when the sample size increase, that is, for $n = 10, 20, 50$ and 100 . From the plots of Figure 2, we observe that as the sample size increases, we have more accurate Bayesian inferences (see also Table 1).

To improve the Bayesian inferences for θ , we could assume a transformation, $\gamma_3^* = \log\left(\frac{\theta}{1-\theta}\right)$, considering θ positive an assumption usually observed for the data ($0 < \theta < 1$), the same prior distributions for $\gamma_1^*, \gamma_2^*, \alpha_1$ and α_2 assumed for the results of Table 1 and a normal prior $N(0, 1)$ distribution for γ_3^* , we have in Table 2, the posterior summaries of interest.

From the results of Table 2, we observe similar posterior summaries for the parameters α_1 , α_2 , γ_1^* , γ_2^* , λ_1 and λ_2 as obtained in Table 1, but better accuracy for the Bayesian estimator for θ as observed in the 95% credible intervals. We also observe that the accuracy of the Bayesian intervals for θ have some improvement as the data sample sizes increases, an indication of identifiability using the reparametrized form of θ .

Table 2 – Posterior summaries (simulated data set, logit transformation for θ).

Sample size	Parameter	Mean	S.D.	95% credible interval
$n = 10$	α_1	1.245	0.4819	(0.4912; 2.405)
	α_2	0.6802	0.2533	(0.2873; 1.287)
	γ_1^*	-6.65	0.4157	(-7054; -5.961)
	γ_2^*	-5.403	0.5508	(-6.638; -4.496)
	γ_3^*	0.1787	0.9878	(-1769; 2.131)
	λ_1	0.00139	0.000531	(0.00053; 0.00258)
	λ_2	0.00514	0.002536	(0.00131; 0.01115)
	θ	0.5372	0.2043	(0.1456; 0.8939)
$n = 20$	α_1	1.215	0.3578	(0.6259; 2.013)
	α_2	0.7132	0.2004	(0.3869; 1.145)
	γ_1^*	-6.644	0.298	(-7.32; -6.145)
	γ_2^*	-5.043	0.3358	(-5.782; -4.46)
	γ_3^*	0.05242	0.9548	(1-803; 1.82)
	λ_1	0.00136	0.000379	(0.000662; 0.002145)
	λ_2	0.00681	0.002169	(0.003081; 0.01156)
	θ	0.5114	0.2012	(0.1415; 0.8605)
$n = 30$	α_1	1.035	0.2526	(0.6053; 1.605)
	α_2	0.4629	0.0988	(0.2909; 0.6843)
	γ_1^*	-6.846	0.2661	(-7.422; -6.372)
	γ_2^*	-5.156	0.311	(4.616; 5.817)
	γ_3^*	-0.07513	0.9302	(-1.909; 1.779)
	λ_1	0.001101	0.000281	(0.00059; 0.0017)
	λ_2	0.00604	0.0018	(0.00297; 0.00989)
	θ	0.4843	0.1963	(0.1291; 0.8556)
$n = 50$	α_1	1.186	0.227	(0.7915; 1.683)
	α_2	0.4948	0.08044	(0.3451; 0.6658)
	γ_1^*	-6.835	0.1977	(-7.249; -6.488)
	γ_2^*	-5.094	0.2503	(-5.636; -4.647)
	γ_3^*	0.1513	0.8779	(-1.6; 1.894)
	λ_1	0.001097	0.000212	(0.00071; 0.001522)
	λ_2	0.006322	0.001533	(0.00357; 0.00959)
	θ	0.5325	0.1859	(0.168; 0.8692)

The Bayesian estimation also performs well in applications with a large number of censored data. Table 3 shows the results of simulation studies for different sample sizes as $n = 10$ ($d_1 = 10, d_2 = 5$); $n = 20$ ($d_1 = 12, d_2 = 20$); $n = 50$ ($d_1 = 30, d_2 = 20$) and $n = 100$ ($d_1 = 30, d_2 = 90$).

Table 3 – Posterior summaries of simulated data set with high level of censoring.

Sample size	Parameter	Mean	S.D.	95% credible interval
$n = 10$	α_1	1.610	0.566	(0.686, 2.821)
	α_2	1.223	0.403	(0.476, 1.943)
	γ_1^*	-6.790	0.338	(-7.513, -6.198)
	γ_2^*	-5.670	0.537	(-6.979, -4.834)
	λ_1	0.001	0.0003	(0.0005, 0.002)
	λ_2	0.004	0.002	(0.0009, 0.008)
	θ	0.464	0.281	(0.023, 0.9660)
$n = 20$	α_1	0.875	0.279	(0.452, 1.508)
	α_2	0.998	0.275	(0.552, 1.627)
	γ_1^*	-7.254	0.415	(-8.147, -6.543)
	γ_2^*	-4.397	0.295	(-5.010, -3.888)
	λ_1	0.001	0.0003	(0.0003, 0.0014)
	λ_2	0.013	0.003	(0.007, 0.020)
	θ	0.445	0.281	(0.019, 0.961)
$n = 50$	α_1	1.223	0.272	(0.771, 1.855)
	α_2	0.698	0.142	(0.454, 0.994)
	γ_1^*	-6.945	0.247	(-7.479, -6.493)
	γ_2^*	-5.402	0.311	(-6.091, -4.903)
	λ_1	0.001	0.0002	(0.0005, 0.0015)
	λ_2	0.005	0.0013	(0.002, 0.007)
	θ	0.487	0.112	(0.271, 0.710)
$n = 100$	α_1	1.115	0.203	(0.770, 1.541)
	α_2	0.632	0.079	(0.491, 0.786)
	γ_1^*	-7.599	0.267	(-8.183, -7.127)
	γ_2^*	-5.027	0.161	(-5.347, -4.746)
	λ_1	0.0005	0.0001	(0.0003, 0.0008)
	λ_2	0.007	0.001	(0.004, 0.008)
	θ	0.557	0.088	(0.384, 0.716)

In summary, we observe good inferences considering the posterior mean for all the random quantities, especially when the samples size increases in comparison to the real value of the parameters ($\lambda_1 = 0.001; \lambda_2 = 0.005; \alpha_1 = 1; \alpha_2 = 0.5$ and $\theta = 0.5$) used to simulate the lifetimes T_1 and T_2 .

Figure 3 shows a comparison of the posterior distributions of each parameter in order to analyze the sensitivity of the estimation when the number of censored lifetime data is increased. We consider samples of size $n = 50$ with $(d_1 = 44, d_2 = 47)$ and $(d_1 = 30, d_2 = 20)$. Despite the high degree of censoring, the performance of the estimates are quite similar for the parameters α_1, λ_1 and θ of the bivariate generalized exponential distribution. We note that the parameters α_2 and λ_2 are more sensitive to censorship certainly due to the higher percentage of censorship occurred for T_2 variable, hence requiring a larger number of observations.

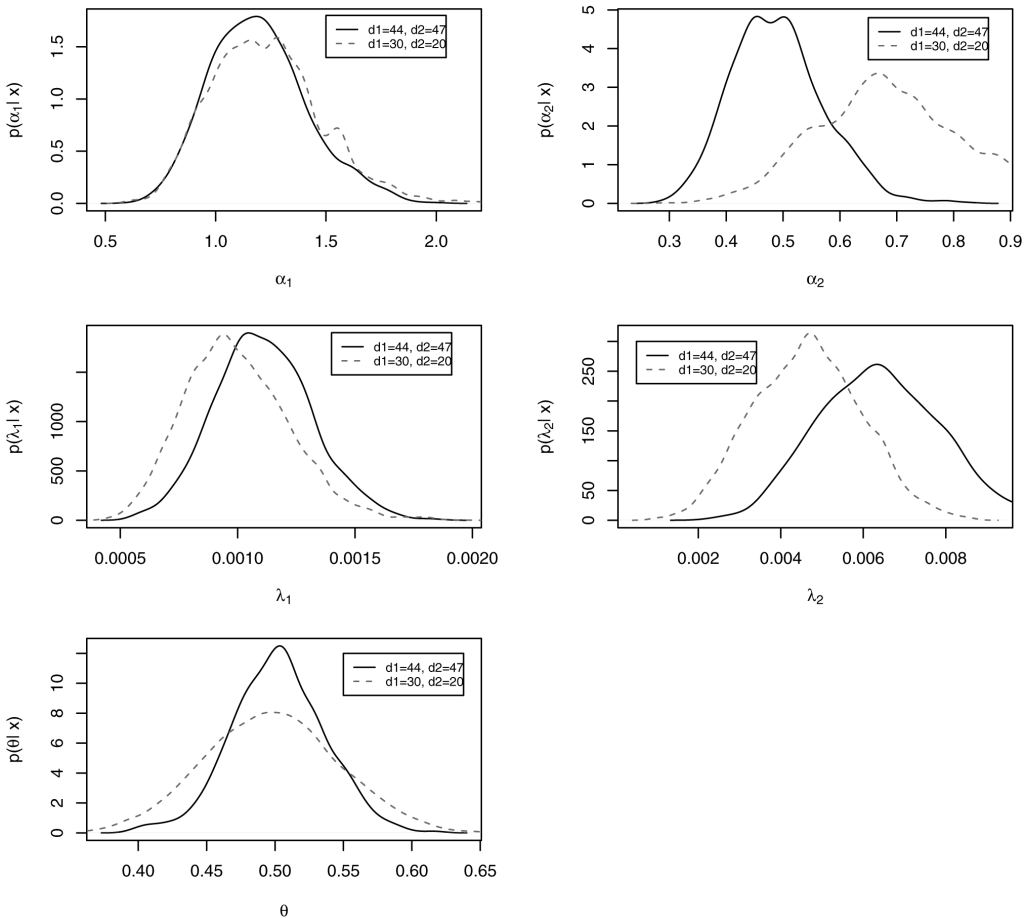


Figure 3 – Marginal posterior densities for each parameter with different sample sizes, $n = 10, 20, 50$ and 100 with high level of censoring.

6.2 Recurrence times of infection for kidney patients

In this application, we consider a survival time data set introduced by McGilchrist & Aisbett (1991) related to kidney infection where the recurrence of infection for 38 Kidney patients, using portable dialysis machines, are recorded. The time recorded, called infection time, is either the

lifetime (in days) of the patient until an infection occurred and the catheter had to be removed, or the censoring time, where the catheter was removed by other reasons. The catheter is reinserted after some time and the second infection time is again observe or censored (data set in Table 4).

As a first analysis, let us assume the bivariate generalized exponential distribution with density (12) not considering the presence of the covariate sex. Let us devote this model as “model 1”.

For a Bayesian analysis of “model 1”, not considering the presence of the covariate sex, let us assume the same reparametrization for λ_1, λ_2 and θ considered in Section 6.1, that is, $\gamma_1^* = \log(\lambda_1)$, $\gamma_2^* = \log(\lambda_2)$ and $\gamma_3^* = \log(\frac{\theta}{1-\theta})$ (from a preliminary data analysis, the sample correlation between the lifetimes considering only the uncensored observations is given by 0.181; that is, we are assuming $0 < \theta < 1$), and the following prior distributions: $\gamma_1^* \sim U(-10, 0)$, $\gamma_2^* \sim U(-10, 0)$, $\alpha_1 \sim U(0, 3)$, $\alpha_2 \sim U(0, 2)$ and $\gamma_3^* \sim U(-1, 1)$.

Using the WinBugs software, we simulated 2000 Gibbs samples from the joint posterior distribution of interest taking every 30th simulated sample after a “burn-in-sample” period of size 5000.

Convergence of the Gibbs sampling algorithm was monitored using standard existing methods as traceplots for the simulated samples. The posterior densities for each parameter are shown in Figure 4.

In Table 5, we have the posterior means, the posterior standard-deviations and 95% Bayesian intervals for the parameters of the model. We also have the MLE estimates and their asymptotical confidence intervals.

Often concern focusses on the survival function $S(t_1, t_2)$ given in (14). For instance, by using the priors proposed in this paper we have $P(T_1 > 8 \text{ days}, T_2 > 12 \text{ days}) = 0.833$ with a credible interval (0.737, 0.914).

Figure 5 shows graphically the posterior distribution of the probability $P(T_1 > 8 \text{ days}, T_2 > 12 \text{ days})$.

Finally, we derive the joint density and survival functions from the (12) and (14) respectively, for kidney infection in patients data and a plot of both functions is provided in Figure 6.

In the presence of the covariate sex, denoted by X , we assume the regression model introduced in Section 5, that is,

$$\begin{aligned} \lambda_{1i} &= \gamma_1 \exp(\beta_1 x_i) \\ \lambda_{2i} &= \gamma_2 \exp(\beta_2 x_i) \end{aligned} \tag{26}$$

where $i = 1, 2, \dots, 38$; $X_i = 1$ (male) and $X_i = 0$ (female) (see (24)). Let us denote this model as “model 2”.

Also assuming the reparametrization $\gamma_3^* = \log(\frac{\theta}{1-\theta})$, and the prior distributions $\gamma_j \sim U(0, 1)$, $\beta_j \sim N(0, 1)$, $\alpha_j \sim U(0, 3)$, $j = 1, 2$ and $\gamma_3^* \sim U(-1, 1)$, we have in Table 5, the posterior summaries of interest based on 2000 simulated Gibbs samples (every 30th sample and a “burn-in-sample” of size 5000).

Table 4 – Recurrence times of infections in 38 kidney patients.

Patient	First time	Second time	Censoring first time	Censoring second time	Sex
1	8	16	1	1	1
2	23	13	1	0	2
3	22	28	1	1	1
4	447	318	1	1	2
5	30	12	1	1	1
6	24	245	1	1	2
7	7	9	1	1	1
8	511	30	1	1	2
9	53	196	1	1	2
10	15	154	1	1	1
11	7	333	1	1	2
12	141	8	1	0	2
13	96	38	1	1	2
14	149	70	0	0	2
15	536	25	1	0	2
16	17	4	1	0	1
17	185	117	1	1	2
18	292	114	1	1	2
19	22	159	0	0	2
20	15	108	1	0	2
21	152	362	1	1	1
22	402	24	1	0	2
23	13	66	1	1	2
24	39	46	1	0	2
25	12	40	1	1	1
26	113	201	0	1	2
27	132	156	1	1	2
28	34	30	1	1	2
29	2	25	1	1	1
30	130	26	1	1	2
31	27	58	1	1	2
32	5	43	0	1	2
33	152	30	1	1	2
34	190	5	1	0	2
35	119	8	1	1	2
36	54	16	0	0	2
37	6	78	0	1	2
38	63	8	1	0	1

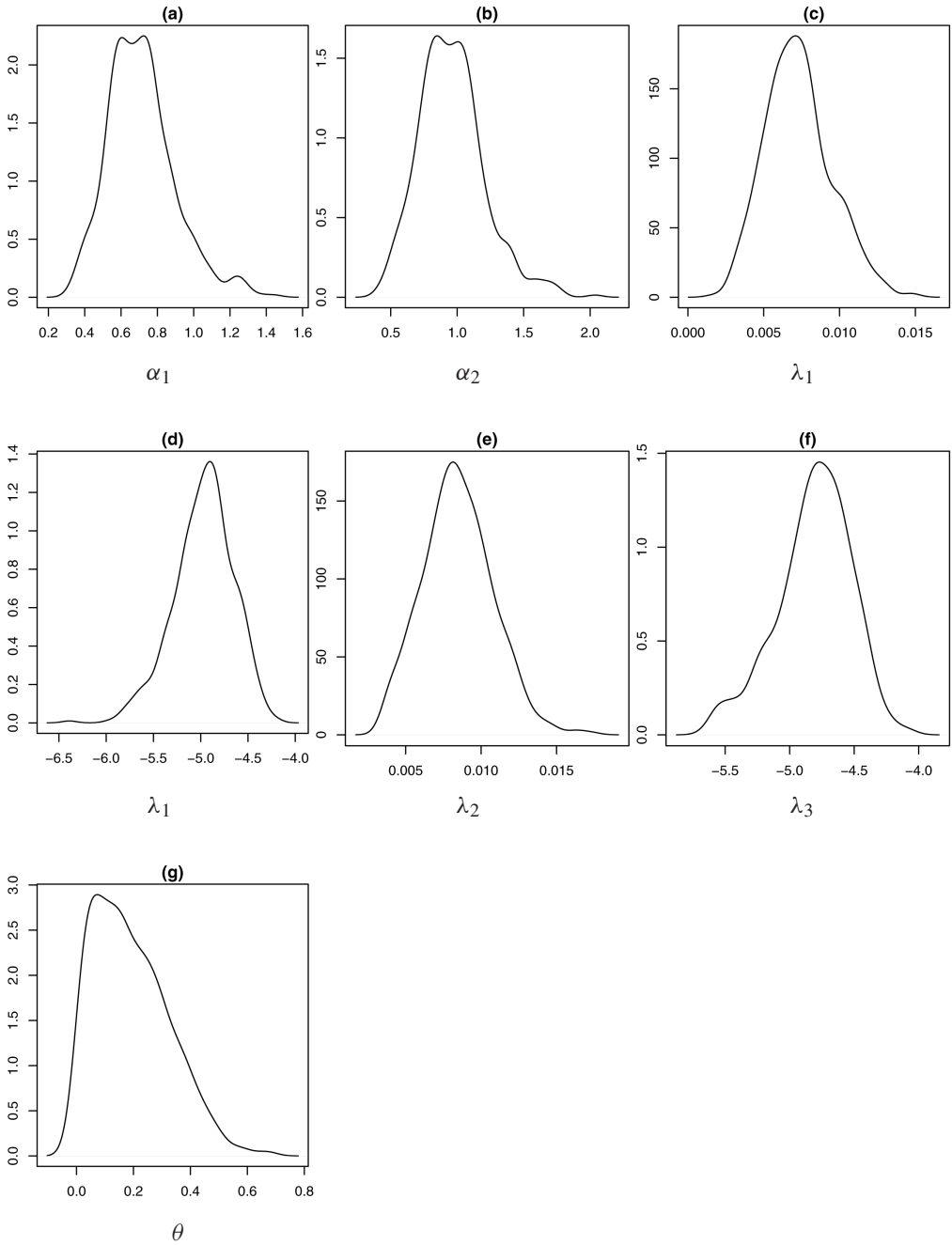


Figure 4 – Marginal posterior densities for each parameter of “model 1”.

From the results of Table 6, we observe that zero is included in the 95% credible intervals for β_1 and β_2 , but zero is very close to the inferior credible limit for β_1 , that is, we have an indication that the lifetime T_1 is affected by the covariate sex.

Table 5 – Bayesian summaries (“model 1” not considering the covariate sex).

Parameter	Mean	95% credible interval	MLE	95% confidence interval
α_1	0.766	(0.490; 1.125)	0.724	(-0.286; 1.733)
α_2	1.130	(0.695; 1.712)	0.974	(-0.503; 2.451)
γ_1^*	-5.139	(-5.724; -4.685)	-5.116	(-6.757; -3.570)
γ_2^*	-4.851	(-5.455; -4.366)	-4.962	(-6.528; -3.336)
γ_3^*	0.067	(-0.939; 0.959)	0.364	(-11.574; 12.300)
λ_1	0.006	(0.003; 0.009)	0.006	(-0.004; 0.015)
λ_2	0.008	(0.004; 0.013)	0.007	(-0.005; 0.019)
θ	0.516	(0.281; 0.723)	0.590	(-2.408; 3.588)

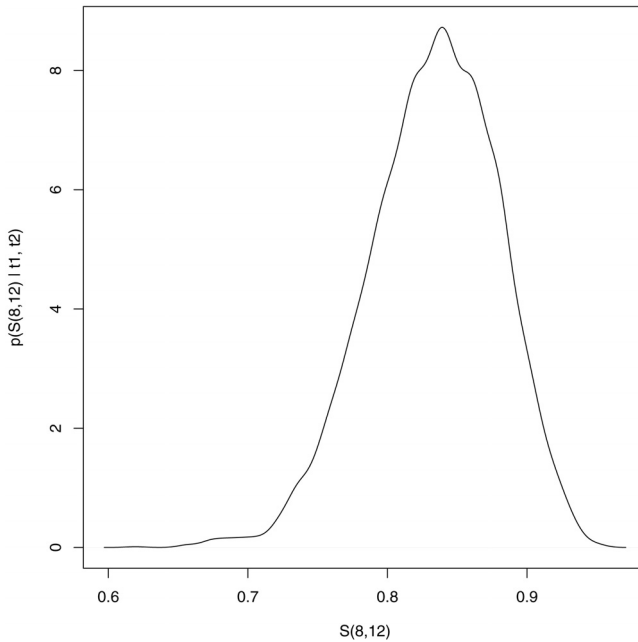


Figure 5 – Posterior density of survival $S(8, 12)$.

To compare the proposed models, we could use some existing Bayesian discrimination criteria, as for example, DIC (Deviance information criterion) introduced by Spiegelhalter et al. (2002) (see appendix) and given automatically by the WinBugs software. Assuming “model 1” (not considering the presence of the covariate sex), we obtained a MonteCarlo estimate for DIC given by the value 686.33; assuming “model 2” (presence of the covariate sex), the DIC value is given by 677.695; that is, “model 2” gives better fit for the data set introduced in Table 3 (smaller value for DIC).

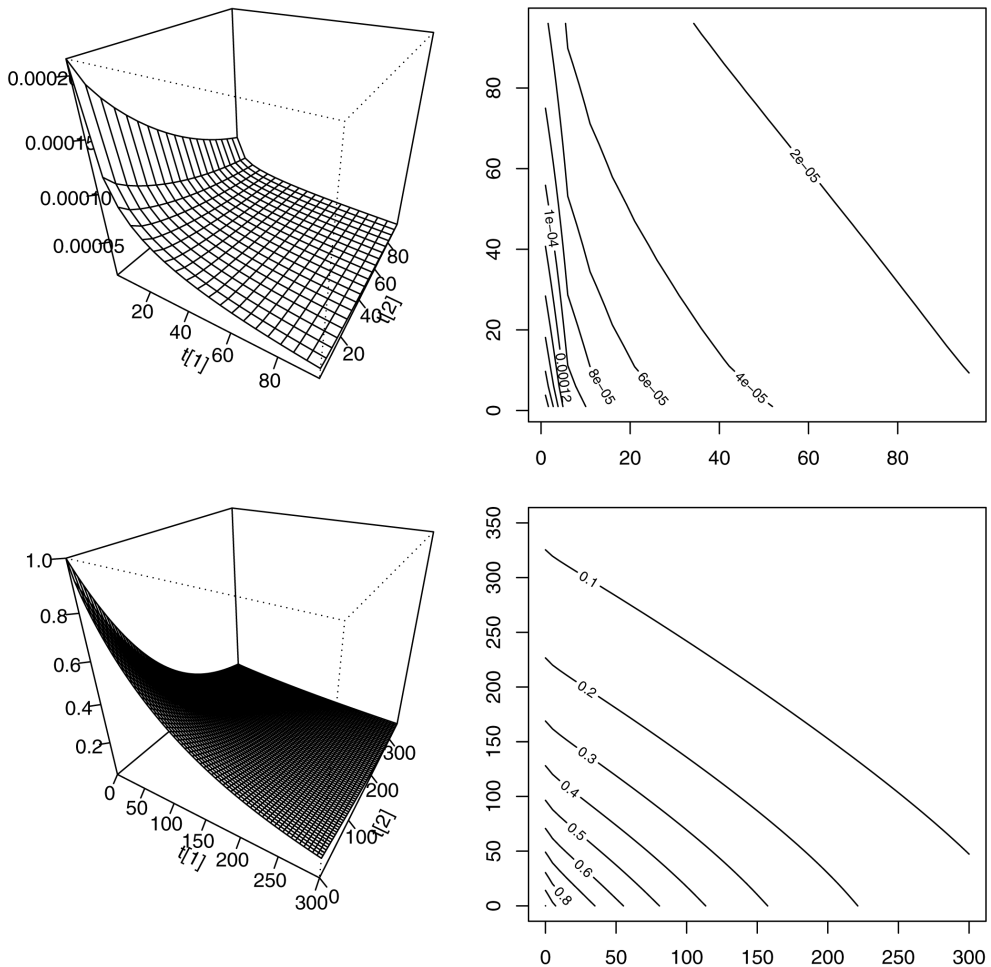


Figure 6 – Plots and contours of bivariate functions for the “model 1”.

Table 6 – Bayesian summaries (“model 2” in the presence of the covariate sex).

Parameter	Posterior mean	S.D.	95% credible interval
α_1	0.842	0.179	(0.588; 1.179)
α_2	1.143	0.257	(0.771; 1.612)
λ_1	0.006	0.001	(0.004; 0.009)
λ_2	0.009	0.002	(0.005; 0.014)
β_1	0.230	0.159	(-0.024; 0.514)
β_2	-0.118	0.147	(-0.345; 0.113)
θ	0.500	0.040	(0.437; 0.569)

7 CONCLUDING REMARKS

The use of bivariate generalized exponential distributions derived from copula functions could be a good alternative to analyze bivariate lifetime data, usually in the presence of censored observations and covariates. Other copula functions also could be used to derive bivariate lifetime distributions. Bayesian inference for this class of models using standard existing MCMC methods is a good alternative to get accurate inference results. It is important to point out that the dependence parameter θ can present some identifiability problems and this problem could be solved considering an informative prior from θ based on expert opinion or considering a reparametrization, as it was observed in this paper.

The use of existing Bayesian softwares like the WinBugs software gives a great simplification to get the posterior summaries of interest.

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APPENDIX

DEVIANCE INFORMATION CRITERION (DIC)

The Deviance Information Criterion (DIC) is a criterion specifically useful for selection model under the Bayesian approach where samples of the posterior distributions for the parameters of the model are obtained using MCMC methods.

The deviance is defined by,

$$D(\theta) = -2 \log L(\theta) + c \quad (\text{A1})$$

where θ is a vector of unknown parameters of the model, is the likelihood function of the model and c is a constant that does not need to be known when the comparison between models is made.

The DIC criterion defined by Spiegelhalter (2002) is given by,

$$DIC = D(\hat{\theta}) + 2n_D \quad (A2)$$

where $D(\hat{\theta})$ is the deviance evaluated at the posterior mean $\hat{\theta} = E(\theta | data)$ and n_D is the effective number of parameters of the model given by $n_D = \bar{D} - D(\hat{\theta})$, where $\bar{D} = E(D(\theta) | data)$ is the posterior deviance measuring the quality of the data fit for the model. Smaller values of DIC indicates better models. Note that these values could be negative.